Lower bounds for Riesz-Fischer maps in rigged Hilbert spaces

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Abstract. This note concerns a further study about Riesz-Fischer maps, already introduced by the author in a recent work, that is a notion that extends to the spaces of distributions the sequences that are known as Riesz-Fischer sequences. In particular it is proved a characterizing inequality that has as consequence the existence of the continuous inverse of the synthesis operator.

Keywords: distributions, rigged Hilbert spaces, frames, Riesz-Fischer sequences

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Introduction

As it is known, given an element $f \in \mathcal{H}$ and a sequence of elements $\{f_n\}_{n \in \mathbb{N}}$ in a Hilbert space \mathcal{H} endowed of the inner product $\langle \cdot | \cdot \rangle$, the sequence $a_n : \mathbb{N} \to \mathbb{C}$, $a_n := \langle f | f_n \rangle$ is called *moment sequence* -briefly *moments- of* $f \in \mathcal{H}$. The problem to find a solution $f \in \mathcal{H}$ of the equations:

$$\langle f|f_n\rangle = a_n, \quad n \in \mathbb{N}$$

given $\{f_n\}_{n\in\mathbb{N}}\subset\mathcal{H}$ and $\{a_n\}_{n\in\mathbb{N}}\subset\mathbb{C}$, is known as moment problem.

In particular, the sequence $\{f_n\}_{n\in\mathbb{N}}$ is called *Riesz-Fischer sequence* if, for every $\{a_n\}_{n\in\mathbb{N}} \in \ell^2$ (i.e. such that $\sum_{1}^{\infty} |a_n|^2 < \infty$), there exists a solution f of the moment problem.

On the other hand, the sequence $\{f_n\}_{n\in\mathbb{N}}$ is called *Bessel sequence* if, for all $f \in \mathcal{H}$, one has $\{\langle f|f_n\rangle\}_{n\in\mathbb{N}} \in \ell^2$.

We have the well-known characterization results [22, Ch. 4, Sec. 2, Th. 3]:

• $\{f_n\}_{n\in\mathbb{N}}$ is a Riesz-Fischer sequence if, and only if, there exists A > 0 such that:

$$A\sum |c_n|^2 \le \|\sum c_n f_n\|^2$$
 (0.1)

for all finite scalar sequences $\{c_n\} \subset \mathbb{C}$;

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• $\{f_n\}_{n\in\mathbb{N}}$ is a Bessel sequence if, and only if, there exists B > 0 such that:

$$\|\sum c_n f_n\|^2 \le B \sum |c_n|^2 \tag{0.2}$$

for all finite scalar sequences $\{c_n\} \subset \mathbb{C}$.

Bessel and Riesz-Fischer sequences play an important role in the theory of frames and, in particular, in the study of Riesz bases [22, 8]. Roughly speaking, a frame is an extension of a basis in a Hilbert space, in the sense that every vector of \mathcal{H} can be decomposed in terms of elements of a frame, but this decomposition is not unique. This "loss of constraints" or "more leeway" allows several applications in many branches of mathematical sciences and technology.

More precisely, a sequence $\{f_n\}_{n\in\mathbb{N}}$ in \mathcal{H} is a *frame* if there exist A, B > 0 such that:

$$A||f||^{2} \leq \sum_{n \in \mathbb{N}} |\langle f|f_{n}\rangle|^{2} \leq B||f||^{2}, \forall f \in \mathcal{H}.$$

A frame $\{f_n\}_{n\in\mathbb{N}}$ that is also a basis for \mathcal{H} , is called *Riesz basis*. One has that Bessel, Riesz-Fischer sequences and Riesz basis are related via linear operators to orthonormal basis (see [22, 8, 5]). Furthermore, if $\{f_n\}_{n\in\mathbb{N}}$ is complete or total (i.e. the set of its linear span is dense in \mathcal{H}), then it is a Riesz basis if, and only if, it is both Bessel and Riesz-Fischer sequence [22].

