

ON THE p -STRESS ENERGY TENSOR AND ITS APPLICATIONS

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Abstract. *We define the p -stress energy tensor and obtain a monotonicity inequality and Liouville-type theorem for p -harmonic maps.*

1 Introduction

Let $f : (M, g) \rightarrow (N, h)$ be a smooth map between Riemannian manifolds with metrics g and h respectively. Then its energy density $e(f) : M \rightarrow R$ is defined by

$$e(f) := \frac{1}{2}|df|^2,$$

where $|\cdot|$ denotes the Hilbert-Schmidt norm of the differential df of f , which is the differential 1-form with values in the induced vector bundle $f^{-1}TN$ ($TN =$ the tangent bundle of N) over M . A.H. Taub suggested that the stress energy tensor, which is defined by

$$S_f := e(f)g - f^*h$$

should be useful in the theory of harmonic maps(see [1]), where f^*h denotes a pull-back 2-tensor field by f , which is symmetric and semi-positive. Indeed, recent developments have confirmed Taub's prediction (cf.[1,4,5]).

In this note, we define the p -stress energy tensor of f and show that it is closely related to the theory of p -harmonic maps.

2 Preliminaries

Let (M, g) and (N, h) be Riemannian manifolds of dimension m and n respectively. For a smooth map $f : (M, g) \rightarrow (N, h)$ and each $p \in [2, \infty)$, the p -energy density $e_p(f)$ and the p -energy $E_p(f)$ of f are respectively defined by

$$e_p(f) := \frac{1}{p}|df|^p,$$

$$E_p(f) := \int_M e_p(f) dv_g,$$

where dv_g is the volume element of M . The p -energy $E_p(f)$ may be infinite, but when M is compact, it has to be finite. We call a symmetric 2-tensor \tilde{S}_f

$$\tilde{S}_f := e_p(f)g - |df|^{p-2}f^*h$$

the p -stress energy tensor, which is a natural generalization of the stress energy tensor S_f . A smooth map f is said to be p -harmonic if it is a critical point of p -energy functional, that is,

$$\left. \frac{dE_p(f_t)}{dt} \right|_{t=0} = 0$$

for any one-parameter family of maps $f_t : M \rightarrow N$ with $f_0 = f$. Note that 2-harmonic maps are harmonic maps by definition. We denote by ∇ and ${}^N\nabla$ the Levi-Civita connections of M and N respectively. Let $\tilde{\nabla}$ denotes the induced connection on the induced vector bundle $f^{-1}TN$ from ${}^N\nabla$ and f . For a local orthonormal frame field $\{e_i\}_{i=1}^m$ on M , we define the p -tension field $\tau_p(f)$ of f by

$$\begin{aligned} \tau_p(f) &:= \sum_{i=1}^m [\tilde{\nabla}_{e_i}(|df|^{p-2}df(e_i)) - |df|^{p-2}df(\nabla_{e_i}e_i)] \\ &= \sum_{i=1}^m [\tilde{\nabla}_{e_i}(|df|^{p-2}df)](e_i), \end{aligned} \tag{2.1}$$

where $\tilde{\nabla}$ is the induced connection on the vector bundle $T^*M \otimes f^{-1}TN$. In the case of $p = 2$, $\tau_p(f)$ is nothing but the tension field $\tau(f)$. The first variation formula (cf.[3]) for a smooth map $f : M \rightarrow N$ is given by

$$\left. \frac{dE_p(f_t)}{dt} \right|_{t=0} = - \int_M h(V, \tau_p(f)) dv_g,$$

where $V := \left. \frac{df_t}{dt} \right|_{t=0}$ may be viewed as a vector field in N along f , that is, $V \in \Gamma(f^{-1}TN)$ (=the set of smooth cross-sections of $f^{-1}TN$). Therefore a smooth map $f : M \rightarrow N$ is a p -harmonic map if and only if the p -tension field $\tau_p(f) = 0$. In the sequel we use the same notation ∇ to denote different connections on different bundles and use summation conventions, namely summing up repeated indices over the range of indices unless otherwise stated.

