THE SUBMANIFOLDS X_m OF THE MANIFOLD $*g - MEX_n$ II. FUNDAMENTAL EQUATIONS ON X_m OF $*g - MEX_n$

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Abstract. In our previous paper [4], we studied the induced connection of the *g-ME-connection on a submanifold X_m embedded in a manifold *g-MEX_n together with the generalized coefficients Ω_{ij} of the second fundamental form of X_m , with emphasis on the proof of a necessary and sufficient condition for the induced connection of X_m in *g-MEX_n to be a *g-ME-connection. This paper is a direct continuation of [4]. In this paper, we derive the generalized fundamental equations on X_m of *g-MEX_n, such as the generalized Gauss formulae, the generalized Weingarten equations, and the Gauss-Codazzi equations. Furthermore, we also present surveyable tensorial representations of curvature tensors $R^{\mu}_{\omega\mu\lambda}$ of *g-MEX_n and R^{h}_{ijk} of X_m .

1 The generalized fundamental equations on a submanifold X_m of *g-MEX_n

This section is a direct continuation of our previous paper [4], which will be denoted by I in the present section. All considerations in this section are based on the results and symbolism of I. Whenever necessary, they will be quoted in the present section.

In this section, we derive the generalized fundamental equations on a submanifold X_m of ${}^*g\text{-MEX}_n$, such as the generalized Gauss formulae, the generalized Weingarten equations, and the Gauss-Codazzi equations. Furthermore, in Theorem 8 we also present surveyable tensorial representations of curvature tensors $R^{\text{v}}_{\omega\mu\lambda}$ of ${}^*g-MEX_n$ and R^h_{ijk} of X_m . The convenient and powerful C-nonholonomic frame of reference in ${}^*g-MEX_n$ at points of X_m , introduced in I-Section 1(b), will be employed throughout the present section. Particularly, we note in virtue of Definition I-11 that under the present conditions the ${}^*g-ME$ -connection of a given ${}^*g-MEX_n$ is unique.

Theorem 1 (The generalized Gauss formulae on X_m of *g-MEX_n) At points of X_m of *g-MEX_n, the following relation holds:

$$D_{j}^{\circ} B_{i}^{\mathsf{v}} = \sum_{x} (-\Lambda_{ij}^{x} + 2\varepsilon_{x} X_{x}^{*} g_{ij}) N_{x}^{\mathsf{v}}$$
 1.1

Proof. This relation is a consequence of I-(3.4) and I-(3.8).

In the derivation of the generalized Weingarten equations, a representation of the vector $D_i^{\circ} N_x^{\alpha}$, it is convenient to introduce the following abbreviations:

$$M_{jx}^{\mathsf{v}} = D_{j}^{\mathsf{o}} N_{x}^{\mathsf{v}} \tag{1.2}$$

$$H_{\gamma}^{xy} = \varepsilon_{y} (\nabla_{\gamma} N_{x}^{\alpha}) N_{\alpha}^{y}$$
 1.3

Theorem 2 The vector H_{γ}^{xy} is skew-symmetric with respect to x and y. That is

$$H_{\gamma}^{xy} = -H_{\gamma}^{yx}, \quad H_{\gamma}^{xx} = 0 \tag{1.4}$$

Proof. The second relation of (1.4) is a consequence of the first. In virtue of I-(2.16a) and I-(2.24), the first relation of (1.4) follows as in the following way:

$$0 = \nabla_{\gamma} (h_{\alpha\beta} N_x^{\alpha} N_y^{\beta})$$

$$= \nabla_{\gamma} (N_x^{\alpha}) N_{\alpha}^{y} + \nabla_{\gamma} (N_y^{\beta}) N_{\beta}^{x}$$

$$= H_{\gamma}^{xy} + H_{\gamma}^{yx}$$

In a sequence of the following four theorems, we derive the generalized Weingarten equations on X_m of *g -MEX_n.

Theorem 3 The vector M_{jx}^{v} may be decomposed as

$$M_{jx}^{V} = M_{jx}^{i} B_{i}^{V} + \sum_{y} M_{jx}^{y} N_{y}^{V}$$
1.5

the first vector on the right being tangential to X_m and the second vector normal to X_m . Here

$$M^{i}_{jx} = M^{\alpha}_{jx} B^{i}_{\alpha}, \quad M^{y}_{jx} = M^{\alpha}_{jx} N^{y}_{\alpha}$$
 1.6

Proof. This Theorem is an immediate consequence of I-Theorem 6.

