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DUALITY THEOREMS FOR REGULAR HOMOTOPY

OF FINITE DIRECTED GRAPHS. (*)

RIASSUNTO. - *Dati uno spazio topologico normale e numerabilmente paracompatto S ed un grafo finito ed orientato G si prova che tra gli insiemi $Q(S,G)$ e $Q^*(S,G)$ delle classi di o -omotopia e di o^* -omotopia esiste una biiezione naturale. Nelle stesse condizioni, se S' è un sottospazio chiuso di S e G' un sottografo di G , esiste ancora una biiezione naturale tra gli insiemi $Q(S,S';G,G')$ e $Q^*(S,S';G,G')$ delle classi di omotopia. Si mostra infine che in condizioni meno restrittive per lo spazio S le precedenti biiezioni possono non sussistere.*

INTRODUCTION

In the extension from the undirected graphs to the directed ones, we have two possible definitions of regular function. In fact, given a topological space S and a finite directed graph G , a function $f: S \rightarrow G$ is called *o -regular* (resp. *o^* -regular*) if for all $v, w \in G$ such that $v \neq w$ and $v \neq w$, it is $\overline{f^{-1}(v)} \cap f^{-1}(w) = \emptyset$ (resp. $f^{-1}(v) \cap \overline{f^{-1}(w)} = \emptyset$). Therefore we can deal with two different homotopies, the o -homotopy and the o^* -homotopy. Hence we examine the problem

(*) Work performed under the auspices of the *Consiglio Nazionale delle Ricerche (CNR, GNSAGA)*, Italy.

of seeing if, under suitable conditions for the space S , the o -homotopy and the o^* -homotopy get to coincide necessarily, i.e. if there exists a natural bijection between the sets of homotopy classes $Q(S,G)$ and $Q^*(S,G)$. As we observed in [2], by the Duality Principle the o -homotopy and o^* -homotopy are interchanged by replacing the graph G by the dually directed graph G^* ; thus we can identify the four sets $Q(S,G)$, $Q^*(S,G)$, $Q(S,G^*)$, $Q^*(S,G^*)$ at the same time.

Briefly we show how to solve the foregoing statements. In Part one , at first, we just consider functions and homotopies that are *completely regular*, i.e. without singularities; hence we examine the sets of complete o -homotopy classes $Q_c(S,G)$ and the ones of complete o^* -homotopy classes $Q_c^*(S,G)$. Then we obtain some properties which characterize the regular and completely regular functions (§ 1) and we give the definition of *pattern*, by which we construct a relation from the set of completely o -regular functions to the one of completely o^* -regular functions. Consequently, we have (§ 3) the Duality Theorem for complete homotopy classes (Theorem 9): "*There exists a natural bijection between the sets of complete homotopy classes $Q_c(S,G)$ and $Q_c^*(S,G)$* ".

Now we recall the results obtained in [3], Theorems 12, 12*, 16, 16*:

- i) If the space S is normal (*), in every class of $Q(S,G)$ (resp. $Q^*(S,G)$) there exists a completely o -regular (resp. o^* -regular) function.
- ii) If $S \times I$ is normal, two completely o -regular (resp. completely o^* -regular) functions, which are homotopic, are also completely homotopic.

Hence it follows (§ 4) that if S and $S \times I$ are normal spaces, there exists a natural bijection from $Q_c(S,G)$ to $Q(S,G)$ and from $Q_c^*(S,G)$ to $Q^*(S,G)$. From here and Theorem 9 the Duality Theorem follows. Now if we recall that a normal space S such that the product $S \times I$ is normal, is said a *countably paracompact normal*

(*) We distinguish between normal space and T_4 -space, according to whether it is a T_2 -space or not.

space (see [12], pp.168-169) we can enunciate the Duality Theorem (Theorem 11): "If S is a countably paracompact normal space, then there exists a natural bijection from $Q(S,G)$ to $Q^*(S,G)$ ".

In Part two we consider the same problem for couples of topological spaces (S,S') and of directed graphs (G,G') . That is not a trivial generalization of Part one, because new difficulties rise. In general, indeed, we cannot construct patterns of completely o -regular functions, then we must add the further condition that the completely regular functions are *balanced* in S' as regards S (§ 5), i.e. such that for all $x' \in S'$, for all $v \in G$, $x' \in \overline{f^{-1}(v)}$ implies that $x' \in \overline{f^{-1}(v)} \cap S'$. Thus we can repeat the construction of patterns (§ 6).

A second difficulty rises in that the so constructed patterns are not in general balanced functions. Hence we must choose as subspace S' an *open subspace* (§ 7) and under this condition the duality for complete homotopy is solved.

Unfortunately we cannot deduce the Duality Theorem since the Normalization Theorems proved in [3] for S and $S \times I$ normal spaces hold only if S' is a closed set. We eliminate this last difficulty (§ 8,9) by considering the *decreasingly filtered set* of open subspaces including S' and the *inductive limit* of the functions balanced in any open neighbourhood of S' . Thus by proceeding as in Part one we obtain the Duality Theorem (Theorem 32): "If S is a countably paracompact normal space and S' a closed subspace of S , then there exists a natural bijection from the set of o -homotopy classes $Q(S,S';G,G')$ to the one of o^* -homotopy classes $Q^*(S,S';G,G')$ ".

In § 11 we generalize the Duality Theorem to the case of $(n+1)$ -tuples of topological spaces and of $(n+1)$ -tuples of graphs. In § 12 we obtain the Duality Theorem for *absolute and relative homotopy groups* and we prove that the natural bijections are isomorphisms. At last in § 13 we give some counterexamples and among these we remark 13.4 and 13.5 which show that under weaker conditions for the space S (quasi compact, T_0 but not T_1) the two Duality Theorems do not hold.

0) Background.

Graphs and their subsets. (See [2] § 1, [3] § 1).

Let G be a *finite directed graph*.

If v, w are two vertices of G , we use the symbol $v \rightarrow w$ (resp. $v \nrightarrow w$) to denote that vw is (resp. is not) a directed edge of G . If $v \rightarrow w$, we call v a *predecessor* of w and w a *successor* of v .

The graph G^* with the same vertices of G and such that $(u \rightarrow v \text{ in } G) \Leftrightarrow (v \rightarrow u \text{ in } G^*)$, is called the *dually directed graph* as regards G . (If $G \equiv G^*$, i.e. if for all $v, w \in G$ we have $(v \rightarrow w) \Leftrightarrow (w \rightarrow v)$, the graph is called *undirected*).

Let X be a non-empty subset of G . A vertex of X is called a *head* (resp. a *tail*) of X in G , if it is a predecessor (resp. a successor) of all the other vertices of X . We denote by $H_G(X)$ (resp. $T_G(X)$) or, simply, by $H(X)$ (resp. $T(X)$) the set of the heads (resp. tails) of X in G . If $H(X) \neq \emptyset$ (resp. $T(X) \neq \emptyset$), X is called *headed* (resp. *tailed*); otherwise, X is called *non-headed* (resp. *non-tailed*). Finally, X is called *totally headed* (resp. *totally tailed*), if all the non-empty subsets of X are headed (resp. tailed). If X is a singleton, we agree to say that X is headed.

Regular and completely regular functions. (See [2] § 1, [3] § 2).

Let S be a *topological space*.

Given a function $f: S \rightarrow G$ from S to G , we denote by capital letter V the set of all the f -counterimages of $v \in G$, and if we want to emphasize the function f , we write $V^f = f^{-1}(v)$.

A function $f: S \rightarrow G$ is called *o-regular* (resp. *o*-regular*), if for all $v, w \in G$ such that $v \neq w$ and $v \nrightarrow w$, it is $V \cap \bar{W} = \emptyset$ (resp. $\bar{V} \cap W = \emptyset$).

Let $I = [0, 1]$ be the unit interval in R^1 . Two o-regular (resp. o*-regular) functions $f, g: S \rightarrow G$ are called *o-homotopic* (resp. *o*-homotopic*), if there exists an o-regular (resp. o*-regular) function $F: S \times I \rightarrow G$, such that $F(x, 0) = f(x)$ and $F(x, 1) = g(x)$, for all $x \in S$. The o-regular (resp. o*-regular) function F is

called an *o-homotopy* (resp. *o*-homotopy*) between f and g . The *o-homotopy* (resp. *o*-homotopy*) is an equivalence relation and we denote by $Q(S,G)$ (resp. $Q^*(S,G)$) the set of *o-homotopy* (resp. *o*-homotopy*) classes. We note that $Q^*(S,G)$ coincides with $Q(S,G^*)$ and $Q^*(S,G^*)$ with $Q(S,G)$.

DUALITY PRINCIPLE. - Every true proposition in which appear the concepts of headed set, tailed set, *o-regularity*, *o*-regularity*, *o-homotopy*, *o*-homotopy*, $Q(S,G)$, $Q^*(S,G)$, remains true if the concepts of headed set and tailed set, *o-regularity* and *o*-regularity*, *o-homotopy* and *o*-homotopy*, $Q(S,G)$ and $Q^*(S,G)$, are interchanged through the statement of the proposition.

Given an *o-regular* (resp. *o*-regular*) function $f: S \rightarrow G$, a n -tuple $X = \{v_1, \dots, v_n\}$, ($n \geq 2$) is called a *singularity* of f if:

i) X is non-headed (resp. non-tailed);

ii) $\overline{V_1^f} \cap \dots \cap \overline{V_n^f} \neq \emptyset$.