3 Some properties of the p -stress energy tensor

In this section, we calculate the divergence of \tilde{S}_f and obtain two important integral formulas, which are useful to study monotonicity inequalities and Liouville-type theorems for p -harmonic maps. First of all, we have

Theorem 1 *The p -stress energy tensor \tilde{S}_f of any smooth map $f : (M, g) \rightarrow (N, h)$ has divergence*

$$\operatorname{div}\tilde{S}_f = - \langle \tau_p(f), df \rangle, \tag{3.1}$$

where $\operatorname{div}\tilde{S}_f$ denotes the divergence of \tilde{S}_f .

Proof. Choose a local orthonormal frame field $\{e_i\}_{i=1}^m$ near an arbitrary point $x \in M$ with $\nabla_{e_i} e_j|_x = 0$. For any $X \in T_x M$ and at the point x

$$\begin{aligned}
 (\operatorname{div} \tilde{S}_f)(X) &= (\nabla_{e_i} \tilde{S}_f)(e_i, X) \\
 &= \nabla_{e_i}(\tilde{S}_f)(e_i, X) - \tilde{S}_f(e_i, \nabla_{e_i} X) \\
 &= \nabla_{e_i} \left[\frac{1}{p} |df|^p g(e_i, X) - |df|^{p-2} h(f_* e_i, f_* X) \right] \\
 &\quad - \left[\frac{1}{p} |df|^p g(e_i, \nabla_{e_i} X) - |df|^{p-2} h(f_* e_i, f_* \nabla_{e_i} X) \right] \\
 &= |df|^{p-2} h(\nabla_X f_* e_i, f_* e_i) - (\nabla_{e_i} |df|^{p-2}) h(f_* e_i, f_* X) \\
 &\quad - |df|^{p-2} h(\nabla_{e_i} f_* e_i, f_* X) + |df|^{p-2} h(f_* e_i, f_* \nabla_{e_i} X) \\
 &\quad - |df|^{p-2} h(f_* e_i, (\nabla_{e_i} df)(X) + f_* \nabla_{e_i} X) \\
 &= -h \left((\nabla_{e_i} |df|^{p-2}) f_* e_i + |df|^{p-2} \nabla_{e_i} f_* e_i, f_* X \right) \\
 &= -h \left(\nabla_{e_i} (|df|^{p-2} df)(e_i), f_* X \right) \\
 &= -h(\tau_p(f), df(X)).
 \end{aligned}$$

□

The following Corollary 3.2 and 3.3 follows immediately from Theorem 3.1.

Corollary 2 Any p -harmonic map satisfies the p -conservation law ,i.e., $\operatorname{div} \tilde{S}_f = 0$.

Corollary 3 Let $f : (M, g) \rightarrow (N, h)$ be a Riemannian submersion. Then f satisfies the p -conservation law if and only if f is p -harmonic map.

A smooth map $f : (M, g) \rightarrow (N, h)$ is called a *weakly conformal* if there exists a function λ on M such that $f^* h = \lambda^2 g$. In case of λ being constant, f is called a *homothetic map*.

Proposition 4 Suppose $f : (M, g) \rightarrow (N, h)$ is a smooth map with rank one at least. Then $\tilde{S}_f \equiv 0$ if and only if $\dim M = m = p$ and f is weakly conformal.

Proof. Assume that $\tilde{S}_f \equiv 0$. Then we have

$$\begin{aligned}
 \tilde{S}_f \equiv 0 &\Rightarrow \frac{1}{p} |df|^p g = |df|^{p-2} f^* h \\
 &\Rightarrow \frac{m}{p} |df|^p = |df|^p \\
 &\Rightarrow \frac{m-p}{p} |df|^p = 0.
 \end{aligned}$$

