# Generalized digital ( $k_{0}, k_{1}$ )-homeomorphism 

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#### Abstract

The aim of this paper is to introduce a generalized digital ( $k_{0}, k_{1}$ )-homeomorphism of the digital curve and the digital surface in $\mathbb{Z}^{n}$. The generalized digital $\left(k_{0}, k_{1}\right)$-continuity is studied with the $n$ kinds of $k$-adjacency relations in $\mathbb{Z}^{n}$. The $k$-type digital fundamental group of the digital image comes from the generalized digital ( $k_{0}, k_{1}$ )-homotopy, $i \in\{0,1\}$. Furthermore, we show how a digital $\left(k_{0}, k_{1}\right)$-homeomophism induces a digital fundamental group ( $k_{0}, k_{1}$ )-isomorphism.


Keywords: digital ( $k_{0}, k_{1}$ )-continuity, digital ( $k_{0}, k_{1}$ )-homeomorphism, digital curve, digital surface.

MSC 2000 classification: primary: 55P10; secondary 55P15.

## Introduction

The digital $k$-adjacency on digital curves and digital surfaces in $\mathbb{Z}^{3}$ are investigated in $[7,8,9]$. The digital continuity was introduced in $[1,2,10]$ and further an advanced concept of the digital continuity was also introduced [1].

Recently, the digital $\left(k_{0}, k_{1}\right)$-continuity was investigated with relation to the digital $\left(k_{0}, k_{1}\right)$-homeomorphism, and further it is a generalization of the concepts from $[1,2,10]$ relative to the dimension and the adjacency.

By virtue of a generalization of the $k$-adjacency relations, we consider the generalized digital $\left(k_{0}, k_{1}\right)$-continuity and the generalized digital $\left(k_{0}, k_{1}\right)$-homeomorphism in $\mathbb{Z}^{4}$ and $\mathbb{Z}^{5}$.

We work in the category of finite digital images and digitally $\left(k_{0}, k_{1}\right)$-continuous maps.

## 1 Notation and basic terminology

In the set $\mathbb{Z}^{n}$ of points in the Euclidean $n$-dimensional space, $n=4,5$, that have integer coordinates, two metric spaces $\left(\mathbb{Z}^{n}, d_{n}\right)$ and $\left(\mathbb{Z}^{n}, d_{*}\right)$ are considered with the following metric functions:
$d_{n}, d_{*}: \mathbb{Z}^{n} \times \mathbb{Z}^{n} \rightarrow \mathbb{N} \cup\{0\}$ are defined by
$(M 1) d_{n}(p, q)=\sum_{i=1}^{n}\left|p_{i}-q_{i}\right|$ and
$(M 2) d_{*}(p, q)=\max \left\{\left|p_{i}-q_{i}\right|\right\}_{i \in M}, M=\{1,2, \cdots, n\}$, respectively
for two points $p, q \in \mathbb{Z}^{n}, \mathbb{N}$ is the set of natural numbers.
By use of the above two metric functions we get the $k$-adjacency relations of a digital image in $\mathbb{Z}^{4}$ and $\mathbb{Z}^{5}$.

Basically, two pixels $\left(p_{1}, p_{2}\right),\left(q_{1}, q_{2}\right) \in \mathbb{Z}^{2}$ are called 4 -adjacent if $\left|p_{1}-q_{1}\right|+$ $\left|p_{2}-q_{2}\right|=1$. And they are called 8 -adjacent if $\max \left\{\left|p_{1}-q_{1}\right|,\left|p_{2}-q_{2}\right|\right\}=1[7,8]$.

Two voxels $\left(p_{1}, p_{2}, p_{3}\right),\left(q_{1}, q_{2}, q_{3}\right)\left(\in \mathbb{Z}^{3}\right)$ are called 6 -adjacent if

$$
\left|p_{1}-q_{1}\right|+\left|p_{2}-q_{2}\right|+\left|p_{3}-q_{3}\right|=1 .
$$

They are called 26-adjacent if $\max \left\{\left|p_{1}-q_{1}\right|,\left|p_{2}-q_{2}\right|,\left|p_{3}-q_{3}\right|\right\}=1[8,9]$.
Furthermore, two points are 18 -adjacent if they are 26 -adjacent and differ in at most two of their coordinates [8].

Concretely, a digital picture is considered as a quadruple $P=(V, k, \bar{k}, X)$ with black points set $X \subset V$ and white points set $V-X$. If $V=\mathbb{Z}^{2},(k, \bar{k})=$ $(4,8)$ or $(8,4)$, and if $V=\mathbb{Z}^{3},(k, \bar{k})=(6,26),(26,6),(6,18)$ or $(18,6)[11,8,9]$.