Theorem 4 At points of X_m of $*g-MEX_n$, the induced vector M^i_{jx} of M^v_{jx} may be given by

$$M_{ix}^{i} = \varepsilon_{x} * h^{ih} \Lambda_{hi}^{x} - 2X^{i} * k_{xi}$$

$$1.7a$$

or equivalently

$$M_{ix}^{i} = \varepsilon_{x} * h^{ih} \Omega_{hi}^{x} + 2[X_{x}(\delta_{i}^{i} - k_{j}^{i}) - X^{i} * k_{xj}]$$
1.7b

Proof. In order to prove the relation (1.7a), we first note that M_{jx}^i is the induced tensor of $D_{\gamma}N_{x}^{\alpha}$ in virtue of (1.2) and (1.6). That is,

$$M^i_{jx} = (D_{\gamma} N^{\alpha}_x) B^i_{\alpha} B^{\gamma}_j$$
 1.8

Making use of I-(2.25), I-(2.24a), and I-(3.9), we also note that

$$(\nabla_{\gamma} N_{x}^{\alpha}) B_{\alpha}^{i} B_{j}^{\gamma} = (\nabla_{\gamma} N_{x}^{\beta *} h_{\beta \epsilon}) (*h^{\epsilon \alpha} B_{\alpha}^{i}) B_{j}^{\gamma} = \varepsilon_{x} *h^{ih} \Lambda_{hj}^{x}$$

$$(1.9)$$

Consequently, making use of I-(3.1), I-(2.20a), I-(2.23), and (1.9), the relation (1.7a) follows from (1.8) as in the following way:

$$M_{jx}^{i} = \left[\partial_{\gamma}N_{x}^{\alpha} + (*\{^{\alpha}_{\beta\gamma}\} + 2\delta^{\alpha}_{\beta}X_{\gamma} - 2*g_{\beta\gamma}X^{\alpha})N_{x}^{\beta}\right]B_{\alpha}^{i}B_{j}^{\gamma}$$

$$= (\nabla_{\gamma}N_{x}^{\alpha})B_{\alpha}^{i}B_{j}^{\gamma} - 2(X^{\alpha}B_{\alpha}^{i})(*k_{\beta\gamma}N_{x}^{\beta}B_{j}^{\gamma})$$

$$= \varepsilon_{x}*h^{ih}\Lambda_{hj}^{x} - 2X^{i}*k_{xj}$$

Substitution of I-(3.8) into (1.7a) gives (1.7b).

Theorem 5 At points of X_m of $*g\text{-}MEX_n$, the C-nonholonomic components M_{jx}^y of M_{jx}^y may be given by

$$M_{jx}^{y} = \varepsilon_{y} H_{\gamma}^{xy} B_{j}^{\gamma} + 2(\delta_{x}^{y} X_{j} + \varepsilon_{x}^{*} k_{j}^{x} X^{y})$$

$$1.10$$

Proof. In virtue of (1.2) and (1.6), we first note that M_{jx}^y is the induced vector of $(D_\gamma N_x^\alpha)N_\alpha^y$. Hence, making use of I-(2.33), I-(2.23), I-(2.20a), and (1.3), the representation (1.10) follows as in the following way:

$$\begin{split} M_{jx}^{y} &= ((D_{\gamma}N_{x}^{\alpha})N_{\alpha}^{y}B_{j}^{\gamma} \\ &= \left[\partial_{\gamma}N_{x}^{\alpha} + (*\{_{\beta\gamma}^{\alpha}\} + 2\delta_{\beta}^{\alpha}X_{\gamma} - 2*g_{\beta\gamma}X^{\alpha})N_{x}^{\beta}\right]N_{\alpha}^{x}B_{j}^{\gamma} \\ &= (\nabla_{\gamma}N_{x}^{\alpha})N_{\alpha}^{y}B_{j}^{\gamma} + 2(N_{x}^{\alpha}N_{\alpha}^{y})(X_{\gamma}B_{j}^{\gamma}) + 2\varepsilon_{x}(*k_{\gamma}^{\beta}N_{\beta}^{x}B_{j}^{\gamma})(X^{\alpha}N_{\alpha}^{y}) \\ &= \varepsilon_{y}H_{\gamma}^{xy}B_{j}^{\gamma} + 2(\delta_{x}^{y}X_{j} + \varepsilon_{x}*k_{x}^{j}X_{j}^{y}) \end{split}$$