This means that $m = p$. Also we have from $\tilde{S}_f \equiv 0$

$$\frac{1}{p} |df|^2 g = f^* h,$$

which implies that f is weakly conformal by putting $\frac{1}{p} |df|^2 =: \lambda^2$. Conversely, assume that $f^* h = \lambda^2 g$ for some function λ on M . Then we obtain $\lambda^2 = \frac{|df|^2}{m}$. So, we get $f^* h = \frac{|df|^2}{m} g$. Substituting these into \tilde{S}_f , we have

$$\begin{aligned}
 \tilde{S}_f &= \frac{1}{p} |df|^p g - |df|^{p-2} f^* h \\
 &= \frac{1}{p} m^{\frac{p-2}{2}} \lambda^p (m-p) g.
 \end{aligned} \tag{3.2}$$

Therefore $\tilde{S}_f = 0$ if $m = p$.

□

Proposition 5 *If $\dim M = m > p$ and $f : (M, g) \rightarrow (N, h)$ is a weakly conformal map, then f is homothetic if and only if it satisfies the p -conservation law (i.e., $\operatorname{div} \tilde{S}_f \equiv 0$).*

Proof. Choose a local orthonormal frame field $\{e_i\}_{i=1}^m$ near an arbitrary point $x \in M$ with $\nabla_{e_i} e_j|_x = 0$. Under the assumption that f is weakly conformal, the equation (3.2) holds. If f is homothetic (i.e., λ is constant), then the divergence of \tilde{S}_f at x is given by

$$(\operatorname{div} \tilde{S}_f)(X) = \frac{1}{p} m^{\frac{p-2}{2}} \lambda^p (m-p) (\nabla_{e_i} g)(e_i, X) = 0$$

for any tangent vector $X \in T_x M$. That is, f satisfies the p -conservation law. Conversely, we also obtain from (3.2)

$$\begin{aligned} 0 &= (\operatorname{div} \tilde{S}_f)(X) = \frac{1}{p} m^{\frac{p-2}{2}} (m-p) g(e_i, X) \nabla_{e_i} \lambda^p \\ &= \frac{1}{p} m^{\frac{p-2}{2}} (m-p) \nabla_X \lambda^p, \end{aligned}$$

which gives $\nabla_X \lambda^p = 0$. Thus λ is constant. □

Proposition 6 *If the support of a vector field X on M ($=: \operatorname{supp}(X)$) is compact, then*

$$\int_M (\operatorname{div} \tilde{S}_f)(X) dv_g + \int_M \langle \tilde{S}_f, \nabla X \rangle dv_g = 0. \tag{3.3}$$

Furthermore, if D is a compact domain in M with its smooth boundary ∂D , then

$$\begin{aligned} \int_{\partial D} e_p(f) g(X, \mathbf{n}) dv_g &= \int_{\partial D} |df|^{p-2} h(f_* X, f_* \mathbf{n}) dv_g \\ &+ \int_D (\operatorname{div} \tilde{S}_f)(X) dv_g + \int_D \langle \tilde{S}_f, \nabla X \rangle dv_g, \end{aligned} \tag{3.4}$$

where \mathbf{n} is a unit vector field normal to the hypersurface ∂D of D , ∇X is a 2-tensor field defined by $\nabla X(Y, Z) := g(\nabla_Y X, Z)$ for any vector fields Y and Z on M and $\langle \cdot, \cdot \rangle$ denotes the inner product on 2-tensor fields.

Proof. Let X be any vector field on M . Then we have

$$\begin{aligned} \operatorname{div}(e_p(f)X) &= (\nabla_{e_i} e_p(f))g(X, e_i) + e_p(f)g(\nabla_{e_i} X, e_i) \\ &= \nabla_X e_p(f) + e_p(f) \langle \nabla X, g \rangle, \end{aligned} \tag{3.5}$$

where $\{e_i\}_{i=1}^m$ is a local orthonormal frame field near a point $x \in M$ with $\nabla_{e_i} e_j|_x = 0$. Note that at x