An *o-regular* (resp. *o*-regular*) function $f: S \rightarrow G$ from S to G is called *completely o-regular* (resp. *completely o*-regular*), or simply *c.o-regular* (resp. *c.o*-regular*), if there are no singularities of f . (If the graph G is undirected, then all the singularities are couples and the *c.regular* functions are called *strongly regular* functions).

Functions between pairs. (See [2] §5,[3] §2).

Let S' be a *subspace* of S and G' a *subgraph* of G .

A function $f: S, S' \rightarrow G, G'$ is called *o-regular* (resp. *o*-regular*) if both $f: S \rightarrow G$ and its restriction $f' = f|_{S'}: S' \rightarrow G'$ are *o-regular* (resp. *o*-regular*) functions.

Two *o-regular* (resp. *o*-regular*) functions $f, g: S, S' \rightarrow G, G'$ are called *o-homotopic* (resp. *o*-homotopic*), if there exists an *o-regular* (resp. *o*-regular*) homotopy $F: S \times I, S' \times I \rightarrow G, G'$, between f and g . The *o-homotopy* (resp. *o*-homotopy*) is an equivalence relation and we denote by $Q(S, S'; G, G')$ (resp. $Q^*(S, S'; G, G')$) the

set of o -homotopy (resp. o^* -homotopy) classes. We note that $Q^*(S, S'; G, G')$ coincides with $Q(S, S', G^*, G'^*)$ and $Q(S, S'; G, G')$ with $Q^*(S, S'; G^*, G'^*)$.

A function $f: S, S' \rightarrow G, G'$ is called *c.o-regular* (resp. *c.o*-regular*) if both $f: S \rightarrow G$ and $f': S' \rightarrow G'$ are *c.o-regular* (resp. *c.o*-regular*) functions.

As before, the *Duality Principle* holds for functions between pairs.

Main results of [2], [3].

R_a : $X \subseteq G$ is totally headed, iff it is totally tailed. (See [3], Proposition 4).

If S is a normal topological space and S' is a closed subspace of S , we have:

R_b : (The first Normalization Theorem). Let $f: S \rightarrow G$ (resp. $f: S, S' \rightarrow G, G'$) be an o -regular function. Then there exists a *c.o-regular* function, o -homotopic to f . (See [3], Theorems 12, 15).

R_c : (Extension Theorem between pairs). Let $f: S, S' \rightarrow G, G'$ be an o -regular function. Then there exist a closed neighbourhood U of S' and an o -regular function $g: S, S' \rightarrow G, G'$, which is o -homotopic to f and such that the function $g: S, U \rightarrow G, G'$ is o -regular, i.e. $g(U) \subseteq G'$ and the restriction $\hat{g}: U \rightarrow G'$ of g to U is o -regular. (See [2], Theorem 20).

R_d : In the construction of R_c , if there exist n vertices $p_1, \dots, p_n \in G$ and m vertices $q_1, \dots, q_m \in G'$, such that $\overline{P_1^f} \cap \dots \cap \overline{P_n^f} \cap \overline{Q_1^{f'}}$ $\dots \cap \overline{Q_m^{f'}} = \emptyset$, then also it follows $\overline{P_1^g} \cap \dots \cap \overline{P_n^g} \cap \overline{Q_1^{\hat{g}}} \dots \cap \overline{Q_m^{\hat{g}}} = \emptyset$. Similarly, from $\overline{P_1^f} \cap \dots \cap \overline{P_n^f} \cap X = \emptyset$ it results $\overline{P_1^g} \cap \dots \cap \overline{P_n^g} \cap U = \emptyset$. (See [2], Corollary 21).

Moreover, if $S \times I$ is normal, then it results:

R_e : (The first Normalization Theorem for homotopies). Let $f, g: S \rightarrow G$ (resp. $f, g: S, S' \rightarrow G, G'$) be two o -homotopic *c.o-regular* functions. Then, between the functions f and g , there also exists an o -homotopy, which is a *c.o-regular* function. (See [3], Theorem 16).

By Duality Principle, the results dual to the previous ones are also true.

PART ONE. DUALITY THEOREM FOR REGULAR FUNCTIONS.

For brevity, we omit the statements of dual propositions, but if we must refer to them, we denote them by *.

1) Properties of regular and completely regular functions.

DEFINITION 1.- Let S be a topological space, x a point of S , G a finite directed graph and $f: S \rightarrow G$ a function from S to G . We call image-envelope of x by f , and we denote by $\langle f(x) \rangle$, the set of vertices, such that the closures of their f -counter images include the point, i.e. $v \in \langle f(x) \rangle \Leftrightarrow x \in \overline{V^f}$.

PROPOSITION 1. - Let S be a topological space, x a point of S , G a finite directed graph and $f: S \rightarrow G$ a function from S to G . Then the image-envelope of x coincides with the intersection of the images of the neighbourhoods of x , i.e. $\langle f(x) \rangle = \bigcap \{f(U_x) \mid U_x \text{ is a neighbourhood of } x\}$.

Proof.- $v \in \langle f(x) \rangle \Leftrightarrow x \in \overline{V^f} \Leftrightarrow (\forall U_x, U_x \cap V^f \neq \emptyset) \Leftrightarrow (\forall U_x, v \in f(U_x)) \Leftrightarrow v \in \bigcap f(U_x)$. ■

PROPOSITION 2. - Let S be a topological space, G a finite directed graph and $f: S \rightarrow G$ a function from S to G . Then f is an o -regular function, iff, for all $x \in S$, $f(x)$ is a head of $\langle f(x) \rangle$, i.e. $f(x) \in H(\langle f(x) \rangle)$.

Proof. - i) Let f be an o -regular function, x a point of S , and $v = f(x)$. Then, for all $w \in \langle f(x) \rangle$, i.e. $x \in \overline{W^f}$, we have $V^f \cap \overline{W^f} \neq \emptyset$. Hence $v \rightarrow w$, i.e. $v \in H(\langle f(x) \rangle)$.

ii) For all $x \in S$, let $f(x) \in H(\langle f(x) \rangle)$ be. We have to prove that, for all $v, w \in G$, such that $v \neq w$ and $v \rightarrow w$, it results that $V^f \cap \overline{W^f} = \emptyset$. If we assume $x \in V^f \cap \overline{W^f}$, it follows $f(x) = v$, $v \in H(\langle f(x) \rangle)$ and $w \in \langle f(x) \rangle$, hence $v \rightarrow w$. Contradiction. ■

PROPOSITION 3. - Let S be a topological space, G a finite directed graph and $f: S \rightarrow G$ a function from S to G . Then f is a c.o-regular function, iff, for all $x \in S$, it is:

- i) $f(x)$ is a head of $\langle f(x) \rangle$, i.e. $f(x) \in H(\langle f(x) \rangle)$;
- ii) $\langle f(x) \rangle$ is a totally headed subset of G .

Proof. - By Proposition 2, we have only to prove that an o-regular function is c.o-regular iff ii) is true.

Then let f be a c.o-regular function. Since each subset $X = \{v_1, \dots, v_n\}$ of $\langle f(x) \rangle$ such that $\overline{V_1^f} \cap \dots \cap \overline{V_n^f} \neq \emptyset$ can not be a singularity of f , X must be headed.

Conversely, let $\langle f(x) \rangle$ be totally headed for all $x \in S$. Then if we assume that $X = \{v_1, \dots, v_n\}$ is a singularity of f , there exists a point $x \in \overline{V_1^f} \cap \dots \cap \overline{V_n^f}$. Hence the non-headed subset X is included in $\langle f(x) \rangle$. Contradiction. ■

REMARK. - Consequently, if G is an undirected graph, a function $f: S \rightarrow G$ is strongly regular i.e. c.regular iff, for all $x \in S$, $\langle f(x) \rangle$ is a totally headed subset of G . In this case, indeed, we have that " $\langle f(x) \rangle$ totally headed" is equivalent to $H(\langle f(x) \rangle) = \langle f(x) \rangle$.

2) Patterns of a function.

DEFINITION 2. - Let $f: S \rightarrow G$ be a function from a topological space S to a finite directed graph G . A function $g: S \rightarrow G$ is called an o-pattern (resp. o*-pattern) of f , if, for all $x \in S$, it holds $g(x) \in H(\langle f(x) \rangle)$ (resp. $g(x) \in T(\langle f(x) \rangle)$).

REMARK. - In general there is no pattern of a given function, because the sets $\langle f(x) \rangle$ may be non-headed for some $x \in S$.

DEFINITION 3. - A function $f: S \rightarrow G$ from a topological space S to a finite directed graph G is called quasi o-regular (resp. quasi o*-regular), or simply q.o-regular (resp. q.o*-regular) if the image-envelope $\langle f(x) \rangle$ is headed (resp. tailed) for all $x \in S$.

Moreover, the function f is called completely quasi regular, or simply c.q. regular, if $\langle f(x) \rangle$ is totally headed.

REMARK 1. - Consequently, if G is an undirected graph, a q. regular function is also regular and a c.q. regular function is also completely regular, i.e. strongly regular.

REMARK 2. - We consider only c.q. regular functions, since by R_α each c.q.o-regular function is also c.q.o*-regular.

PROPOSITION 4. - An o-regular function is q.o-regular. A c.o-regular function is c.q. regular.

Proof. - It follows from Propositions 2, 3. ■

PROPOSITION 5. - A function $f: S \rightarrow G$ is q.o-regular iff there exists an o-pattern of f .