The point $p=\left(p_{1}, p_{2}, p_{3}, p_{4}, p_{5}\right) \in \mathbb{Z}^{5}$ is considered as a 5-cube $\left\{\left(p_{1} \pm\right.\right.$ $\left.\left.1 / 2, p_{2} \pm 1 / 2, p_{3} \pm 1 / 2, p_{4} \pm 1 / 2, p_{5} \pm 1 / 2\right)\right\}$ with a center $p$, whose edges are parallel to each axes.

Now in $\mathbb{Z}^{5}$, we consider the following equations which are relevant for the $k$-neighborhood and the $k$-adjacency relations.

For two 5 -xels $p=\left(p_{1}, p_{2}, p_{3}, p_{4}, p_{5}\right), q=\left(q_{1}, q_{2}, q_{3}, q_{4}, q_{5}\right) \in \mathbb{Z}^{5}$
(1) $d_{5}(p, q)=5, d_{*}(p, q)=1 \Rightarrow$ then $p$ shares a point with $q$,
(2) $d_{5}(p, q)=4, d_{*}(p, q)=1 \Rightarrow$ then $p$ shares an edge with $q$,
(3) $d_{5}(p, q)=3, d_{*}(p, q)=1 \Rightarrow$ then $p$ shares a face with $q$,
(4) $d_{5}(p, q)=2, d_{*}(p, q)=1 \Rightarrow$ then $p$ shares a cube with $q$,
(5) $d_{5}(p, q)=1, d_{*}(p, q)=1 \Rightarrow$ then $p$ shares a 4 -cube with $q$.

Consequently, in $\mathbb{Z}^{5}$, the 5 kinds of digital $k$-neighborhoods are obtained from (1) $\sim(5)$ above and by the properties of the combination as follows:
(1) ${ }^{\prime} N_{242}(p)=\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q) \leq 5, d_{*}(p, q)=1\right\}$ from the above formula (1) such that $\sharp\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q) \leq 5, d_{*}(p, q)=1\right\}=242$, where $\sharp$ means the cardinality of the set.
(2) ${ }^{\prime} N_{210}(p)=\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q) \leq 4, d_{*}(p, q)=1\right\}$ from the above formula (2).

Namely, for $p=\left(p_{1}, p_{2}, p_{3}, p_{4}, p_{5}\right) \in \mathbb{Z}^{5}, N_{210}(p)=N_{242}(p)-X_{5}(p)$, where $X_{5}(p)=\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q)=5, d_{*}(p, q)=1\right\}$. In fact, $X_{5}(p)=\left\{\left(p_{1} \pm 1, p_{2} \pm\right.\right.$ $\left.\left.1, p_{3} \pm 1, p_{4} \pm 1, p_{5} \pm 1\right)\right\}$. Now we use the notation, $X_{5}(p)=\cup_{i=0}^{5} X_{5}(p)^{i}$ in terms of the following notations:
$X_{5}(p)^{0}=\left\{\left(p_{1}+1, p_{2}+1, p_{3}+1, p_{4}+1, p_{5}+1\right)\right\}$ with $\sharp X_{5}(p)^{0}=C_{0}^{5}=1$, where $C_{i}^{5}$ stands for the combination of 5 objects taken $i$.
$X_{5}(p)^{1}=\left\{\left(p_{1}+1, p_{i-1}+1, p_{i}-1, p_{i+1}+1, p_{5}+1\right) \mid i \in[1,5]_{\mathbb{Z}}\right\}$ and $\sharp X_{5}(p)^{1}=$ $C_{1}^{5}$, i.e., $X_{5}(p)^{1}$ consists of the elements which have the coordinates with only one element $p_{i}-1(1 \leq i \leq 5)$ and the others are $p_{j}+1(i \neq j)$.
$X_{5}(p)^{2}=\left\{\left(p_{i-1}+1, p_{i}-1, p_{j}-1, p_{j+1}+1, p_{j+2}+1\right)\right\}$, where $i \neq j \in[1,5]_{\mathbb{Z}}$ and $\sharp X_{5}(p)^{2}=C_{2}^{5}$, i.e., $X_{5}(p)^{2}$ consists of the elements which have the coordinates with only two elements, $p_{i}-1, p_{j}-1,1 \leq i, j \leq 5$, and the others $p_{k}+1(k \neq i, j)$.
$X_{5}(p)^{3}=\left\{\left(p_{i}-1, p_{i+1}+1, p_{j}-1, p_{k}-1, p_{k+1}+1\right)\right\}$, where $i \neq j \neq k \in$ $[1,5]_{\mathbb{Z}}$ with $\sharp X_{5}(p)^{3}=C_{3}^{5}$, i.e., $X_{5}(p)^{3}$ consists of the elements which have the coordinates with only three elements, $p_{i}-1, p_{j}-1, p_{k}-1,1 \leq i, j, k \leq 5$, and the others are $p_{l}+1,1 \leq l \leq 5, l \neq i, j, k$.
$X_{5}(p)^{4}=\left\{\left(p_{1}+1, p_{2}-1, p_{3}+1, p_{4}+1, p_{5}-1\right),\left(p_{1}-1, p_{2}+1, p_{3}-1, p_{4}-\right.\right.$ $\left.\left.1, p_{5}-1\right), \cdots,\left(p_{1}-1, p_{2}-1, p_{3}-1, p_{4}-1, p_{5}+1\right)\right\}$ with $\sharp X_{5}(p)^{4}=C_{4}^{5}$.