If it is not diversely specified, a frame is intended as discrete. However, a notion of *continuous frame* have been introduced by S. T. Ali, J. P. Antoine, J. P. Gazeau in [1, 2] in order to study coherent states, and, independently, by G. Kaiser in [17]. Instead of a sequence, it is considered a map F from a measure space (X, μ) (μ is a positive measure) to a Hilbert space \mathcal{H} , i.e.: $F : X \to \mathcal{H}$, $F : x \mapsto F_x$. The map F is called continuous frame with respect to (X, μ) if:

- F is weakly measurable, i.e. that is $x \to \langle f | F_x \rangle$ is μ -measurable for every $f \in \mathcal{H}$;
- there exist A, B > 0 such that:

$$A||f||^2 \le \int_X |\langle f|F_x\rangle|^2 d\mu \le B||f||^2, \quad \forall f \in \mathcal{H}.$$

In [20], C. Trapani, S. Triolo and the author have extended the notion of frame, and related topics as Bessel, bases, Riesz basis, etc., to the spaces of distributions; in [21] and [10] a further study has been done respectively for Riesz-Fischer sequences and multipliers.

An appropriate framework for the spaces of distributions is given by the rigged Hilbert space i.e. a triple $\mathcal{D} \subset \mathcal{H} \subset \mathcal{D}^{\times}$ where \mathcal{D} is a locally convex space,

 \mathcal{D}^{\times} the conjugate dual to \mathcal{D} , and where the inclusions have to be intended as continuous and dense embedding. They have been introduced by Gel'fand in [13, 14] with the aim to define the *generalized eigenvectors* of an essential self-adjoint operator on \mathcal{D} and to prove the theorem known as Gel'fand-Maurin theorem, on the existence of a complete system of generalized eigenvector (see also [15]). For that it is called also *Gel'fand triple*, also denoted by $(\mathcal{D}, \mathcal{H}, \mathcal{D})$.

However *Gel'fand triple* play a relevant role also in other branches of mathematics, such as Gabor Analysis: see for example [9, 11, 12]. More exhaustive references, papers and talks can be found on: www.nuhag.eu/talks.

Reconsidering Riesz-Fischer maps introduced in [21], the aim of this paper is to continue the study, proving characterizing conditions, analogously to (0.1)for the Riesz-Fischer sequences. The paper is organized as follows. In Section 2 are recalled some preliminaries, definitions and previous results. In Section 3 are proved some characterizations of Riesz-Fischer maps in term of lower bounds properties.

1 Preliminary definitions and facts

As usual, let us denote by \mathcal{H} a Hilbert space, $\langle \cdot | \cdot \rangle$ its inner product and $\| \cdot \|$ the Hilbert norm. Let \mathcal{D} be a dense subspace of \mathcal{H} endowed with a locally convex topology t stronger than the topology induced by the Hilbert norm. The embedding of \mathcal{D} in \mathcal{H} is continuous and dense, and it is denoted by $\mathcal{D} \hookrightarrow \mathcal{H}$. The space of conjugate linear continuous forms on \mathcal{D} is called *conjugate dual* of \mathcal{D} and it is denoted by \mathcal{D}^{\times} . Unless otherwise stated, the value of $F \in \mathcal{D}^{\times}$ on $f \in \mathcal{D}$ is denoted by $\langle f | F \rangle$. The space \mathcal{D}^{\times} is endowed with the strong dual topology $t^{\times} = \beta(\mathcal{D}^{\times}, \mathcal{D})$ defined by the set of seminorms:

$$p_{\mathcal{M}}(F) = \sup_{g \in \mathcal{M}} |\langle g | F \rangle|, \quad F \in \mathcal{D}^{\times},$$
(1.3)

where \mathcal{M} is a bounded subset of $\mathcal{D}[t]$. In this way, the Hilbert space \mathcal{H} can be continuously embedded as subspace of \mathcal{D}^{\times} (see [16]). If \mathcal{D} is reflexive, i.e. $\mathcal{D}^{\times \times} = \mathcal{D}$, the embedding is dense and the Gel'fand triple is obtained:

$$\mathcal{D}[t] \hookrightarrow \mathcal{H} \hookrightarrow \mathcal{D}^{\times}[t^{\times}], \tag{1.4}$$

where \hookrightarrow denotes a continuous and dense embedding. The sesquilinear form $\langle \cdot | \cdot \rangle$ that puts \mathcal{D} and \mathcal{D}^{\times} in duality is an extension of the inner product of \mathcal{H} and has the same notation. We put: $\langle F | f \rangle := \overline{\langle f | F \rangle}$.

Throughout the paper, (X, μ) will be measure space, where μ is a σ -finite positive measure. By $L^1(X, \mu), L^2(X, \mu), \cdots$ we mean the usual spaces of measurable functions; if $X = \mathbb{R}$, and μ is the Lebesgue measure, we denote them as

 $L^p(\mathbb{R})$. Furthermore, S stands for the *Schwartz space*, i.e. the space of infinitely differentiable and rapidly decreasing functions on \mathbb{R} . The conjugate dual of S, denoted by S^{\times} , is known as the space of *tempered distributions* (see [18] for more accurate definitions). An usual example of rigged Hilbert space is given by:

$$\mathcal{S} \hookrightarrow L^2(\mathbb{R}) \hookrightarrow \mathcal{S}^{\times}$$

The vector space of all continuous linear maps from $\mathcal{D}[t]$ into $\mathcal{D}^{\times}[t^{\times}]$ will be denoted by $\mathcal{L}(\mathcal{D}, \mathcal{D}^{\times})$. If $\mathcal{D}[t]$ is barreled (e.g. reflexive), an involution can be introduced in $\mathcal{L}(\mathcal{D}, \mathcal{D}^{\times})$, $X \mapsto X^{\dagger}$, by:

$$\left\langle X^{\dagger}\eta|\xi\right\rangle = \overline{\langle X\xi|\eta\rangle}, \quad \forall \xi, \eta \in \mathcal{D}.$$
 (1.5)

Hence, in this case, $\mathcal{L}(\mathcal{D}, \mathcal{D}^{\times})$ is a [†]-invariant vector space. For a detailed study, see [3].

In this paper we consider maps with values in a distribution space, defined in [20] as *weakly measurable maps*, and here denoted by ω . The definition extends the notion, previously recalled in the introduction, of weakly measurable functions considered for continuous frames (see [2]).

Definition 1. The correspondence $\omega : X \to \mathcal{D}^{\times}, x \mapsto \omega_x$ is called *weakly* measurable map if the complex valued function $x \mapsto \langle f | \omega_x \rangle \in \mathbb{C}$ is μ -measurable for all $f \in \mathcal{D}$.

In particular, the notions of completeness and independence of sequences in the Hilbert space is extended to the spaces of distributions by the following:

Definition 2. Let $\omega : x \in X \to \omega_x \in \mathcal{D}^{\times}$ be a weakly measurable map, then:

- i) ω is total or complete if, $f \in \mathcal{D}$ and $\langle f | \omega_x \rangle = 0$ μ -a.e. $x \in X$ implies f = 0;
- ii) ω is μ -independent if the unique measurable function $\xi : X \to \mathbb{C}$ such that $\int_X \xi(x) \langle g | \omega_x \rangle \, d\mu = 0$ for every $g \in \mathcal{D}$, is $\xi(x) = 0 \mu$ -a.e.

Let us recall the notion of *Bessel map*:

Definition 3. [20, Definition 3.2] A weakly measurable map ω is a *Bessel* distribution map (briefly: Bessel map) if for every $f \in \mathcal{D}$, $\int_X |\langle f | \omega_x \rangle|^2 d\mu < \infty$.