Proof. - i) Let g be an o-pattern of f . Since, for all $x \in S$, $g(x) \in H(\langle f(x) \rangle)$, $\langle f(x) \rangle$ is headed.

ii) Let $\langle f(x) \rangle$ be headed. In order to construct an o-pattern g of f , we number the vertices of the finite graph G by v_1, \dots, v_n . Then, for all $x \in S$, we choose as $g(x)$ the vertex with the lowest index among the vertices of $H(\langle f(x) \rangle)$. ■

REMARK. - We note that a c.q. regular function is q.o-regular and q.o*-regular. Hence, there exist both o-patterns and o*-patterns for a c.q-regular function.

PROPOSITION 6. - Let $f: S \rightarrow G$ be a $q.o$ -regular function. Then:

- i) all its o -patterns are o -regular functions;
- ii) two o -patterns of f are o -homotopic to each other.

Proof. - i) Let $g: S \rightarrow G$ be an o -pattern of f . At first, we prove that $\overline{V^g} \subseteq \overline{V^f}$, for each $v \in G$. We have, indeed, $x \in V^g \Rightarrow g(x) = v \Rightarrow v \in \langle f(x) \rangle \Rightarrow x \in \overline{V^f}$. Hence it results $V^g \subseteq \overline{V^f}$ and also $\overline{V^g} \subseteq \overline{V^f}$. Consequently, $\langle g(x) \rangle \subseteq \langle f(x) \rangle$, for all $x \in S$. Now, since $g(x)$ is a head of $\langle f(x) \rangle$, it is also a head of $\langle g(x) \rangle$. Then, by Proposition 2, g is an o -regular function.

ii) Let g, h be two o -patterns of f . The function $F: S \times I \rightarrow G$, given by:

$$F(x, t) = \begin{cases} g(x) & \text{for } t = 0 \\ h(x) & \forall t \in [0, 1], \end{cases}$$

is a homotopy between g and h . Besides, for all $(x, t) \in S \times I$, it is:

$$\langle F(x, t) \rangle = \begin{cases} \langle g(x) \rangle \cup \langle h(x) \rangle \subseteq \langle f(x) \rangle & \text{for } t = 0, \\ \langle h(x) \rangle & \forall t \in [0, 1]. \end{cases}$$

Then, since $g(x)$ and $h(x)$ are heads of $\langle f(x) \rangle$, they are also, respectively, a head of $\langle g(x) \rangle \cup \langle h(x) \rangle$ and a head of $\langle h(x) \rangle$. Consequently, F is an o -regular function.

DEFINITION 4. - Let S be a topological space and G a finite directed graph. Two $c.o$ -regular (resp. $c.o^*$ -regular) functions $f, g: S \rightarrow G$ are called completely o -homotopic (resp. completely o^* -homotopic) or simply $c.o$ -homotopic (resp. $c.o^*$ -homotopic) if there exists a homotopy F between f and g , which is a $c.o$ -regular (resp. $c.o^*$ -regular) function. F is called a complete o -homotopy (resp. complete o^* -homotopy), or simply a $c.o$ -homotopy (resp. $c.o^*$ -homotopy).

PROPOSITION 7. - Let $f: S \rightarrow G$ be a $c.q$ -regular function. Then:

- i) all its o -patterns are $c.o$ -regular functions;
- ii) any two o -patterns of f are $c.o$ -homotopic to each other.

Proof. - i) Like in Proposition 6, we prove that $\langle g(x) \rangle \subseteq \langle f(x) \rangle$, for all $x \in S$. Consequently, since $\langle f(x) \rangle$ is totally headed, also $\langle g(x) \rangle$ is totally headed.

Hence, by i) of Proposition 6 and by Proposition 3, g is c.o-regular.

ii) We define the homotopy like in Proposition 6. Since, $\forall x \in S$, $f(x)$ is totally headed, the subsets $\langle g(x) \rangle \cup \langle h(x) \rangle$ and $\langle h(x) \rangle$ are also totally headed. Hence, $\forall (x, t) \in S \times I$, $F(x, t)$ is totally headed and so is a c.o-homotopy between g and h , by Proposition 3. ■

3) Duality Theorem for complete homotopy classes.

We see it is possible to construct homotopy classes, by considering only c. regular functions and c.regular homotopies.

PROPOSITION 8. - *The c.o-homotopy is an equivalence relation in the set of c.o-regular functions from S to G .*

Proof. - The relation obviously satisfies the reflexive and symmetric properties. (See [2], Remark to Definition 5). Also the transitive property is true. In fact, let F (resp. J) be a c. o-homotopy between the c. o-regular functions f and g (resp. g and k). Then the function $K: S \times I \rightarrow G$, given by:

$$K(x, t) = \begin{cases} F(x, 3t) & \forall x \in S, \quad \forall t \in [0, \frac{1}{3}] \\ g(x) & \forall x \in S, \quad \forall t \in [\frac{1}{3}, \frac{2}{3}] \\ J(x, 3t-2) & \forall x \in S, \quad \forall t \in [\frac{2}{3}, 1] \end{cases},$$

is an o-homotopy between f and k .

We have to prove that k is a c.o-regular function. Let us assume that the image-envelope of the point (x, t) is non-totally headed. Then, if $t \leq \frac{1}{3}$, also the image-envelope of $(x, 3t)$ is non-totally headed for the function F . If $t \geq \frac{2}{3}$, also the image-envelope of $(x, 3t-2)$ is non-totally headed for the function J . If $\frac{1}{3} < t < \frac{2}{3}$, also the image-envelope of the point x is non-totally headed for the function g . Anyhow, we obtain a non-totally headed image-envelope for a c.o-regular function. This contradicts to Proposition 3. ■

REMARK. - By considering as homotopy between f and g that given by the sum (see [2], Remark to Defintion 5), we obtain only an o-regular function, in general.

DEFINITION 5. - Let S be a topological space and G a finite directed graph. We de-
note by $Q_c(S,G)$ (resp. $Q_c^*(S,G)$) the set of c.o-homotopy (resp. c.o*-homotopy) classes.

REMARK. - We note that $Q_c^*(S,G)$ coincides with $Q_c(S,G^*)$, and $Q_c^*(S,G^*)$ with $Q_c(S,G)$.

THEOREM 9. - Let S be a topological space and G a finite directed graph. Then
there exists a natural bijection from the set of complete o-homotopy classes $Q_c(S,G)$
to the one of complete o*-homotopy classes $Q_c^*(S,G)$.

Proof. - We denote by $F_c(S,G)$ (resp. $F_c^*(S,G)$) the set of all the c.o-regular
(resp. c.o*-regular) functions. We define a relation $\phi: F_c(S,G) \rightarrow F_c^*(S,G)$ which
sends each $f \in F_c(S,G)$ in any its o*-pattern $\phi(f)$ and similarly a relation $\psi: F_c^*(S,G)$
 $\rightarrow F_c(S,G)$ which sends each $h \in F_c^*(S,G)$ in any its o-pattern $\psi(h)$.

i) ϕ induces a function Φ from $Q_c(S,G)$ to $Q_c^*(S,G)$.

By the Remark to Proposition 5 and by i) of Proposition 7 the relation ϕ is defined
on all the set $F_c(S,G)$ and by ii) of Proposition 7 every o*-pattern of f is o*-hom-
otopic to $\phi(f)$. Then we define a function $\bar{\phi}: F_c^*(S,G) \rightarrow Q_c(S,G)$ by putting:

$$\forall f \in F_c(S,G), \quad \bar{\phi}(f) = \{\phi(f)\}.$$

Now let g be a function c.o-homotopic to f by the homotopy H , and let $\phi(g)$ be an
o*-pattern of g . We construct the c.o-homotopy:

$$F(x,t) = \begin{cases} f(x) & 0 \leq t \leq \frac{1}{3}, \\ H(x, 3t-1) & \frac{1}{3} \leq t \leq \frac{2}{3}, \\ g(x) & \frac{2}{3} \leq t \leq 1. \end{cases}$$

Let \hat{F} be an o*-pattern of F , it follows from Proposition 7* that \hat{F} is a c.o*-homotopy
between the restrictions $\hat{f} = \hat{F}/_{S \times \{0\}}$ and $\hat{g} = \hat{F}/_{S \times \{1\}}$. Since $f = F/_{S \times \{0\}}$ and H does
not interfere in the construction of \hat{f} , \hat{f} is an o*-pattern of f . Similarly, \hat{g} is an o*-
pattern of g . Then by Proposition 7*, $\phi(f)$ and \hat{f} are c.o*-homotopic, and the same
happens for $\phi(f)$ and \hat{g} . For the relation is transitive, $\phi(f)$ is c.o*-homotopic to $\phi(g)$.

Since the function $\bar{\phi}$ is compatible with the c.o-homotopy relation in $F_c(S,G)$, ϕ induces a function ϕ from $Q_c(S,G)$ to $Q_c^*(S,G)$ given by:

$$\forall \alpha \in Q_c(S,G), \quad \phi(\alpha) = \{\phi(f)\}, \text{ where } f \text{ is a representative of } \alpha.$$

ii) ψ induces a function ψ from $Q_c^*(S,G)$ to $Q_c(S,G)$.

By dual arguments we can prove that the required function ψ is individualized by putting:

$$\forall \beta \in Q_c^*(S,G), \quad \psi(\beta) = \{\psi(h)\}, \text{ where } h \text{ is a representative of } \beta.$$

iii) ϕ and ψ are bijective functions.