$$\begin{aligned} \nabla_X e_p(f) &= |df|^{p-2} h(\nabla_X f_* e_i, f_* e_i) \\ &= |df|^{p-2} h((\nabla_{e_i} df)(X), f_* e_i) \\ &= |df|^{p-2} [\nabla_{e_i} h(f_* X, f_* e_i) - h(f_* X, \nabla_{e_i} f_* e_i) \\ &\quad - g(\nabla_{e_i} X, e_j) h(f_* e_j, f_* e_i)] \\ &= |df|^{p-2} [\operatorname{div}(h(f_* X, f_* e_i)e_i) - h(f_* X, \tau(f)) \\ &\quad - \langle \nabla X, f^* h \rangle], \end{aligned} \tag{3.6}$$

where $\tau(f)$ denotes the tension field of f .

Substituting (3.6) into (3.5), we obtain

$$\begin{aligned}
 \operatorname{div}(e_p(f)X) &= |df|^{p-2} \operatorname{div}(h(f_*X, f_*e_i)e_i) - |df|^{p-2} h(f_*X, \tau(f)) \\
 &\quad + \langle \nabla X, \frac{1}{p}|df|^p g - |df|^{p-2} f^*h \rangle \\
 &= |df|^{p-2} \operatorname{div}(h(f_*X, f_*e_i)e_i) - |df|^{p-2} h(f_*X, \tau(f)) \\
 &\quad + \langle \nabla X, \tilde{S}_f \rangle \\
 &= |df|^{p-2} \operatorname{div}(h(f_*X, f_*e_i)e_i) - h(f_*X, \nabla_{e_i}(|df|^{p-2}df)(e_i)) \\
 &\quad + \nabla_{e_i}|df|^{p-2} h(f_*X, f_*e_i) + \langle \nabla X, \tilde{S}_f \rangle \\
 &= \operatorname{div}(|df|^{p-2} h(f_*X, f_*e_i)e_i) - h(f_*X, \tau_p(f)) \\
 &\quad + \langle \nabla X, \tilde{S}_f \rangle.
 \end{aligned} \tag{3.7}$$

If $\operatorname{supp}(X)$ is compact, integrating both sides of (3.7), then using Green’s theorem and Theorem 3.1 we have the integral formula (3.3).

For the proof of the second formula (3.4) we take a local orthonormal frame field $\{e_i\}_{i=1}^m$ of M along ∂D such that e_1, \dots, e_{m-1} are tangent to ∂D and $\mathbf{n} = e_m$ is normal to ∂D . By Green’s theorem

$$\int_D \operatorname{div}X \, dv_g = \int_{\partial D} g(X, \mathbf{n}) \, dv_g,$$

integrating (3.7) again over D gives the formula (3.4). □

4 A monotonicity inequality and Liouville-type theorem for p -harmonic maps

In this section, using the integral formulas (3.3) and (3.4), we shall prove a monotonicity inequality and Liouville-type theorem for p -harmonic maps. The proofs are based on those for harmonic maps due to Y.L.Xi([4,5]).

Theorem 7 *Let (M, g) be an m -dimensional Riemannian manifold, and $B_\sigma(x)$ its geodesic ball with radius σ and centered at $x \in M$. Suppose that the distance from a point $x_0 \in M$ to its cut locus and the boundary of M is at least one. If $f : (M, g) \rightarrow (N, h)$ is a p -harmonic map, then for any $x \in B_{\frac{1}{2}}(x_0)$ and $0 < \sigma \leq \rho \leq \frac{1}{2}$*

$$e^{C\Lambda\sigma} \sigma^{p-m} \int_{B_\sigma(x)} e_p(f) \, dv_g \leq e^{C\Lambda\rho} \rho^{p-m} \int_{B_\rho(x)} e_p(f) \, dv_g, \tag{4.1}$$

where C is a constant depending on m and Λ is a constant depending only on the bounds of the sectional curvature in $B_1(x_0)$.

Proof. Let r be the distance function in $B_{\frac{1}{2}}(x)$ from x , and $\frac{\partial}{\partial r}$ the unit radial vector field. Let

$$X = \xi(r)r \frac{\partial}{\partial r},$$

where $\xi(r)$ will be chosen later. Let us derive (4.1) by using (3.3).