As a consequence of the closed graph theorem, if \mathcal{D} is a Frèchet space, for the Bessel maps one has the following characterization result:

Proposition 1. [20, Proposition 3.1] Let $\mathcal{D}[t]$ be a Frèchet space, and ω : $x \in X \to \omega_x \in \mathcal{D}^{\times}$ be a weakly measurable map. The following statements are equivalent.

(i) ω is a Bessel map;

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(ii) there exists a continuous seminorm p on $\mathcal{D}[t]$ such that:

$$\left(\int_X |\langle f|\omega_x\rangle|^2 d\mu\right)^{1/2} \le p(f), \quad \forall f \in \mathcal{D}$$

(iii) for every bounded subset \mathcal{M} of \mathcal{D} there exists $C_{\mathcal{M}} > 0$ such that:

$$\sup_{f \in \mathcal{M}} \left| \int_X \xi(x) \left\langle \omega_x | f \right\rangle d\mu \right| \le C_{\mathcal{M}} \|\xi\|_2, \quad \forall \xi \in L^2(X,\mu).$$

The previous proposition has the following consequences [20]:

• If $\xi \in L^2(X, \mu)$, then the conjugate linear functional Λ_{ω}^{ξ} on \mathcal{D} defined by:

$$\left\langle f|\Lambda_{\omega}^{\xi}\right\rangle := \int_{X} \xi(x) \left\langle f|\omega_{x}\right\rangle d\mu, \quad \forall f \in \mathcal{D}$$
 (1.6)

is defined and continuous, i.e. $\Lambda_{\omega}^{\xi} \in \mathcal{D}^{\times}[t^{\times}];$

• the synthesis operator $D_{\omega} : L^2(X,\mu) \to \mathcal{D}^{\times}[t^{\times}]$ weakly defined by $D_{\omega} : \xi \mapsto \Lambda_{\omega}^{\xi}$, i.e. such that:

$$\langle f|D_{\omega}\xi\rangle := \int_{X} \xi(x) \langle f|\omega_{x}\rangle d\mu, \quad \forall f \in \mathcal{D}$$

is continuous;

- the analysis operator $C_{\omega} : \mathcal{D}[t] \to L^2(X,\mu)$ defined by $(C_{\omega}f)(x) = \langle f | \omega_x \rangle$ is continuous;
- the frame operator $S_{\omega} : \mathcal{D} \to \mathcal{D}^{\times}, S_{\omega} := D_{\omega}C_{\omega}$ is continuous, i.e. $S_{\omega} \in \mathcal{L}(\mathcal{D}, \mathcal{D}^{\times}).$

Remark 1. If \mathcal{D} is a Frèchet space, a Bessel map ω is bounded from above by a continuous seminorm on \mathcal{D} , but, in general, is not bounded from above by the Hilbert norm. An example, considered in [21], is the system of derivative of Dirac deltas on $\mathcal{S} \hookrightarrow L^2(\mathbb{R}) \hookrightarrow \mathcal{S}^{\times}$ denoted by $\{\delta'_x\}_{x \in \mathbb{R}}$, and defined by: $\langle f | \delta'_x \rangle := -f'(x)$. Then δ'_x is a Bessel map but is not bounded from above by the Hilbert norm. In [20] the notion of *bounded Bessel map* is defined, i.e. a Bessel map ω such that there exists B > 0 such that: $\int_X |\langle f | \omega_x \rangle|^2 d\mu \leq B \| f \|^2$ for all $f \in \mathcal{D}$. In particular, if ω is also total and if there exists B > 0 such that $0 < \int_X |\langle f | \omega_x \rangle|^2 d\mu \leq B \| f \|^2$ for all $f \neq 0$, then ω is called *distribution upper semiframe* [21], as extension to the space of distributions of the corresponding notion of *continuous upper semiframe* introduced in [4]. If a bounded Bessel map ω is also bounded from below by the Hilbert norm, we have the definition of *distribution frame*:

Definition 4. [20, Definition 3.6] Let $\mathcal{D}[t] \hookrightarrow \mathcal{H} \hookrightarrow \mathcal{D}^{\times}[t^{\times}]$ be a rigged Hilbert space, with $\mathcal{D}[t]$ a reflexive space and ω is a Bessel map. We say that ω is a *distribution frame* if there exist A, B > 0 such that:

$$A\|f\|^{2} \leq \int_{X} |\langle f|\omega_{x}\rangle|^{2} d\mu \leq B\|f\|^{2}, \quad \forall f \in \mathcal{D}.$$

We have that (see [20] for details): Λ_{ω}^{ξ} is bounded in $(\mathcal{D}, \|\cdot\|)$ and the bounded extension to \mathcal{H} is denoted by $\tilde{\Lambda}_{\omega}^{\xi}$; the synthesis operator D_{ω} has range in \mathcal{H} and it is bounded; the Hilbert adjoint D_{ω}^* extends C_{ω} to \mathcal{H} ; the operator $\tilde{S}_{\omega} = D_{\omega}D_{\omega}^*$ is bounded and extends the frame operator S_{ω} .

If ω is a distribution frame, then the frame operator \hat{S}_{ω} satisfies the inequality:

$$A||f|| \le ||S_{\omega}f|| \le B||f||, \quad \forall f \in \mathcal{H},$$

with A, B > 0 frame bounds for ω . Since \hat{S}_{ω} is symmetric, this implies that \hat{S}_{ω} has a bounded inverse \hat{S}_{ω}^{-1} everywhere defined in \mathcal{H} .

In [21] are defined the Riesz-Fischer maps in the space of distributions. They are the analogous of that notion in Hilbert spaces whose extension to the continuous case is given in [19].

Definition 5. [21, Definition 3.4] Let $\mathcal{D}[t]$ be a locally convex space. A weakly measurable map $\omega : x \in X \mapsto \omega_x \in \mathcal{D}^{\times}$ is called a *Riesz-Fischer* distribution map (briefly: Riesz-Fischer map) if, for every $h \in L^2(X, \mu)$, there exists $f \in \mathcal{D}$ such that:

$$\langle f | \omega_x \rangle = h(x) \quad \mu\text{-a.e.}$$
 (1.7)

In this case, we say that f is a solution of equation $\langle f | \omega_x \rangle = h(x)$.

Clearly, if f_1 and f_2 are solutions of (1.7), then $f_1 - f_2 \in \omega^{\perp} := \{g \in \mathcal{D} : \langle g | \omega_x \rangle = 0, \quad \mu - a.e. \}$. If ω is total, the solution is unique.

The analysis operator C_{ω} is defined on $dom(C_{\omega}) := \{f \in \mathcal{D} : \langle f | \omega_x \rangle \in L^2(X, \mu)\}$ as $C_{\omega} : f \in dom(C_{\omega}) \mapsto \langle f | \omega_x \rangle \in L^2(X, \mu)$. Clearly, ω is a Riesz-Fischer map if and only if $C_{\omega} : dom(C_{\omega}) \to L^2(X, \mu)$ is surjective. If ω is total, it is injective too, so, in this case, C_{ω} is invertible.

To define the synthesis operator D_{ω} we consider the following subset of $L^2(X,\mu)$:

$$dom(D_{\omega}) := \{\xi \in L^2(X,\mu), \text{s.t. } \int_X \xi(x)\omega_x d\mu \text{ is convergent in } \mathcal{D}^{\times}\}.$$

Where convergent in \mathcal{D}^{\times} means that: $\int_X \xi(x) \langle f | \omega_x \rangle d\mu$ is convergent for all $f \in \mathcal{D}$ and the conjugate functional on \mathcal{D} defined in (1.6) by Λ_{ω}^{ξ} , is continuous,