We have only to prove that $\psi\phi$ is the identity in $Q_c(S,G)$ and $\phi\psi$ the one in $Q_c^*(S,G)$. Let α be a class of $Q_c(S,G)$ and $f \in \alpha$ a c.o-regular function. We have $\phi(\alpha) = \{\phi(f)\}$, and, successively, $\psi\phi(\alpha) = \{\psi\phi(f)\}$. We observe that the function $\psi\phi(f)$ is c.o-regular by Propositions 7, 7*. Following i) of the proof of Proposition 6, it results, $\forall v \in G, \overline{v\psi\phi(f)} \subseteq \overline{v\phi(f)} \subseteq \overline{v^f}$, then like ii) of the same proof, we can construct a c.o-homotopy between f and $\psi\phi(f)$. Consequently, $\psi\phi(\alpha) = \{\psi\phi(f)\} = \{f\} = \alpha$. Similarly, it results, $\forall \beta \in Q_c^*(S,G), \phi\psi(\beta) = \beta$. ■

4) Duality theorem for homotopy classes.

By the two Normalization Theorems R_h, R_e , the duality can be extended to the homotopy classes $Q(S,G)$ and $Q^*(S,G)$.

PROPOSITION 10. - *Let $S \times I$ be a normal topological space and G a finite directed graph. Then there exists a natural bijection from the set of c.o-homotopy classes $Q_c(S,G)$ to the one of o-homotopy classes $Q(S,G)$.*

Proof. - Let $F(S,G)$ and $F_c(S,G)$ be the sets of o-regular and c.o-regular functions from S to G and $j: F_c(S,G) \rightarrow F(S,G)$ the identical embedding. Obviously, j is compatible with the c.o-homotopy relation in $F_c(S,G)$ and with the o-homotopy relation in $F(S,G)$, hence j induces a function J from $Q_c(S,G)$ to $Q(S,G)$. Moreover, J is onto by R_h , and it is one to one by R_e . ■

Finally, by Propositions 10, 10* and Theorem 9 we obtain:

THEOREM 11. - *Let S be a countably paracompact normal space and G a finite directed graph. Then there exists a natural bijection from the set of o -homotopy classes $O(S,G)$ to the one of o^* -homotopy classes $O^*(S,G)$.*

Proof. In fact the assumption on S is equivalent to suppose that S and $S \times I$ are normal spaces. (See Introduction). ■

REMARK 1. - In general the previous result does not hold for any topological space. (See Example 13.5).

REMARK 2. - In the foregoing conditions it follows that the sets $Q(S,G)$, $Q(S,G^*)$, $Q^*(S,G)$, $Q^*(S,G^*)$ can be identified.

PART TWO. DUALITY THEOREM FOR REGULAR FUNCTIONS BETWEEN PAIRS.

5) Balanced functions.

We can characterize the regular functions between pairs, similarly to Propositions 2, 3, by the following:

PROPOSITION 12. - *Let $f: S, S' \rightarrow G, G'$ be a function from a pair of topological spaces S, S' to a pair of finite directed graphs G, G' and $f': S' \rightarrow G'$ the restriction of $f: S \rightarrow G$ to S' . Then f is an o -regular function, iff $f(x)$ is a head of $\langle f(x) \rangle$ in G , for all $x \in S$; while $f'(x)$ is a head of $\langle f'(x) \rangle$ in G' , for all $x \in S'$. Moreover, f is $c.o$ -regular, iff also the subsets $\langle f(x) \rangle$ are totally headed in G and all the subsets $\langle f'(x) \rangle$ are totally headed in G' . ■*

REMARK. - Consequently, if G is an undirected graph, a function $f: S, S' \rightarrow G, G'$

is strongly regular, iff $\langle f(x) \rangle$ is totally headed in G for all $x \in S$, and so is $\langle f'(x) \rangle$ in G' for all $x \in S'$.

Unfortunately the considerations developed in Part one in order to obtain the Duality Theorem for regular functions can not be directly generalized to regular functions between pairs, since there does not exist an o^* -pattern of any c.o-regular function $f: S, S' \rightarrow G, G'$ in general. Hence we must add the following new condition:

$$T_G(\langle f(x') \rangle) \cap T_{G'}(\langle f'(x') \rangle) \neq \phi, \forall x' \in S',$$

and consequently we put:

DEFINITION 6. - Let $f: S, S' \rightarrow G, G'$ be a function from a pair of topological spaces S, S' to a pair of finite directed graph G, G' and let $f': S' \rightarrow G'$ be the restriction to S' of $f: S \rightarrow G$. The function f is said to be balanced in (S, S') or simply a b.function if, for all $x' \in S'$ and for all $v \in G$, it is $x' \in \overline{V^f} \Rightarrow x' \in \overline{V^{f'}}$; i.e., for all $x' \in S'$, $\langle f(x') \rangle = \langle f'(x') \rangle$.

REMARK 1. - If the restriction f' of a b.function f is c.o-regular, by R_a and Proposition 3 it results $T_G(\langle f(x') \rangle) \cap T_{G'}(\langle f'(x') \rangle) \neq \phi$, since now we have $T_{G'}(\langle f'(x') \rangle) \subseteq T_G(\langle f(x') \rangle)$; while for a c.o-regular function it can happen that $T_G(\langle f(x') \rangle) \cap T_{G'}(\langle f'(x') \rangle) = \phi$. (See Example 13.1).

REMARK 2. - We can also write *b.o-regular function, ..., b.homotopy, ...* instead of *balanced o-regular function, ..., balanced homotopy, ...*

PROPOSITION 13. - Under the assumptions of Definition 6, if S' is an open set of S , all the functions $f: S, S' \rightarrow G, G'$ are balanced in (S, S') .

Proof. - By Proposition 1 we have $\langle f(x') \rangle = \cap \{f(U_{x'}) / U_{x'} \text{ is a neighbourhood of } x' \text{ in } S\}$, while for S' it results $\langle f'(x') \rangle = \cap \{f'(U_{x'} \cap S')\}$. Now, since S' is open in S , it follows $\cap \{f'(U_{x'} \cap S')\} = \cap \{f(U_{x'})\}$. ■

6) Patterns of a function between pairs.

As in Definitions 2, 3 we have:

DEFINITION 7. - Let $f: S, S' \rightarrow G, G'$ be a function from a pair of topological spaces S, S' to a pair of finite directed graphs G, G' . A function $g: S, S' \rightarrow G, G'$ is called an o -pattern (resp. o^* -pattern) of f , if $g: S \rightarrow G$ is an o -pattern (resp. o^* -pattern) of $f: S \rightarrow G$ and its restriction $g': S' \rightarrow G'$ is an o -pattern (resp. o^* -pattern) of $f': S' \rightarrow G'$.

REMARK. - For an o -pattern g of f , we have the following relations:

- i) $\forall x \in S-S', \quad g(x) \in H_G(\langle f(x) \rangle)$
 ii) $\forall x' \in S', \quad g(x') \in H_G(\langle f(x') \rangle) \cap H_{G'}(\langle f'(x') \rangle).$

DEFINITION 8. - Under the assumptions of Definition 7, the function $f: S, S' \rightarrow G, G'$ is called $a.o$ -regular (resp. $q.o^*$ -regular, $c.q.$ regular), if such are the function $f: S \rightarrow G$ and its restriction $f': S' \rightarrow G'$.

REMARK. - Also for pairs, we can get results similar to those of Remarks 1, 2 to Definition 3 and of Proposition 4.

Instead of Proposition 5, we have only:

PROPOSITION 14. - If a $a.o$ -regular function $f: S, S' \rightarrow G, G'$ is balanced in (S, S') , there exists an o -pattern of f .

Proof. - For all $x \in S-S'$, we proceed as in ii) of the proof of Proposition 5. While, for all $x' \in S'$, we choose as $g(x')$ the vertex with the lowest index among the vertices of $H_{G'}(\langle f'(x') \rangle) \subseteq H_G(\langle f(x') \rangle) = H_G(\langle f(x') \rangle)$. ■

REMARK 1. - In general there are no patterns of functions that are only balanced

or q.o-regular. The condition of q.o-regularity, indeed, is necessary by Proposition 5, while the condition of b.q.o-regularity is only sufficient. (See Example 13.2).

REMARK 2. - In general an o-pattern of a b.function $f: S, S' \rightarrow G, G'$ is not balanced. (See Example 13.2).

DEFINITION 9. - Two functions $f, g: S, S' \rightarrow G, G'$ from a pair of topological spaces S, S' to a pair of finite directed graphs G, G' are called c.o-homotopic (resp. c.o*-homotopic) if there exists a homotopy F between f and g , which is a c.o-regular (resp. c.o*-regular) function.

By following the proofs of Propositions 6, 7 and by using Definitions 7, 8, we can obtain properties similar to Propositions 6,7, since both the functions from S to G and the ones from S' to G' satisfy the conditions. But, on account of Remark 2 to Proposition 14, in general, the constructed o-patterns are not balanced. Nevertheless, by Proposition 13, we have:

PROPOSITION 15. - Let S be a topological space, S' an open subset of S , G a finite directed graph, G' a subgraph of G and $f: S, S' \rightarrow G, G'$ a b.c.q.regular function from S, S' to G, G' . Then:

- i) all its o-patterns are b.c.o-regular functions,
- ii) two o-patterns of f are b.c.o-homotopic to each other. ■

7) Duality Theorem for complete homotopy classes when S' is open.