Now, we are ready to present the following representation of the generalized Weingarten equations by simply substituting (1.7a, b) and (1.10) into (1.5). We formally state

Theorem 6 (The generalized Weingarten equations on X_m of $*g\text{-MEX}_n$) At points of X_m of $*g\text{-MEX}_n$, the following equations hold:

$$D_{j}^{\circ}N_{x}^{\vee} = (\varepsilon_{x} * h^{ih} \Lambda_{hj}^{x} - 2X^{i} * k_{xj})B_{i}^{\vee} + + \sum_{x} \left[\varepsilon_{y} H_{\gamma}^{xy} B_{j}^{\gamma} + 2(\delta_{x}^{y} X_{j} + \varepsilon_{x} * k_{j}^{x} X^{y}) \right] N_{y}^{\vee}$$
1.11*a*

or equivalently

$$D_{j}^{\circ}N_{x}^{\vee} = \left[\varepsilon_{x} * h^{ih} \Omega_{hj}^{x} + 2(X_{x}(\delta_{j}^{i} - *k_{j}^{i}) - X^{i} * k_{xj}) \right] B_{i}^{\vee} + \sum_{y} \left[\varepsilon_{y} H_{\gamma}^{xy} B_{j}^{\gamma} + 2(\delta_{x}^{y} X_{j} + \varepsilon_{x} * k_{j}^{x} X^{y}) \right] N_{y}^{\vee}$$
1.11b

Our next considerations concern the derivation of the generalized Gauss-Codazzi equations for X_m of *g-MEX_n. For this purpose, we need the following curvature tensors:

$$R_{\omega\mu\lambda}{}^{\nu} = 2(\partial_{[\mu} \Gamma_{|\lambda|}{}^{\nu}{}_{\omega]} + \Gamma_{\alpha}{}^{\nu}{}_{[\mu} \Gamma_{|\lambda|}{}^{\alpha}{}_{\omega]})$$

$$1.12$$

$$\bar{R}_{ijk}^{\ h} = 2(\partial_{[i} \Gamma_{|k|}^{\ h}_{\ i]} + \Gamma_{p}^{\ h}_{\ [i} \Gamma_{|k|}^{\ p}_{\ i]})$$
 1.13

$$H_{\omega\mu\lambda}^{\ \nu} = 2(\partial_{[\mu}^{\ *} \{ \begin{matrix} \nu \\ \omega] \lambda \end{Bmatrix} + {}^{*} \{ \begin{matrix} \nu \\ \alpha [\mu \end{Bmatrix} \} {}^{*} \{ \begin{matrix} \alpha \\ \omega] \lambda \end{Bmatrix})$$

$$1.14$$

$$\bar{H}_{ijk}^{h} = 2(\partial_{[j} * \{ \frac{h}{i]k} \} + * \{ \frac{h}{p[j} \} * \{ \frac{p}{i]k} \})$$
1.15

where $\Gamma^{\rm V}_{\lambda\mu}$ is the *g-ME-connection of *g-MEX_n and Γ^k_{ij} is the induced connection on X_m of *g-MEX_n. The tensors $R_{\omega\mu\lambda}{}^{\rm V}$ and $\bar{R}_{ijk}{}^h$ are called *g-curvature tensors of *g-MEX_n and X_m , respectively. It should be noted that $\bar{R}_{ijk}{}^h$ and $\bar{H}_{ijk}{}^h$ are not the induced tensors of $R^{\rm V}_{\omega\mu\lambda}$ and $H^n_{\omega\mu\lambda}u$, respectively.

The following Theorem gives precise tensorial representations of *g-curvature tensors.