Choose a local orthonormal frame field $\{e_\alpha, \frac{\partial}{\partial r}\} (\alpha = 1, \dots, m-1)$. Then

$$\nabla_{\frac{\partial}{\partial r}} X = (\xi' r + \xi) \frac{\partial}{\partial r},$$

and

$$\begin{aligned} \nabla_{e_\alpha} X &= \xi r \nabla_{e_\alpha} \frac{\partial}{\partial r} \\ &= \xi r \left[g \left(\nabla_{e_\alpha} \frac{\partial}{\partial r}, \frac{\partial}{\partial r} \right) \frac{\partial}{\partial r} + g \left(\nabla_{e_\alpha} \frac{\partial}{\partial r}, e_\beta \right) e_\beta \right] \\ &= \xi r \text{Hess}(r)(e_\alpha, e_\beta) e_\beta, \end{aligned}$$

where $\text{Hess}(\cdot)$ stands for the Hessian operator.

If the sectional curvature in $B_1(x_0)$ lies in $[a, b]$, then, by using Hessian comparison theorem, i.e.,

$$\sqrt{|b|} F(\sqrt{|b|r}) \leq \text{Hess}(r)(e_\alpha, e_\alpha) \leq \sqrt{|a|} F(\sqrt{|a|r}) \tag{4.2}$$

for each α , where

$$\sqrt{|c|r} F(\sqrt{|c|r}) = \begin{cases} \sqrt{cr} \cot(\sqrt{cr}), & c > 0, \\ 1, & c = 0, \\ \sqrt{-cr} \coth(\sqrt{-cr}), & c < 0, \end{cases}$$

and

$$\left| \sqrt{|c|r} F(\sqrt{|c|r}) - 1 \right| \leq r\Lambda, \tag{4.3}$$

we have

$$\begin{aligned} \text{div} X &= g \left(\nabla_{\frac{\partial}{\partial r}} X, \frac{\partial}{\partial r} \right) + g(\nabla_{e_\alpha} X, e_\alpha) \\ &\geq \xi' r + \xi + \xi(m-1) \sqrt{|b|r} F(\sqrt{|b|r}), \end{aligned} \tag{4.4}$$

and

$$\begin{aligned} \langle f^* h, \nabla X \rangle &= h(f_* e_\alpha, f_* e_\beta) g(\nabla_{e_\alpha} X, e_\beta) \\ &\quad + h \left(f_* \frac{\partial}{\partial r}, f_* \frac{\partial}{\partial r} \right) g \left(\nabla_{\frac{\partial}{\partial r}} X, \frac{\partial}{\partial r} \right) \\ &= \xi r \text{Hess}(r)(e_\alpha, e_\beta) h(f_* e_\alpha, f_* e_\beta) \\ &\quad + (\xi' r + \xi) h \left(f_* \frac{\partial}{\partial r}, f_* \frac{\partial}{\partial r} \right) \\ &\leq \xi r h(f_* e_\alpha, f_* e_\alpha) \sqrt{|a|r} F(\sqrt{|a|r}) \\ &\quad + (\xi' r + \xi) h \left(f_* \frac{\partial}{\partial r}, f_* \frac{\partial}{\partial r} \right) \\ &= \xi r |df|^2 \sqrt{|a|r} F(\sqrt{|a|r}) + \xi' r h \left(f_* \frac{\partial}{\partial r}, f_* \frac{\partial}{\partial r} \right) \\ &\quad + \xi \left\{ 1 - r \sqrt{|a|r} F(\sqrt{|a|r}) \right\} h \left(f_* \frac{\partial}{\partial r}, f_* \frac{\partial}{\partial r} \right). \end{aligned} \tag{4.5}$$

On the other hand, the formula (3.3) and the definition of \tilde{S}_f show that

$$\begin{aligned} 0 &= \int_M \langle \tilde{S}_f, \nabla X \rangle dv_g \\ &= \int_M \frac{1}{p} |df|^p \langle g, \nabla X \rangle dv_g \\ &\quad - \int_M |df|^{p-2} \langle f^* h, \nabla X \rangle dv_g. \end{aligned} \tag{4.6}$$

The first equality follows from the assumption that f is p -harmonic.