Now we just state the Duality Theorem for the c.homotopy, when S' is an open subspace of S .

Similarly to Proposition 8, we can prove that the c.o-homotopy is an equivalence relation in the set of c.o-regular functions from S, S' to G, G' . Then it follows:

DEFINITION 10. - Let S be a topological space, S' a subspace of S , G a finite directed graph and G' a subgraph of G . We denote by $Q_C(S, S'; G, G')$ (resp. $Q_C^*(S, S'; G, G')$) the set of c.o-homotopy (resp. c.o*-homotopy) classes.

REMARK. - $Q_C^*(S, S'; G, G')$ coincides with $Q_C(S, S'; G^*, G'^*)$ and $Q_C(S, S'; G, G')$ with $Q_C^*(S, S'; G^*, G'^*)$.

THEOREM 16. - Let S be a topological space, S' an open subspace of S , G a finite directed graph and G' a subgraph of G . Then there exists a natural bijection ϕ from the set of complete o-homotopy classes $Q_C(S, S'; G, G')$ to the one of complete o*-homotopy classes $Q_C^*(S, S'; G, G')$.

Proof. - It is similar to that one of Theorem 9, by using Propositions 15, 15*. We just observe that, since S' is open, the functions are balanced, hence the sought patterns can be constructed. ■

REMARK. - The proof of Theorem 9 can not be generalized for any subspace S' of S . In step iii), indeed, in order to construct an o-pattern z of h , it is necessary that h is a balanced o*-pattern of f . (See Example 13.1).

8) Inductive limits.

Let S' be any subspace of S and U any open neighbourhood of S' . We have:

DEFINITION 11. - We denote by $F_C(S, S'; G, G')$ the set of c.o-regular functions from S, S' to G, G' , by $F_U = F_C(S, U; G, G')$ the set of c.o-regular functions from S, U to G, G' and by $Q_U = Q_C(S, U; G, G')$ the set of c.o-homotopy classes of functions from S, U to G, G' . Dually, we can consider $F_C^*(S, S'; G, G')$, $F_U^* = F_C^*(S, U; G, G')$ and $Q_U^* = Q_C^*(S, U; G, G')$.

Now we consider the collection of sets $\mathcal{U}_{S'} = \{ U / U \text{ is an open neighbourhood}$

of S' and, since $U_{S'}$ is decreasingly filtrated, it follows:

PROPOSITION 17. - *The family of sets $\{F_U / U \in U_{S'}\}$ with associated maps $\{\lambda_V^U / U, V \in U_{S'}, V \subseteq U\}$ is an inductive family if $\lambda_V^U : F_U \rightarrow F_V$ is the identical embedding. ■*

PROPOSITION 18. - *The associated map λ_V^U ($U, V \in U_{S'}, V \subseteq U$) defined in Proposition 17, is compatible with the c.o-homotopy in F_U and F_V .*

Proof. - If $f, g: S, U \rightarrow G, G'$ are c.o-homotopic, such are also the functions $f, g: S, V \rightarrow G, G'$. ■

PROPOSITION 19. - *Let $\Lambda_V^U: Q_U \rightarrow Q_V$ be the function induced by the identical embedding $\lambda_V^U: F_U \rightarrow F_V$, then the family of sets $\{Q_U / U \in U_{S'}\}$ with associated maps $\{\Lambda_V^U / U, V \in U_{S'}, V \subseteq U\}$ is an inductive family.*

Proof. - The family $\{Q_U\}$ is inductive since, given $U, V, W \in U_{S'} / U \subseteq V \subseteq W$, from $\lambda_W^U = \lambda_W^V \lambda_V^U$ it results $\Lambda_W^U = \Lambda_W^V \Lambda_V^U$. ■

Now, if we consider the family of bijections $\{\phi_U: Q_U \rightarrow Q_U^* / U \in U_{S'}\}$ (see Theorem 16), we obtain:

THEOREM 20. - *Let S be a topological space, S' a subspace of S , G a finite directed graph and G' a subgraph of G . Then there exists a natural bijection ϕ from the inductive limit $\varinjlim Q_U$ to $\varinjlim Q_U^*$.*

Proof. - Let $U, V \in U_{S'}$, be and $V \subseteq U$. We see that the diagram:

$$\begin{array}{ccc} Q_U & \xrightarrow{\phi_U} & Q_U^* \\ \Lambda_V^U \downarrow & & \downarrow \Lambda_V^{*U} \\ Q_V & \xrightarrow{\phi_V} & Q_V^* \end{array}$$

is commutative. Following, indeed, the proof of Theorem 9, we must just observe that the identical embedding of a pattern of $f \in F_U$ is a pattern of $f \in F_V$. Consequently, there exists a natural bijection ϕ from $\lim_{\longrightarrow} Q_U$ to $\lim_{\longrightarrow} Q_U^*$, since $\forall U \in U_{S'}$, ϕ_U is a natural bijection by Theorem 16. (See [8], 40.1). ■

9) Neighbourhood completely regular functions and homotopies.

The inductive limits of § 8 can be regarded also as sets of regular functions and homotopy classes.

DEFINITION 12. - Let $f: S, S' \rightarrow G, G'$ be a c.o-regular (resp. c.o*-regular) function from a pair of topological spaces S, S' to a pair of finite directed graphs G, G' . The function f is called neighbourhood completely o-regular (resp. neighbourhood completely o*-regular) in (S, S') , or simply n.c.o-regular (resp. n.c.o*-regular) if there exists an open neighbourhood U of S' , such that the function $f: S, U \rightarrow G, G'$ is c.o-regular (resp. c.o*-regular). The open neighbourhood U is called a balancer of $f: S, S' \rightarrow G, G'$

REMARK 1. - We call U a balancer since by Proposition 13 the function $f: S, U \rightarrow G, G'$ is balanced.

REMARK 2. - A function $f: S, S' \rightarrow G, G'$ can be b.c.o-regular without being n.c.o-regular. (See Example 13.3).

PROPOSITION 21. - The inductive limit $\lim_{\longrightarrow} F_U$ coincides with the set $F_{nc}(S, S; G, G')$ of the n.c.o-regular functions from S, S' to G, G' .

Proof. - In fact, two c.o-regular functions $f: S, U \rightarrow G, G'$ and $g: S, V \rightarrow G, G'$ ($U, V \in U_{S'}$) are equivalent iff $f: S \rightarrow G$ coincides with $g: S \rightarrow G$, since $\lambda_{U \cap V}^U(f) = \lambda_{U \cap V}^V(g)$. ■

DEFINITION 13. - Let S be a topological space, S' a subspace of S , G a finite

directed graph and G' a subgraph of G . Two n.c.o-regular (resp. n.c.o*-regular) functions $f, g: S, S' \rightarrow G, G'$ are called n.c.o-homotopic (resp. n.c.o*-homotopic), if there exist an open neighbourhood W of $S' \times I$ and a homotopy $F: S \times I, S' \times I \rightarrow G, G'$ between f and g such that $F: S \times I, W \rightarrow G, G'$ is a c.o-regular (resp. c.o*-regular) function. F is called a n.c.o-homotopy (resp. n.c.o*-homotopy).

REMARK. - $W \cap (S \times \{0\})$ and $W \cap (S \times \{1\})$ can be considered respectively balancers of f and g .

LEMMA 22. - Let S be a topological space and S' a subspace of S . Then, for every neighbourhood W of $S' \times I$ in $S \times I$, there exists a neighbourhood U of S' , such that $S' \times I \subseteq U \times I \subseteq W$.

Proof. - If x is a point of S' , then, for all $t \in I$, there is a neighbourhood of (x, t) of the form $U_x^{(t)} \times U_t \subseteq W$. Since I is compact, there exists a finite set, namely U_{t_1}, \dots, U_{t_n} , of neighbourhoods which covers I . Thus, if we put $U_x = U^{(t_1)} \cap \dots \cap U^{(t_n)}$, we have $U_x \times I$ is a neighbourhood of $\{x\} \times I$ included in W . By choosing $U = \cup U_x, \forall x \in S'$, the assertion immediately follows. ■

Directly, for open neighbourhoods we have:

PROPOSITION 23. - Under the assumptions of Definition 13, let F be a n.c.o-homotopy. Then there exists a balancer of F of the form $U \times I$, where $U \in \mathcal{U}_{S'}$. ■

PROPOSITION 24. - The n.c.o-homotopy relation is an equivalence relation in the set $F_{nc}(S, S'; G, G')$ of n.c.o-regular functions from S, S' to G, G' .

Proof. - The relation obviously satisfies the reflexive and symmetric properties. Also the transitive property is true: in fact, by using the same notations of the proof of Proposition 8, the homotopy K is c.o-regular by the same proposition. Moreover, f is n.c.o-regular, because if we construct by Proposition 23 a balancer $U \times I$

of F and a balancer $V \times I$ of J , $(U \cap V) \times I$ is a balancer of K . ■

DEFINITION 14. - Under the assumptions of Definition 13, we call $Q_{nc}(S, S'; G, G')$ (resp. $Q_{nc}^*(S, S'; G, G')$) the set of n.c.o-homotopy (resp. n.c.o*-homotopy) classes.

REMARK. - We note that $Q_{nc}^*(S, S'; G, G')$ coincides with $Q_{nc}(S, S'; G^*, G'^*)$ and $Q_{nc}^*(S, S'; G^*, G'^*)$ with $Q_{nc}(S, S'; G, G')$.