Theorem 7 The *g-curvature tensors $R_{\omega\mu\lambda}^{\ \nu}$ and $\bar{R}_{ijk}^{\ h}$ may be given by

$$R_{\omega\mu\lambda}^{\nu} = H_{\omega\mu\lambda}^{\nu} + 4(\delta^{\nu}_{[\omega} \partial_{\mu]} X_{\lambda} - X^{\nu} \nabla_{[\omega}^{*} k_{\mu]\lambda} -$$

$$- *g_{\lambda[\omega} \nabla_{\mu]} X^{\nu} + 2 *g_{\lambda[\omega}^{*} g_{|\alpha|\mu]} X^{\alpha} X^{\nu})$$

$$1.16$$

$$\bar{R}_{ijk}^{h} = \bar{H}_{ijk}^{h} + 4(\delta_{[i}^{h} \partial_{j]} X_{k} - X^{h} \nabla_{[i}^{*} k_{j]k} - \\
- *g_{k[i} \nabla_{j]} X^{h} + 2 *g_{k[i} *g_{|p|j]} X^{p} X^{h})$$
1.17

Proof. In virtue of I-(2.33), (1.12), and (1.14), the representation (1.16) may be proved as in the following way:

$$\begin{split} R_{\omega\mu\lambda}{}^{\mathrm{V}} &= 2\partial_{[\mu}(^{*}\{^{\mathrm{V}}_{\omega]\lambda}\} + 2\delta^{\mathrm{V}}_{\omega]}X_{\lambda} - 2^{*}g_{|\lambda|\omega]}X^{\mathrm{V}}) + \\ &+ 2(^{*}\{^{\mathrm{V}}_{\alpha[\mu}\} + 2\delta^{\mathrm{V}}_{\alpha}X_{[\mu} - 2X^{\mathrm{V}} * g_{\alpha[\mu}) \times \\ &\times (^{*}\{^{\mathrm{C}}_{\omega]\lambda}\} + 2X_{\omega]}\delta^{\alpha}_{\lambda} - 2^{*}g_{\omega]\lambda}X^{\alpha}) \\ &= H_{\omega\mu\lambda}{}^{\mathrm{V}} + 4\delta^{\mathrm{V}}_{[\omega}\partial_{\mu]}X_{\lambda} - 4X^{\mathrm{V}}(\partial_{[\mu}{}^{*}g_{|\lambda|\omega]} + {}^{*}g_{\alpha[\mu}{}^{*}\{^{\mathrm{C}}_{\omega]\lambda}\}) - \\ &- 4^{*}g_{\lambda[\omega}(\partial_{\mu]}X^{\mathrm{V}} + {}^{*}\{^{\mathrm{V}}_{\mu]\alpha}\}X^{\alpha}) + 8^{*}g_{\lambda[\omega}{}^{*}g_{|\alpha|\mu]}X^{\alpha}X^{\mathrm{V}} \\ &= H_{\omega\mu\lambda}{}^{\mathrm{V}} + 4(\delta^{\mathrm{V}}_{[\omega}\partial_{\mu]}X_{\lambda} - X^{\mathrm{V}}\nabla_{[\mu}{}^{*}g_{|\lambda|\omega]} - \\ &- {}^{*}g_{\lambda[\omega}\nabla_{\mu]}X^{\mathrm{V}} + 2^{*}g_{\lambda[\omega}{}^{*}g_{|\alpha|\mu]}X^{\alpha}X^{\mathrm{V}}) \end{split}$$

Similarly, the representation (1.17) may be obtained from (1.13) in virtue of I-(3.11) and (1.15).

Now, we are ready to display the Gauss-Codazzi equations for X_m of *g-MEX_n.

Theorem 8 At points of ${}^*g\text{-}MEX_n$, the ${}^*g\text{-}curvature tensors }R_{\omega\mu\lambda}{}^{\mathrm{V}}$ of ${}^*g\text{-}MEX_n$ and $\bar{R}_{ijk}{}^h$ of X_m are involved in the following equations:

(The generalized Gauss equations on X_m of *g-MEX_n)

$$\bar{R}_{ijk}^{h} = R_{\beta\gamma\epsilon}^{\alpha} B_{i}^{\alpha} B_{j}^{\gamma} B_{k}^{\epsilon} B_{\alpha}^{h} + 2\sum_{x} \Omega_{k[i}^{x} [\Omega_{|p|j]}^{x} h^{hp} \varepsilon_{x} + 2(\delta_{j]}^{h} - k_{j]}^{h} X_{x} + 2 k_{j]x} X^{h}]$$
1.18