Substituting (4.4) and (4.5) into (4.6) yields

$$\begin{aligned} 0 \geq & \int_M \left[|df|^{p\xi' r} - (p-m) |df|^{p\xi} + |df|^{p\xi} (m-1) \{ \sqrt{|b|r} F(\sqrt{|b|r}) - 1 \} \right. \\ & \left. + p\xi \{ 1 - \sqrt{|a|r} F(\sqrt{|a|r}) \} |df|^p - p\xi' r \left| f_* \frac{\partial}{\partial r} \right|^2 |df|^{p-2} \right. \\ & \left. - p\xi \{ 1 - \sqrt{|a|r} F(\sqrt{|a|r}) \} \left| f_* \frac{\partial}{\partial r} \right|^2 |df|^{p-2} \right] dv_g. \end{aligned}$$

Noting (4.3), we have

$$\begin{aligned}
 & - \int_M |df|^p \xi' r dv_g + (p - m) \int_M |df|^p \xi dv_g \\
 & + (m + p - 1) \Lambda \int_M |df|^p r \xi dv_g \geq - \int_M p \xi' r \left| f_* \frac{\partial}{\partial r} \right|^2 |df|^{p-2} dv_g \\
 & - \int_M p \xi \{1 - \sqrt{|a|} r F(\sqrt{|a|} r)\} \left| f_* \frac{\partial}{\partial r} \right|^2 |df|^{p-2} dv_g.
 \end{aligned} \tag{4.7}$$

Choose a smooth function

$$\phi(t) = \begin{cases} 1, & \text{for } t \in [0, 1], \\ 0, & \text{for } t \in [1 + \varepsilon, \infty), \end{cases}$$

and $\phi' \leq 0$, where $\varepsilon > 0$ is a sufficiently small number. For $r \in [\sigma, \rho]$ set

$$\xi(r) = \xi_\tau(r) = \phi\left(\frac{r}{\tau}\right).$$

Then

$$\tau \frac{\partial}{\partial \tau} (\xi_\tau(r)) = -r \xi'_\tau(r), \quad \xi'_\tau = \phi'\left(\frac{r}{\tau}\right) \frac{1}{\tau}$$

and

$$\xi_\tau r = \phi\left(\frac{r}{\tau}\right) r \leq \phi\left(\frac{r}{\tau}\right) \tau(1 + \varepsilon) = \xi_\tau(1 + \varepsilon)\tau.$$

Substituting these formulas into (4.7) gives

$$\tau \frac{\partial}{\partial \tau} \int_M \xi_\tau |df|^p dv_g + (p - m) \int_M \xi_\tau |df|^p dv_g + C\tau \Lambda \int_M \xi_\tau |df|^p dv_g \geq 0,$$

where $C = (1 + \varepsilon)(m + p - 1)$, which means that

$$\frac{\partial}{\partial \tau} \left(e^{C\Lambda\tau} \tau^{p-m} \int_M \xi_\tau |df|^p dv_g \right) \geq 0.$$

Thus we complete the proof. □

Theorem 8 *Let M be a Cartan-Hadamard manifold (i.e., complete simply-connected Riemannian manifold of nonpositive sectional curvature) whose sectional curvature varies in a small range (the precise range will be seen in the proof), and f a p -harmonic map from M into any Riemannian manifold N with finite p -energy. If $\dim M = m > p$, then f has to be constant.*