PROPOSITION 25. - The inductive limit $\lim_{\longrightarrow} Q_U$ coincides with the set $Q_{nc}(S, S'; G, G')$ of the n.c.o-homotopy classes.

Proof. - $\forall U \in U_{S'}$, let $\phi_U: F_U \rightarrow F_{nc}(S, S'; G, G')$ be the identical embedding. Since ϕ_U is compatible with the respective homotopy relations, we denote by $\Phi_U: Q_U \rightarrow Q_{nc}(S, S'; G, G')$ the induced function. Now the diagram:

$$\begin{array}{ccc} Q_U & \xrightarrow{\Phi_U} & Q_{nc}(S, S'; G, G') \\ \Lambda_V^U \downarrow & & \\ Q_V & \xrightarrow{\Phi_V} & \end{array} \quad (\forall U, V \in U_{S'} / V \subseteq U)$$

is commutative, then we can define a function $\phi: \lim_{\longrightarrow} Q_U \rightarrow Q_{nc}(S, S'; G, G')$. Moreover ϕ is onto by definition. Finally, we see that ϕ is one to one. Let, indeed, $\alpha, \beta \in Q_U / \phi(\alpha) = \phi(\beta)$ be, then, if $f \in \alpha$ and $g \in \beta$, there exists a balancer V such that f and g are c.o-homotopic. Consequently, we have $\Lambda_{U \cap V}^U \alpha = \Lambda_{U \cap V}^U \beta$. ■

Then, Theorem 20 becomes:

THEOREM 26. - Let S be a topological space, S' a subspace of S , G a finite directed graph, G' a subgraph of G . Then there exists a natural bijection from the set of neighbourhood complete o-homotopy classes $Q_{nc}(S, S'; G, G')$ to the one of neighbourhood complete o*-homotopy classes $Q_{nc}^*(S, S'; G, G')$. ■

10) Duality Theorem for homotopy classes.

In addition to the Extension Theorem R_c , we need the following:

PROPOSITION 27. - Let S be a normal topological space, S' a closed subspace of S , X a closed subset of S' , G a finite directed graph, G' a subgraph of G and $f: S, S' \rightarrow G, G'$ an o -regular function. Then there exist a closed neighbourhood W of X and an o -regular function $g: S, S' \rightarrow G, G'$, which is o -homotopic to f and such that $g: S, S' \cup W \rightarrow G, G'$ is o -regular.

Proof. - It is similar to that one of Theorem 20 in [2], by putting $X^* = X$, rather than $X^* = S'$. ■

Moreover, if we recall the definition of singularity (see Background), by P_d the Extension Theorem can be completed by the following:

PROPOSITION 28. - Let S be a normal topological space, S' a closed subspace of S , G a finite directed graph, G' a subgraph of G and $f: S, S' \rightarrow G, G'$ a $c.o$ -regular function. Then there exists a closed neighbourhood W of S' and a function $g: S, S' \rightarrow G, G'$, which is o -homotopic to f and such that the function $g: S, W \rightarrow G, G'$ is $c.o$ -regular. (See [2], Corollary 22). ■

Similarly, we have (see also [2], Corollaries 12, 19) :

PROPOSITION 29. - Under the assumptions of Proposition 27, if $f: S, S' \rightarrow G, G'$ is $c.o$ -regular, so is also the function $g: S, S' \cup W \rightarrow G, G'$. ■

PROPOSITION 30. - Let $S \times I$ a normal topological space, S' a closed subspace of S , G a finite directed graph and G' a subgraph of G . Then two $c.o$ -homotopic $n.c.o$ -regular functions $f, g: S, S' \rightarrow G, G'$ are also $n.c.o$ -homotopic.

Proof. - Let the open neighbourhood U be a balancer of f and g , and let $F: S \times I, S' \times I \rightarrow G, G'$ be a $c.o$ -homotopy between f and g . We define the $c.o$ -homotopy $J: S \times I,$

$S' \times I \rightarrow G, G'$, given by:

$$J(x, t) = \begin{cases} f(x) & \forall x \in S, \quad \forall t \in [0, \frac{1}{3}] \\ F(x, 3t-1) & \forall x \in S, \quad \forall t \in [\frac{1}{3}, \frac{2}{3}] \\ g(x) & \forall x \in S, \quad \forall t \in [\frac{2}{3}, 1]. \end{cases} \quad (\text{See [3], Theorem 16}).$$

Since S is normal, there exists a closed neighbourhood W of S' included in U . We put $Z = W \times [0, \frac{1}{4}] \cup S' \times [\frac{1}{4}, \frac{3}{4}] \cup W \times [\frac{3}{4}, 1]$ and we note that the function $J: S \times I, Z \rightarrow G, G'$ is c.o-regular, since $W \times [0, \frac{1}{4}] \subset U \times [0, \frac{1}{3}]$, $S' \times [\frac{1}{4}, \frac{3}{4}] \subset S' \times I$ and $W \times [\frac{3}{4}, 1] \subset U \times [\frac{2}{3}, 1]$. Moreover, we can apply Propositions 27, 29, since Z is closed, $S' \times [\frac{1}{4}, \frac{3}{4}]$ is a closed subset of Z and $S \times I$ is normal. Then we can construct a closed neighbourhood T of $S' \times [\frac{1}{4}, \frac{3}{4}]$ and a c.o-regular function $K: S \times I, Z \cup T \rightarrow G, G'$ which is also a homotopy between f and g , by choosing the closed neighbourhoods $L^{(i, j, k)}$, which we employ, disjointed from $S \times \{0\}$ and $S \times \{1\}$. Finally, since $Z \cup T$ is a closed neighbourhood of $S' \times I$, it follows immediately that f and g are n.c.o-homotopic. ■

THEOREM 31. - Let $S \times I$ be a normal topological space, S' a closed subspace of S , G a finite directed graph and G' a subgraph of G . Then there exists a natural bijection from the set of n.c.o-homotopy classes $O_{nc}(S, S'; G, G')$ to the one of o-homotopy classes $Q(S, S'; G, G')$.

Proof. - Let $j: F_{nc}(S, S'; G, G') \rightarrow F(S, S'; G, G')$ be the identical embedding. Since two n.c.o-homotopic functions are also o-homotopic, j induces a function J from $Q_{nc}(S, S'; G, G')$ to $Q(S, S'; G, G')$. Moreover, J is onto by R_p and Proposition 28 and it is one to one by R_e and Proposition 30. ■

Finally, by Theorems 31, 31* and 26 we obtain (see Theorem 11):

THEOREM 32. - Let S be a countably paracompact normal space, S' a closed subspace of S , G a finite directed graph and G' a subgraph of G . Then there exists a natural bijection from the set of o-homotopy classes $O(S, S', G, G')$ to the one of o*-homotopy classes $Q^*(S, S'; G, G')$. ■

REMARK 1. - In general the previous result does not hold for any topological space. (See Example 13.4).

REMARK 2. - In the foregoing conditions it follows that the sets $Q(S, S'; G, G')$, $Q(S, S'; G^*, G'^*)$, $Q^*(S, S', G, G')$, $Q^*(S, S'; G^*, G'^*)$ can be identified.

11) Case of n subspaces and of n subgraphs.

The previous results between pairs can be easily generalized to the case between $(n+1)$ -tuples. (See [2], § 8 b).

Let S be a topological space, G a finite directed graph, S_1, \dots, S_n subspaces of S and G_1, \dots, G_n subgraphs of G such that S_j is a subspace of S_i and G_j is a subgraph of G_i , $\forall i, j = 1, \dots, n$, $j > i$.

In this case we have to consider functions $f: S, S_1, \dots, S_n \rightarrow G, G_1, \dots, G_n$ between $(n+1)$ -tuples and their restrictions $f_1: S_1 \rightarrow G_1, \dots, f_n: S_n \rightarrow G_n$.

We only remark that:

1) A function $f: S, S_1, \dots, S_n \rightarrow G, G_1, \dots, G_n$ is said to be *balanced* in (S, S_1, \dots, S_n) if:

$$\text{i) } \forall x_1 \in S_1, \quad \langle f(x_1) \rangle = \langle f_1(x_1) \rangle,$$

$$\text{ii) } \forall x_2 \in S_2, \quad \langle f(x_2) \rangle = \langle f_1(x_2) \rangle = \langle f_2(x_2) \rangle,$$

...

$$\text{n) } \forall x_n \in S_n, \quad \langle f(x_n) \rangle = \langle f_1(x_n) \rangle = \dots = \langle f_n(x_n) \rangle. \quad (\text{See Definition 6}).$$

2) If the subspaces S_1, \dots, S_n are open in S , all the functions $f: S, S_1, \dots, S_n \rightarrow G, G_1, \dots, G_n$ are balanced in (S, S_1, \dots, S_n) . (See Proposition 13). Hence the Duality Theorem for complete homotopy classes holds when all the subspaces are open. (See Theorem 16).

3) If we denote by U_{S_1}, \dots, U_{S_n} the collections of open neighbourhoods respectively of the subspaces S_1, \dots, S_n , in $U_{S_1} \times \dots \times U_{S_n}$ we can consider the subset U of all the n -tuples $U = (U_1, \dots, U_n)$ such that $U_1 \supseteq \dots \supseteq U_n$. By putting $U \leq V \Leftrightarrow U_1 \subseteq V_1, \dots, U_n \subseteq V_n$, it follows that U is decreasingly filtrated, then the families of sets $\{F_U / U \in U\}$ and $\{Q_U / U \in U\}$ are inductive and there exists a natural bijection between $\lim_{\longrightarrow} Q_U$ and $\lim_{\longrightarrow} Q_U^*$. (See Theorem 20).