(The generalized Codazzi equations on X_m of $*g\text{-MEX}_n$)

$$2\nabla_{[k}\Omega^{x}_{|i|j]} = R_{\beta\gamma\epsilon}{}^{\alpha} B^{\beta}_{k} B^{\gamma}_{j} B^{\epsilon}_{i} N^{x}_{\alpha} + 2\sum_{y} \Omega^{y}_{i[k} (B^{\gamma}_{j]} H^{yx}_{\gamma\epsilon_{x}} + 2^{*}k_{j]y} X^{x}) + 4X^{h} *g_{i[j} \Omega^{x}_{|h|k]}$$

Proof. We first note that I-(3.11) gives

$$S_{jk}^{h} = 2\delta_{[j}^{h} X_{k]} - 2^{*} k_{jk} X^{h}$$
1.20

In virtue of I-(3.6), I-(3.4), (1.12), (1.13) and (1.20), it follows that

$$2D_{[k}^{\circ}(D_{j]}^{\circ}B_{i}^{\alpha}) = 2\partial_{[k}(D_{j]}^{\circ}B_{i}^{\alpha}) + 2\Gamma_{\beta\gamma}^{\alpha}B_{[k}^{\gamma}(D_{j]}^{\circ}B_{i}^{\beta}) - \\
-2\Gamma_{i[k}^{p}(D_{j]}^{\circ}B_{p}^{\alpha}) - 2\Gamma_{[jk]}^{h}(D_{h}^{\circ}B_{i}^{\alpha}) = \\
= 2\partial_{[k}(B_{j]i}^{\alpha} + B_{j]}^{\gamma}B_{i}^{\beta}\Gamma_{\beta\gamma}^{\alpha} - \Gamma_{[i|j]}^{h}B_{h}^{\alpha}) + \\
+2\Gamma_{\beta\gamma}^{\alpha}B_{[k}^{\gamma}(B_{j]i}^{\beta} + B_{j]}^{\phi}B_{i}^{\theta}\Gamma_{\theta\phi}^{\beta} - \Gamma_{[i|j]}^{h}B_{h}^{\beta}) - \\
-2\Gamma_{i[k}^{p}(B_{j]p}^{\alpha} + B_{j]}^{\gamma}B_{p}^{\beta}\Gamma_{\beta\gamma}^{\alpha} - \Gamma_{[p|j]}^{h}B_{h}^{\alpha}) + \\
+4(\delta_{[j}^{h}X_{k]} - *k_{jk}X^{h})\sum_{x}\Omega_{ih}^{x}N_{x}^{\alpha} = \\
-R_{\epsilon\gamma\beta}^{\alpha}B_{i}^{\beta}B_{j}^{\gamma}B_{k}^{\epsilon} + \bar{R}_{kji}^{h}B_{h}^{\alpha} + \\
+4\sum_{x}(\Omega_{i[j}^{x}X_{k]} - *k_{jk}\Omega_{ih}^{x}X^{h})N_{x}^{\alpha}$$
1.21

On the other hand, the relation I-(3.4) gives

$$2D_{[k}^{\circ}(D_{j]}^{\circ}B_{i}^{\alpha}) = -2\sum_{x}D_{[k}^{\circ}(\Omega_{|i|j]}^{x}N_{x}^{\alpha})$$

$$= 2\sum_{x}(D_{[j}^{\circ}\Omega_{|i|k]}^{x})N_{x}^{\alpha} + 2\sum_{x}\Omega_{i[k}^{x}(D_{j]}^{\circ}N_{x}^{\alpha})$$
1.22

In virtue of I-(2.33), the first term in the right-hand side of (1.22) may be written as