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so $\Lambda_{\omega}^{\xi} \in \mathcal{D}^{\times}$. Then the synthesis operator $D_{\omega} : dom(D_{\omega}) \to \mathcal{D}^{\times}$ is weakly defined by:

$$D_{\omega}: \xi \mapsto \Lambda_{\omega}^{\xi} := \int_X \xi(x) \omega_x d\mu.$$

The range of D_{ω} is denoted by $Ran(D_{\omega})$:

$$Ran(D_{\omega}) := \Big\{ F \in \mathcal{D}^{\times} : \exists \xi \in dom(D_{\omega}) : \forall f \in \mathcal{D}, \langle f | F \rangle := \int_{X} \xi(x) \langle f | \omega_{x} \rangle \, d\mu \Big\}.$$

If \mathcal{D} is a Frèchet space, as a consequence of the closed graph theorem one has, for a total Riesz-Fischer map ω , the following inequality:

Corollary 1. [21, Corollary 3.7] Assume that $\mathcal{D}[t]$ is a Frèchet space. If the map $\omega : x \in X \to \omega_x \in \mathcal{D}^{\times}$ is a total Riesz-Fischer map, then for every continuous seminorm p on \mathcal{D} , there exists a constant C > 0 such that, for the solution f of (1.7):

$$p(f) \le C \| \langle f | \omega_x \rangle \|_2.$$

It follows that, if ω is a total Riesz-Fischer map, the inverse of the analysis operator $C_{\omega}^{-1}: L^2(X, \mu) \to dom(C_{\omega})$ is continuous.

2 Main results

In this section are proved some characterization properties of Riesz-Fischer maps. We have the following:

Proposition 2. Let (X, μ) be a measure space, $h(x) \in L^2(X, \mu)$ and $\omega : X \ni x \mapsto \omega_x \in \mathcal{D}^{\times}$ a weakly measurable map. Then ω is a Riesz-Fischer map if, and only if, there exists a bounded subset $\mathcal{M} \subset \mathcal{D}$ such that:

$$\left|\int_{X} \xi(x)\overline{h(x)}d\mu\right| \leq \sup_{f \in \mathcal{M}} \left|\int_{X} \xi(x)\left\langle\omega_{x}|f\right\rangle d\mu\right|$$
(2.8)

for all $\xi(x) \in L^2(X,\mu)$ such that $\int_X \xi(x) \omega_x d\mu$ is convergent in \mathcal{D}^{\times} .

Proof. Necessity is obvious: let \overline{f} be a solution of (1.7), then, for all $\xi(x)$, one has:

$$\Big|\int_X \xi(x)\overline{h(x)}d\mu\Big| = \Big|\int_X \xi(x)\left\langle\omega_x|\bar{f}\right\rangle d\mu\Big| \le \sup_{f\in\mathcal{M}}\Big|\int_X \xi(x)\left\langle\omega_x|f\right\rangle d\mu\Big|.$$

Sufficiency: if the condition (2.8) holds, consider the subspace $\mathcal{E} \subset \mathcal{D}^{\times}$ defined by the set of elements $F \in \mathcal{D}^{\times}$ such that there exists $\xi \in L^2(X,\mu)$: $F = \int_X \xi(x) \omega_x d\mu$, and let us define the linear functional ν on \mathcal{E} by:

$$\nu(F) = \nu\Big(\int_X \xi(x)\omega_x d\mu\Big) := \int_X \xi(x)\overline{h(x)}d\mu$$

It follows immediately from hypothesis that ν is defined unambiguously. Furthermore, from (2.8) one has:

$$\left|\nu(F)\right| = \left|\int_{X} \xi(x)\overline{h(x)}d\mu\right| \le \sup_{f\in\mathcal{M}} \left|\int_{X} \xi(x)\left\langle\omega_{x}|f\right\rangle d\mu\right| = \sup_{f\in\mathcal{M}} \left|\left\langle f|F\right\rangle\right|, \forall F\in\mathcal{E}$$