4) A function $f: S, S_1, \dots, S_n \rightarrow G, G_1, \dots, G_n$ is called *n.c.o-regular* in (S, S_1, \dots, S_n) if in U there exists a n -tuple $U = (U_1, \dots, U_n)$ such that the function $f: S, U_1, \dots, U_n \rightarrow G, G_1, \dots, G_n$ is c.o-regular. (See Definition 12).

Then two n.c.o-regular functions $f, g: S, S_1, \dots, S_n \rightarrow G, G_1, \dots, G_n$ are called *n.c.o-homotopic* if there exists a homotopy $F: S \times I, S_1 \times I, \dots, S_n \times I \rightarrow G, G_1, \dots, G_n$ which is a n.c.o-regular function (See Definition 13).

Hence by 3) we obtain a natural bijection between the sets of n.c.homotopy classes $Q_{nc}(S, S_1, \dots, S_n; G, G_1, \dots, G_n)$ and $Q_{nc}^*(S, S_1, \dots, S_n; G, G_1, \dots, G_n)$. (See Theorem 26).

Moreover, if $S \times I$ is a normal space and S_1, \dots, S_n are closed subspaces of S , we also observe that:

5) We can generalize the Normalization Theorems (R_b, R_e) following the construction used in [3], Final remark i).

6) For the generalization of the Extension Theorems (see R_c , Proposition 27), let $f: S, S_1, \dots, S_n \rightarrow G, G_1, \dots, G_n$ be an o-regular function. By following what we said in [2], §8 b, it results:

i) We can construct a closed neighbourhood U_n of S_n and an o-regular function $g^{(1)}: S, S_1 \cup U_n, \dots, S_{n-1} \cup U_n, U_n \rightarrow G, G_1, \dots, G_n$ o-homotopic to f .

ii) Let V_n be a closed neighbourhood of S_n such that $S_n \subseteq V_n \subseteq A_n \subseteq U_n$, where A_n is an open set. We construct a closed neighbourhood U_{n-1} of $S_{n-1} \cup U_n$ and an o-regular function $g^{(2)}: S, S_1 \cup U_{n-1}, \dots, S_{n-2} \cup U_{n-1}, U_{n-1} \rightarrow G, G_1, \dots, G_{n-1}$ o-homotopic to $g^{(1)}$ by choosing the closed neighbourhoods, which we employ in the construction of $g^{(2)}$, disjoint from V_n . Consequently, also the function $g^{(2)}: S, S_1 \cup U_{n-1}, \dots, S_{n-2} \cup U_{n-1}, U_{n-1}, V_n \rightarrow G, G_1, \dots, G_n$ is o-regular and o-homotopic to f .

iii) Let V_{n-1} be a closed neighbourhood of $S_{n-1} \cup V_n$ such that $S_{n-1} \cup V_n \subseteq V_{n-1} \subseteq A_{n-1} \subseteq U_{n-1}$, where A_{n-1} is an open set. Then we go on as in step ii).

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n) Let $g^{(n-1)}: S, S_1 \cup U_2, U_2, V_3, \dots, V_n \rightarrow G, G_1, \dots, G_n$ be the o-regular function, o-homotopic to f , which follows from the previous process. Then, let V_2 be a closed neighbourhood of $S_2 \cup V_3$ such that $S_2 \cup V_3 \subseteq V_2 \subseteq A_2 \subseteq U_2$, where A_2 is an open set. We construct a closed neighbourhood U_1 of $S_1 \cup U_2$ and an o-regular func

tion $g^{(n)}: S, U_1 \rightarrow G, G_1$ o-homotopic to $g^{(n-1)}$ by choosing the closed neighbourhoods, which we employ in the construction of $g^{(n)}$ disjointed from V_2 . Consequently, also the function $g^{(n)}: S, U_1, V_2, \dots, V_n \rightarrow G, G_1, \dots, G_n$ is o-regular and o-homotopic to f . Since U_1, V_2, \dots, V_n are respectively closed neighbourhoods of S_1, \dots, S_n , the function $g^{(n)}$ is the sought extension.

7) Similarly to Theorem 31, from 6) it follows that there exists a natural bijection between the sets of o-homotopy classes $Q_{nc}(S, S_1, \dots, S_n; G, G_1, \dots, G_n)$ and $Q(S, S_1, \dots, S_n; G, G_1, \dots, G_n)$, when $S \times I$ is a normal space and the subspaces S_i are closed.

8) Finally, by 4) we obtain the *conclusive theorem* (see Theorem 32):

THEOREM 33. - *Let S be a countably paracompact normal space, G a finite directed graph, S_1, \dots, S_n closed subspaces of S and G_1, \dots, G_n subgraphs of G , such that S_j is a subspace of S_i and G_j is a subgraph of G_i , $\forall i, j = 1, \dots, n, j > i$. Then there exists a natural bijection from the set of o-homotopy classes $Q(S, S_1, \dots, S_n; G, G_1, \dots, G_n)$ to the one of o^* -homotopy classes $Q^*(S, S_1, \dots, S_n; G, G_1, \dots, G_n)$. ■*

12) Duality Theorems for homotopy groups.

If we apply the previous results to the particular case of homotopy groups (see [8]), we obtain:

THEOREM 34. - *Let G be a finite directed graph and v a vertex of G . Then there exists a natural isomorphism between the m -th o-homotopy group $Q_m(G, v)$ and the m -th o^* -homotopy group $Q_m^*(G, v)$.*

Proof. - At first, let I^m be the unite m -cube and \dot{I}^m its boundary. We note that now $Q_m(G, v)$ and $Q_m^*(G, v)$ coincide with $Q(I^m, \dot{I}^m; G, v)$ and $Q^*(I^m, \dot{I}^m; G, v)$ respectively, and every function $f: I^m, \dot{I}^m \rightarrow G, v$ is a loop. Since I^m is a compact normal space and \dot{I}^m a closed subspace, by Theorem 32 there exists a natural bijection between $Q_m(G, v)$ and $Q_m^*(G, v)$, for all $m \geq 0$. Moreover, if $f, h: I^m, \dot{I}^m \rightarrow G, v$ are two loops with balancers U, V respectively, we can also call sum of loops f, h the function $f \cdot h$

given by:

$$(f \star h)(x_1, \dots, x_m) = \begin{cases} f(3x_1, x_2, \dots, x_m) & \forall x_1 \in [0, \frac{1}{3}] \\ f(1, x_2, \dots, x_m) = h(0, x_2, \dots, x_m) & \forall x_1 \in [\frac{1}{3}, \frac{2}{3}] \\ h(3x_1 - 2, x_2, \dots, x_m) & \forall x_1 \in [\frac{2}{3}, 1] \end{cases}$$

It follows that $f \star h$ is a n.c.o-regular function, since there exists a balancer W of $f \star h$ of the form $W = U' \cup [\frac{1}{3}, \frac{2}{3}] \times I^{m-1} \cup V'$, where U', V' are the correspondents of U, V which result from concentrating f, h on $[0, \frac{1}{3}] \times I^{m-1}, [\frac{2}{3}, 1] \times I^{m-1}$ respectively. Moreover the operation \star is compatible with the n.c.o-homotopy, since the previous sum of n.c.o-homotopies is a n.c.o-regular function. Hence \star induces an operation in $Q_{nc}(I^m, \dot{I}^m, G, v)$.

Now if $g: I^m, U \rightarrow G, v$ and $k: I^m, V \rightarrow G, v$ are two o^* -patterns of $f: I^m, U \rightarrow G, v$ and $h: I^m, V \rightarrow G, v$ respectively, it follows that $g \star k: I^m, W \rightarrow G, v$ is an o^* -pattern of $f \star h: I^m, W \rightarrow G, v$. Then the natural bijection in Theorem 26 between $Q_{nc}(I^m, \dot{I}^m, G, v)$ and $Q_{nc}^*(I^m, \dot{I}^m, G, v)$ is an isomorphism.

Finally, $Q_{nc}(I^m, \dot{I}^m, G, v)$ is isomorphic to $Q(I^m, \dot{I}^m, G, v) = Q_m(G, v)$. There exists, indeed, a natural bijection by Theorem 31 and the loop $f \star h$ is o -homotopic to the loop $f+h$, given by:

$$(f+h)(x_1, \dots, x_m) = \begin{cases} f(2x_1, x_2, \dots, x_m) & \forall x_1 \in [0, \frac{1}{2}] \\ h(2x_1 - 1, x_2, \dots, x_m) & \forall x_1 \in [\frac{1}{2}, 1] \end{cases} \text{ (See [7], Properties 3.3, 3.7).}$$

Thus the theorem follows. ■

THEOREM 35. - Let G be a finite directed graph, G' a subgraph of G and v a vertex of G' . Then there exists a natural isomorphism between the relative o -homotopy group $Q_m(G, G', v)$ and the relative o^* -homotopy group $Q_m^*(G, G', v)$.