First term
$$= 2\sum_{x} (\partial_{[j}\Omega^{x}_{|i|k]} - \Gamma^{h}_{i[j}\Omega^{x}_{|h|k]} - \Gamma^{h}_{[kj]}\Omega^{x}_{ih})N^{\alpha}_{x}$$

$$= 2\sum_{x} (\nabla_{[j}\Omega^{x}_{|i|k]} + 4\Omega^{x}_{i[j}X_{k]} + 2X^{h} * g_{i[j}\Omega^{x}_{|h|k]} -$$

$$-2X^{h} * k_{jk}\Omega^{x}_{ih})N^{\alpha}_{x}$$

$$1.23a$$

Making use of the relations (1.11b) and

$$\varepsilon_x^* k_j^x = {}^*k_{jx}^1$$

the second term in the right-hand side of (1.22) is equal to

Second term
$$= 2\sum_{x} \Omega_{i[k}^{x} [\Omega_{|h|j]}^{x} * h^{ph} \varepsilon_{x} + 2(\delta_{j]}^{p} - *k_{j]}^{p}) X_{x} + \\ + 2*k_{j]x} X^{p} B_{p}^{\alpha} + 4\sum_{x} \Omega_{i[k} X_{j]} N_{x}^{\alpha} + \\ + 2\sum_{x,y} \Omega_{i[k} (B_{j]}^{\gamma} H_{\gamma \varepsilon_{y}}^{xy} + 2*k_{j]x} X^{y}) N_{y}^{\alpha}$$
 1.23b

Substitution of (1.23) into (1.22) gives

$$2D_{[k}^{\circ}D_{j]}^{\circ}B_{i}^{\alpha} = 2\sum_{x}\Omega_{i[k}^{x}(\Omega_{|h|j]}^{x} *h^{ph}\varepsilon_{x} + 2(\delta_{j]}^{p} - *k_{j]}^{p})X_{x} + \\ + 2*k_{j]x}X^{p})B_{p}^{\alpha} + 2\sum_{x}(\nabla_{[j}\Omega_{|i|k]}^{x} + \\ + 2X^{h}*g_{i[j}\Omega_{|h|k]}^{x} + 2\Omega_{i[j}^{x}X_{k]} - 2X^{h}*k_{jk}\Omega_{ih}^{x})N_{x}^{\alpha} + \\ + 2\sum_{x,y}\Omega_{i[k}(B_{j]}^{\gamma}H_{\gamma\varepsilon_{y}}^{xy} + 2*k_{j]x}X^{y})N_{y}^{\alpha}$$

$$1.24$$

$$\varepsilon_x^* k_j^x = \varepsilon_x^* k_\alpha^\beta B_j^\alpha N_\beta^x = {}^*k_{\alpha\beta} B_j^\alpha (\varepsilon_x N_\beta^x) = {}^*k_{\alpha\beta} B_j^\alpha N_x^\beta = {}^*k_{jx}$$

¹The relation I-(2.24b) show that

Consequently, comparing (1.21) and (1.24), we finally have

$$\bar{R}_{kji}{}^{h}B_{h}^{\alpha} = R_{\beta\gamma\epsilon}{}^{\alpha}B_{i}^{\beta}B_{j}^{\gamma}B_{k}^{\epsilon} + 2\sum_{x}\Omega_{i[k}^{x}[\Omega_{|h|j]}^{x} *h^{ph}\epsilon_{x} + 2(\delta_{j]}^{p} - *k_{j]}^{p})X_{x} + 2*k_{j]x}X^{p}]B_{p}^{\alpha} + 2\sum_{x}(\nabla_{[j}\Omega_{[i|k]}^{x} + 2X^{h} *g_{i[j}\Omega_{[h|k]}^{x})N_{x}^{\alpha} + 2\sum_{x,y}\Omega_{i[k}^{x}(B_{j]}^{\gamma}H_{\gamma\epsilon_{y}}^{xy} + 2*k_{j]x}X^{y})N_{y}^{\alpha} \tag{1.25}$$

The generalized Gauss equations (1.18) follow by multiplying B_{α}^{q} to both sides of (1.25) and rearranging the indices suitably. Similarly, the generalized Codazzi equations (1.19) may be obtained by multiplying N_{α}^{z} to both sides of (1.25) and rearranging the indices. In the derivation of both equations, use of the relations I-(2.23) has been made.

2 The generalized fundamental equations on a hypersubmanifold X_{n-1} of *g-MEX_n

In this section, we investigate the fundamental equations on a hypersubmanifold of *g -MEX_n. On a hypersubmanifold X_{n-1} of *g -MEX_n, the theory of submanifolds assumes a particularly simple and geometrically illuminating form. This simplication is mainly due to the fact that at each point of X_{n-1} there exists a unique normal N^{\vee} .