Proof. Let $D = B_R(x_0)$ be a geodesic ball of radius R and centered at x_0 . Its boundary $\partial B_R(x_0)$ is the geodesic sphere. Obviously, the square of the distance function from x_0 in $B_R(x_0)$ is smooth. Let $\frac{\partial}{\partial r}$ denote the unit radial vector field which is also the unit normal vector field \mathbf{n} to $\partial B_R(x_0)$. Choosing $X = r \frac{\partial}{\partial r}$ in the formula (3.4), we have

$$\begin{aligned}
 & \int_{\partial B_R(x_0)} e_p(f) g(X, \mathbf{n}) dv_g - \int_{\partial B_R(x_0)} |df|^{p-2} h(f_* X, f_* \mathbf{n}) dv_g \\
 & = \int_{\partial B_R(x_0)} R e_p(f) dv_g - \int_{\partial B_R(x_0)} R |df|^{p-2} h\left(f_* \frac{\partial}{\partial r}, f_* \frac{\partial}{\partial r}\right) dv_g \\
 & \leq \int_{\partial B_R(x_0)} R e_p(f) dv_g.
 \end{aligned} \tag{4.8}$$

On the other hand,

$$\begin{aligned} \nabla_{\frac{\partial}{\partial r}} X &= \frac{\partial}{\partial r}, \\ \nabla_{e_\alpha} X &= r \nabla_{e_\alpha} \frac{\partial}{\partial r} \\ &= r \text{Hess}(r)(e_\alpha, e_\beta) e_\beta, \\ \text{div} X &= 1 + r \text{Hess}(r)(e_\alpha, e_\alpha), \end{aligned}$$

where $\{e_\alpha, \frac{\partial}{\partial r}\}_{\alpha=1}^{m-1}$ is a local orthonormal frame field on $B_R(x_0)$. Thus,

$$\begin{aligned} &h(f_* e_s, f_* e_t) g(\nabla_{e_s} X, e_t) \\ &= r \text{Hess}(r)(e_\alpha, e_\beta) h(f_* e_\alpha, f_* e_\beta) + h\left(f_* \frac{\partial}{\partial r}, f_* \frac{\partial}{\partial r}\right), \end{aligned}$$

and

$$\begin{aligned} \langle \tilde{S}_f, \nabla X \rangle &= \langle e_p(f)g - |df|^{p-2} f^* h, \nabla X \rangle \\ &= e_p(f) \langle g, \nabla X \rangle - |df|^{p-2} \langle f^* h, \nabla X \rangle \\ &= e_p(f) \text{div} X - |df|^{p-2} h(f_* e_s, f_* e_t) g(\nabla_{e_s} X, e_t) \\ &= e_p(f) [1 + \text{Hess}(r)(e_\alpha, e_\alpha)] \\ &\quad - |df|^{p-2} \left[r \text{Hess}(r)(e_\alpha, e_\beta) h(f_* e_\alpha, f_* e_\beta) + \left| f_* \frac{\partial}{\partial r} \right|^2 \right], \end{aligned} \tag{4.9}$$

where $s, t \in \{1, \dots, m\}$ and $e_m = \frac{\partial}{\partial r}$.

We consider cases when the sectional curvature K of the domain manifold satisfies one of the following conditions;

- (1) $-a^2 \leq K \leq -b^2 < 0$, a, b are positive constant,
- (2) $-\frac{A}{1+r^2} \leq K \leq 0$, A is another constant.