Proof. - Let J^{m-1} be the union of the $(m-1)$ -faces of I^m , different from the face $x_m = 0$. We note that $Q_m(G, G', v)$ and $Q_m^*(G, G', v)$ coincide with $Q(I^m, \dot{I}^m, J^{m-1}; G, G', v)$ and $Q^*(I^m, \dot{I}^m, J^{m-1}; G, G', v)$ respectively, and every function $f: I^m, \dot{I}^m, J^{m-1} \rightarrow G, G', v$ is a relative loop. By Theorem 33 there exists a natural bijection between $Q_m(G, G', v)$ and $Q_m^*(G, G', v)$ for $m \geq 1$. Proceeding as before we obtain a natural isomorphism between $Q_{nc}(I^m, \dot{I}^m, J^{m-1}; G, G', v)$ and $Q_{nc}^*(I^m, \dot{I}^m, J^{m-1}; G, G', v)$ for $m > 1$. Then we have

also a natural isomorphism between $Q_m(G, G', v)$ and $Q_m^*(G, G', v)$. ■

REMARK. - We define as sum of loops f, h the function $f * h$ instead of $f + h$, since we always must obtain a n.c.o-regular function. (See Remark to Proposition 8). Nevertheless in the proof of Theorem 34 we can also choose as sum of loops the function $f + h$, since G' is a singleton.

13) Examples.

13.1) There exists a c.o-regular function without o^* -patterns.

Let $S = [0, 1]$ be the unit interval, $S' = \{0\}$ the subspace of S , $G = \{a, b; b \rightarrow a\}$ the directed graph and $G' = \{a\}$ the subgraph of G . Then the function $f: S, S' \rightarrow G, G'$ given by:

$$\begin{cases} f(0) = a \\ f([0, 1]) = \{b\} \end{cases}$$

is not balanced since $\{a, b\} = \langle f(0) \rangle \supset \langle f'(0) \rangle = \{a\}$. Moreover, there is no pattern of f , in fact it is $T_G(\langle f(0) \rangle) = \{b\}$ and $T_{G'}(\langle f'(0) \rangle) = \{a\}$, hence it follows $T_G(\langle f(0) \rangle) \cap T_{G'}(\langle f'(0) \rangle) = \emptyset$.

13.2) There exists a non-balanced o^* -pattern of a b.c.o-regular function.

Let $S = I \times I$ be the topological space, $S' = I \times \{0\}$ the subspace of S , $G = \{a, b; a \rightarrow b, b \rightarrow a\}$ the directed graph and $G' = \{a, b; a \rightarrow b\}$ the subgraph of G . Then the function given by:

$$\begin{cases} f(\{0\} \times I) = \{a\} \\ f([0, 1] \times I) = \{b\} \end{cases}$$

is c.o-regular and balanced since:

$$\langle f(0, t) \rangle = \langle f'(0, t) \rangle = \begin{cases} \{a, b\} & \text{for } t = 0, \\ \{b\} & \forall t \in]0, 1[. \end{cases}$$

For it is $T_{G'}(\langle a, b \rangle) = \{b\}$, it follows that the function $g: S, S' \rightarrow G, G'$, given by:

$$\begin{cases} g(0,0) = b \\ g(\{0\} \times]0,1]) = \{a\} \\ g(]0,1[\times I) = \{b\} \end{cases}$$

is an o^* -pattern of f . But the function g is not balanced since $\langle g(0,0) \rangle = \{a,b\} \supset \{b\} = \langle g'(0,0) \rangle$. Nevertheless g is also an o -pattern of itself. In fact we have $\mathcal{H}_G(\langle g(0,0) \rangle) \cap \mathcal{H}_{G'}(\langle g'(0,0) \rangle) = \{b\}$.

13.3) *There exists a b.c.o-regular function which is not n.c.o-regular.*

Let $S = I \times I$ be the topological space, $S' = I \times \{0\}$ the subspace of S , $G = \{a,b; a \rightarrow b, b \rightarrow a\}$ the directed graph and $G' = \{a,b; a \rightarrow b\}$ the subgraph of G . Then the function $f: S, S' \rightarrow G, G'$ given by:

$$\begin{cases} f(]0, \frac{1}{2}[\times \{0\}) = \{a\} \\ f(] \frac{1}{2}, 1[\times \{0\}) = \{b\} \\ f(]0, \frac{1}{2}[\times]0, 1]) = \{a\} \\ f(] \frac{1}{2}, 1[\times]0, 1]) = \{b\} \end{cases}$$

is b.c.o-regular since:

$$\langle f(t,0) \rangle = \langle f'(t,0) \rangle = \begin{cases} \{a\} & \forall t \in]0, \frac{1}{2}[\\ \{a,b\} & \text{for } t = \frac{1}{2} \\ \{b\} & \forall t \in] \frac{1}{2}, 1[. \end{cases}$$

But f is not n.c.o-regular. For every open neighbourhood U of S' , indeed, the function $\hat{f}: U \rightarrow G'$ is not o -regular since it is $b \neq a$ and $B^{\hat{f}} \cap A^{\hat{f}} \neq \emptyset$

13.4) *There exist a pair of topological spaces S, S' and a pair of directed graphs G, G' such that $Q(S, S'; G, G')$ and $O^*(S, S'; G, G')$ are not equipotent (see [9]).*

Let $S = \{x, x', y, y'\}$ be the topological space with the collection of open sets given by $\emptyset, \{x\}, \{x'\}, \{x, x'\}, \{x, x', y\}, \{x, x', y'\}, S$ and let $G = \{a, a', b, b'; a \rightarrow b, a \rightarrow b', a' \rightarrow b, a' \rightarrow b'\}$ be the directed graph. We obtain that:

- i) All the non-bijective o -regular (resp. o^* -regular) functions are o -homotopic (resp. o^* -homotopic) among themselves and particularly they are o -homotopic (resp. o^* -homotopic) to the constant function $f_0: (x, x', y, y') \rightarrow (a, a, a, a)$.
- ii) There exist only the following four o -regular bijective functions:

$f_1: (x, x', y, y') \rightarrow (b, b', a, a')$, $f_2: (x, x', y, y') \rightarrow (b', b, a, a')$, $f_3: (x, x', y, y') \rightarrow (b, b', a', a)$, $f_4: (x, x', y, y') \rightarrow (b', b, a', a)$ and the following four o^* -regular bijective functions: $f_1^*: (x, x', y, y') \rightarrow (a, a', b, b')$, $f_2^*: (x, x', y, y') \rightarrow (a', a, b, b')$, $f_3^*: (x, x', y, y') \rightarrow (a, a', b', b)$, $f_4^*: (x, x', y, y') \rightarrow (a', a, b', b)$. We note that f_1, f_2, f_3, f_4 (resp. $f_1^*, f_2^*, f_3^*, f_4^*$) are not c.o-regular (resp. c.o^{*}-regular) functions.

iii) The functions f_1, f_2, f_3, f_4 (resp. $f_1^*, f_2^*, f_3^*, f_4^*$) are not o-homotopic (resp. o^{*}-homotopic) either among themselves or to f_0 . Thus both $Q(S, G)$ and $Q^*(S, G)$ consist of five classes.

iv) Let $S' = \{y\}$ and $G' = \{a\}$ be. It follows that $Q(S, S'; G, G')$ consists of the three classes $\{f_0\}, \{f_1\}, \{f_2\}$, while $Q^*(S, S'; G, G')$ consists only of the class $\{f_0\}$.

v) Every c.o-regular (resp. c.o^{*}-regular) function is c.o-homotopic (resp. c.o^{*}-homotopic) to the constant function. Then Theorem 26 holds since $Q_{nc}(S, S'; G, G')$ (resp. $Q_{nc}^*(S, S'; G, G')$) consists of the class $\{f_0\}$.

13.5) There exist a topological space S and a directed graph G such that $Q(S, G)$ and $Q^*(S, G)$ are not equipotent (see [9]).

Let $S = \{x, x', y, y', y''\}$ be the topological space with the collection of open sets given by $\emptyset, \{x\}, \{x'\}, \{x, x'\}, \{x, x', y\}, \{x, x', y'\}, \{x, x, y''\}, \{x, x', y, y'\}, \{x, x', y, y''\}, \{x, x', y', y''\}, S$ and let $G = \{a, a', b, b', b''; a \rightarrow b, a \rightarrow b', a \rightarrow b'', a' \rightarrow b, a' \rightarrow b', a' \rightarrow b''\}$ be the directed graph. By the results of 13.4, in order to obtain regular functions which do not belong to the class of constant functions, it is necessary that the range of S consists of the vertices a, a' and of two vertices at least among b, b', b'' . Thus we consider functions which are not c.o-regular and such that:

i) The image of $\{x, x'\}$ is given by two of the three elements b, b', b'' .

ii) The image of $\{y, y', y''\}$ is given by the two elements a, a' .

Then there exist $6 \cdot 6 = 36$ possibilities, and, consequently, $Q(S, G)$ consists of 37 classes.

On the contrary for the o^{*}-regularity condition, we consider functions which are not c.o^{*}-regular and such that:

i^{*}) The image of $\{x, x'\}$ is given by the two elements a, a' .

ii^{*}) The image of $\{y, y', y''\}$ is given by at least two of the three elements b, b', b'' .

Then there exist $2 \cdot 24 = 48$ possibilities, and, consequently, $Q^*(S, G)$ consists of 49 classes.

We remark that Theorem 9 holds since $Q_c(S, G)$ (resp. $Q_c^*(S, G)$) consists of the class $\{f_0\}$.

REMARK. - The topological space considered in Examples 4, 5 are quasi-compact, T_0 , non- T_1 spaces. For other similar examples which concern quasi-compact T_1 , non- T_2 spaces, see [9].

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