In this case, we may take

$$\varepsilon_x = 1$$
 2.1

without the loss of generality. Therefore, quantities intoduced in I and the previous section take the following simpler forms and values:

$$N_x^{\alpha} = N_n^{\alpha} \stackrel{\text{def}}{=} N^{\alpha}, \quad N_{\alpha}^x = N_{\alpha}^n \stackrel{\text{def}}{=} N_{\alpha}$$
 2.2a

$$X_x = X^x = X_\alpha N^\alpha \stackrel{\text{def}}{=} \chi$$
 2.2b

$$\Omega_{ij}^{x} = \Omega_{ij}^{n} = (D_{\beta}N_{\alpha})B_{i}^{\alpha}B_{j}^{\beta} \stackrel{\text{def}}{=} \Omega_{ij}$$
 2.2c

$$\Lambda_{ij}^{x} = \Lambda_{ij}^{n} = (\nabla_{\beta} N_{\alpha}) B_{i}^{\alpha} B_{j}^{\beta} \stackrel{\text{def}}{=} \Lambda_{ij}$$
 2.2d

$$^*k_{ix} = ^*k_i{}^x = ^*k_{in} = ^*k_{\alpha\beta} B_i^{\alpha} B^{\beta} \stackrel{\text{def}}{=} ^*k_i$$
 2.2e

$$^*k_{xy} = ^*k_x{}^y = ^*k_{nn} = 0 2.2f$$

$$H_{\gamma}^{xy} = H_{\gamma}^{nn} = 0 ag{2.2g}$$

In virtue of (2.1) and (2.2), it may be easily shown that

$$\Omega_{ij} = \Lambda_{ij} - 2\chi * g_{ij}$$
 2.3a

$$^*k_x{}^i = -^*k_i 2.3b$$

Theorem 9 At points of a hypersubmanifold X_{n-1} of *g-MEX_n, the following generalized fundamental equations hold:

(The generalized Gauss formulae on X_{n-1} of *g-MEX_n)

$$D_{i}^{\circ}B_{i}^{\vee} = (-\Lambda_{ij} + 2\chi^{*}g_{ij})N^{\vee}$$
2.4a

(The generalized Weingarten equations on X_{n-1} of *g-MEX_n)

$$D_{j}^{\circ}N_{x}^{\vee} = (*h^{ih} \Lambda_{hj} + 2X^{i} *k_{j})B_{i}^{\vee} + 2(X_{j} + \chi *k_{j})N^{\vee}$$

$$= [*h^{ih} \Omega_{hj} + 2X^{i} *k_{j} + 2\chi(\delta_{j}^{i} - *k_{j}^{i})]B_{i}^{\vee} +$$

$$+2(X_{j} + \chi *k_{j})N^{\vee}$$
2.4b

(The generalized Gauss equations on X_{n-1} of *g-MEX_n)

$$\bar{R}_{ijk}{}^{h} = R_{\beta\gamma\epsilon}{}^{\alpha} B_{i}^{\beta} B_{j}^{\gamma} B_{k}^{\epsilon} B_{\alpha}^{h} + 2\Omega_{k[i} (\Omega_{|p|j]}{}^{*} h^{hp} + 2\chi (\delta_{j]}^{h} - {}^{*}k_{j]}{}^{h} + 2 {}^{*}k_{j]} X^{h})$$

$$2.4c$$

(The generalized Codazzi equations on X_{n-1} of $*g\text{-MEX}_n$)

$$2\nabla_{[k}\Omega_{|i|j]} = R_{\beta\gamma\epsilon}{}^{\alpha}B_{k}^{\beta}B_{j}^{\gamma}B_{i}^{\epsilon}N_{\alpha} + 4\chi\Omega_{i[k}{}^{*}k_{j]} + 4{}^{*}g_{i[j}\Omega_{|h|k]}X^{h}$$
 2.4d)

Proof. In virtue of (2.1), (2.2), and (2.3), the identities (2.4) follow from (1.1), (1.11), (1.18), and (1.19), respectively.

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