Case (1). By using Hessian comparison theorem (4.2), (4.9) becomes

$$\begin{aligned} \langle \tilde{S}_f, \nabla X \rangle &\geq \frac{1}{p} |df|^p \left[1 + (m-1)(br) \coth(br) \right] \\ &\quad - |df|^{p-2} \left[\left| f_* \frac{\partial}{\partial r} \right|^2 + (ar) \coth(ar) h(f_* e_\alpha, f_* e_\alpha) \right] \\ &= \frac{1}{p} |df|^{p-2} \left[|df|^2 \{ 1 + (m-1)(br) \coth(br) \} - p \left| f_* \frac{\partial}{\partial r} \right|^2 \right. \\ &\quad \left. - p(ar) \coth(ar) h(f_* e_\alpha, f_* e_\alpha) \right] \\ &= \frac{1}{p} |df|^{p-2} \left[-p(ar) \coth(ar) h(f_* e_\alpha, f_* e_\alpha) - p \left| f_* \frac{\partial}{\partial r} \right|^2 \right. \\ &\quad \left. + \{ h(f_* e_\alpha, f_* e_\alpha) + \left| f_* \frac{\partial}{\partial r} \right|^2 \} \{ 1 + (m-1)(br) \coth(br) \} \right] \\ &= \frac{1}{p} |df|^{p-2} \left[\{ 1 + (m-1)(br) \coth(br) \} \right. \\ &\quad \left. - p(ar) \coth(ar) \} h(f_* e_\alpha, f_* e_\alpha) \right. \\ &\quad \left. + \{ 1 + (m-1)(br) \coth(br) - p \} \left| f_* \frac{\partial}{\partial r} \right|^2 \right] \\ &\geq \frac{1}{p} |df|^{p-2} \left[\{ 1 + r \coth(br) (b(m-1) - pa) \} h(f_* e_\alpha, f_* e_\alpha) \right. \\ &\quad \left. + (m-p) \left| f_* \frac{\partial}{\partial r} \right|^2 \right] \\ &\geq \frac{\delta}{p} |df|^p \end{aligned} \tag{4.11}$$

where $\delta > 0$, provided $b(m - 1) - pa \geq 0$. Thus we have

$$\delta \int_{B_R(x_0)} e_p(f) dv_g \leq \int_{B_R(x_0)} \langle \nabla X, \tilde{S}_f \rangle dv_g.$$

Therefore combining this with (3.4) and (4.8) gives

$$R \int_{\partial B_R(x_0)} e_p(f) dv_g \geq \delta \int_{B_R(x_0)} e_p(f) dv_g.$$

If the p -energy density $e_p(f)$ does not vanish identically, then there exists $R_0 > 0$ such that for $R > R_0$,

$$\int_{B_R(x_0)} e_p(f) dv_g \geq C,$$

where C is a positive constant. Hence

$$\int_{\partial B_R(x_0)} e_p(f) dv_g \geq \frac{\delta C}{R}.$$

This implies that

$$\begin{aligned} \int_M e_p(f) dv_g &= \int_0^\infty dr \int_{\partial B_r(x_0)} e_p(f) dv_g \\ &\geq \int_{R_0}^\infty dr \int_{\partial B_r(x_0)} e_p(f) dv_g \\ &\geq \int_{R_0}^\infty \frac{\delta C}{r} dr \rightarrow \infty, \end{aligned}$$

which contradicts the finiteness of the p -energy. Therefore f has to be constant.

Case(2). If the sectional curvature K satisfies $K \geq -\frac{A}{1+r^2}$, then, by Hessian comparison theorem (see [2]), i.e.,

$$\frac{1}{r}(g - dr \otimes dr) \leq Hess(r) \leq \frac{\beta}{r}(g - dr \otimes dr),$$

where $\beta = \frac{1}{2} + \frac{1}{2}(1 + 4A)^{\frac{1}{2}}$, we get

$$\begin{aligned} \langle \tilde{S}_f, \nabla X \rangle &\geq \frac{m}{p} |df|^p - |df|^{p-2} \left| f_* \frac{\partial}{\partial r} \right|^2 - \beta |df|^{p-2} h(f_* e_\alpha, f_* e_\alpha) \\ &= \frac{1}{p} |df|^{p-2} \left[m |df|^2 - p \left| f_* \frac{\partial}{\partial r} \right|^2 - p\beta h(f_* e_\alpha, f_* e_\alpha) \right] \\ &= \frac{1}{p} |df|^{p-2} \left[(m - p) \left| f_* \frac{\partial}{\partial r} \right|^2 + (m - p\beta) h(f_* e_\alpha, f_* e_\alpha) \right] \\ &\geq \delta e_p(f) \end{aligned}$$

for some constant $\delta > 0$. Hence, for the proof of the rest part, we can argue as that of Case (1).

Therefore we complete the proof. □

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