i.e. $\nu(F)$ is bounded by a seminorm of $\mathcal{D}^{\times}[t^{\times}]$. By Hahn-Banach theorem, there exists an extension $\tilde{\nu}$ of ν to \mathcal{D}^{\times} . Since \mathcal{D} is reflexive, there exists $\bar{f} \in \mathcal{D}$ such that: $\tilde{\nu}(F) = \langle F | \bar{f} \rangle$. Since:

$$\int_{X} \xi(x) [\langle \omega_{x} | \bar{f} \rangle - \overline{h(x)}] d\mu = \nu(F) - \int_{X} \xi(x) \overline{h(x)} d\mu = 0, \quad \forall \xi \in L^{2}(X, \mu)$$

then $\langle f | \omega_x \rangle = h(x) \mu$ -a.e.

As consequence, we have the following:

Corollary 2. ω is a Riesz-Fischer map if, and only if, there exists a bounded subset $\mathcal{M} \subset \mathcal{D}$ such that:

$$\|\xi\|_{2} \leq \sup_{f \in \mathcal{M}} \Big| \int_{X} \xi(x) \langle f | \omega_{x} \rangle \, d\mu \Big|, \tag{2.9}$$

for all $\xi(x) \in L^2(X,\mu)$ such that $\int_X \xi(x) \omega_x d\mu$ is convergent in \mathcal{D}^{\times} .

Proof. Sufficiency: if the condition (2.9) holds, consider $h(x) \in L^2(X, \mu)$ with $||h(x)||_2 \leq 1$, then:

$$\Big|\int_X \xi(x)\overline{h(x)}d\mu\Big| \le \|\xi\|_2 \le \sup_{f\in\mathcal{M}}\Big|\int_X \xi(x)\langle f|\omega_x\rangle\,d\mu\Big|.$$

Then, for the previous proposition, ω is a Riesz-Fischer map. Necessity: lete ω be a Riesz-Fischer map and put $\frac{\xi(x)}{\|\xi(x)\|_2} = h(x)$ (for $\xi \neq 0$), by Proposition 2 there exists a bounded subset $\mathcal{M} \subset \mathcal{D}$ such that:

$$\|\xi\|_{2} = \int_{X} \xi(x) \frac{\overline{\xi(x)}}{\|\xi(x)\|_{2}} d\mu \leq \sup_{f \in \mathcal{M}} \Big| \int_{X} \xi(x) \langle f|\omega_{x} \rangle \, d\mu \Big|.$$
QED

The previous Corollary can be rephrased as:

Corollary 3. ω is a Riesz-Fischer map if, and only if, the synthesis operator D_{ω} is invertible and the inverse $D_{\omega}^{-1} : Ran(D_{\omega}) \to L^2(X, \mu)$ is continuous.

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3 Conclusions

The inequalities in Proposition 1(iii) and in Corollary 2 are an extension to the rigged Hilbert spaces respectively of the inequalities (0.2), and (0.1) for sequences in Hilbert spaces (see [22, Ch. 4, Sec. 2, Th. 2, Th. 3]). In the case of sequences, it follows immediately that: if $\{e_n\}_{n\in\mathbb{N}}$ is an orthonormal basis of \mathcal{H} , then $\{f_n\}_{n\in\mathbb{N}}$ is a Bessel sequence if, and only if, there exists a bounded operator $T: \mathcal{H} \to \mathcal{H}$ such that $f_n = Te_n$; $\{f_n\}_{n\in\mathbb{N}}$ is a Riesz-Fischer sequence if, and only if, there exists a bounded operator $V: \mathcal{H} \to \mathcal{H}$ such that $Vf_n = e_n$ (for frames and Riesz-bases see also [5, Proposition 4.6]). Since in the spaces of distributions the orthonormality is not defined, a sort of "orthonormal basis" is played by the *Gel'fand basis*: see [20] and [21, Definition 5.3]. So, it would be appropriate to carry on a further study, started in [20], about the transformations between Gal'fand basis, Bessel, Riesz-Fischer maps, distribution frames, and Riesz distribution basis.

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