Finally,
$X_{5}(p)^{5}=\left\{\left(p_{1}-1, p_{2}-1, p_{3}-1, p_{4}-1, p_{5}-1\right)\right\}$ with $\sharp X_{5}(p)^{5}=C_{5}^{5}$.
Then $X_{5}(p)^{i}$ and $X_{5}(p)^{j}$ are disjoint for $i \neq j \in\{0,1,2,3,4,5\}$.
Thus we get $\sharp X_{5}(p)=\sum_{i=0}^{5} C_{i}^{5}$.
Consequently, $\sharp\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q) \leq 4, d_{*}(p, q)=1\right\}$
$=\sharp\left(N_{242}(p)-X_{5}(p)\right)=242-\left(C_{0}^{5}+C_{1}^{5}+C_{2}^{5}+\cdots+C_{5}^{5}\right)=210$.
$(3)^{\prime} N_{130}(p)=\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q) \leq 3, d_{*}(p, q)=1\right\}$
$=N_{210}(p)-X_{4}(p)$ from $(3)$ above, where $X_{4}(p)=\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q)=\right.$ $\left.4, d_{*}(p, q) 1\right\}$.

Actually, $X_{4}(p)=\left\{\left(p_{i-2} \pm 1, p_{i-1} \pm 1, p_{i}, p_{i+1} \pm 1, p_{i+2} \pm 1\right)\right\}(i \in\{1,2,3,4,5\})$
$=\cup_{i=0}^{4} X_{4}(p)^{i}$ via the following notations:
$X_{4}(p)^{0}=\left\{\left(p_{j-1}+1, p_{j}+1, p_{j+1}+1, p_{i}, p_{i+1}+1\right) \mid i \neq j \in[1,5]_{\mathbb{Z}}\right\}$ with $\sharp X_{4}(p)^{0}=C_{0}^{4}$.
$X_{4}(p)^{1}=\left\{\left(p_{j-1}+1, p_{j}-1, p_{i-1}+1, p_{i}, p_{i+1}+1\right) \mid i \neq j \in[1,5]_{\mathbb{Z}}\right\}$, i.e., $X_{4}(p)^{1}$ consists of the elements which have the coordinates with only one $p_{j}-1,1 \leq$ $j(\neq i) \leq 5$, and the others are $p_{k}+1,1 \leq k \leq 5, i \neq j \neq k$, except $p_{i}$ with $\sharp X_{4}(p)^{1}=C_{1}^{4}$.
...,
Finally,
$X_{4}(p)^{4}=\left\{\left(p_{i-2}-1, p_{i-1}-1, p_{i}, p_{i+1}-1, p_{i+2}-1\right)\right\}$ with $\sharp X_{4}(p)^{4}=C_{4}^{4}$.
Then $X_{4}(p)^{i}$ and $X_{4}(p)^{j}$ are disjoint for $i \neq j \in\{0,1,2,3,4\}$.
Therefore $\sharp X_{4}(p)=C_{1}^{5}\left(C_{0}^{4}+C_{1}^{4}+C_{2}^{4}+C_{3}^{4}+C_{4}^{4}\right)$.
Thus we get the following:
$\sharp\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q) \leq 3, d_{*}(p, q)=1\right\}=\sharp\left(N_{210}(p)-X_{4}(p)\right)$
$=210-C_{1}^{5}\left(C_{0}^{4}+C_{1}^{4}+C_{2}^{4}+C_{3}^{4}+C_{4}^{4}\right)=130$. Similarly,
$(4)^{\prime} N_{50}(p)=N_{130}(p)-X_{3}(p)=\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q) \leq 2, d_{*}(p, q)=1\right\}$ from (4) above,
where $X_{3}(p)=\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q)=3, d_{*}(p, q)=1\right\}$

$$
=\left\{\left(p_{i-1} \pm 1, p_{i}, p_{i+1} \pm 1, p_{j}, p_{j+1} \pm 1\right)\right\}=\cup_{i=0}^{3} X_{3}(p)^{i}
$$

By the same method above, we get
$\sharp X_{3}(p)=C_{2}^{5}\left(C_{0}^{3}+C_{1}^{3}+C_{2}^{3}+C_{3}^{3}\right)=50$.
(5) ${ }^{\prime} N_{10}(p)=\left\{q \in \mathbb{Z}^{5} \mid d_{5}(p, q) \leq 1\right\}$ from (5) above such that $\sharp N_{10}(p)=10$.

At last, 5 kinds of $k$-adjacency relations in $\mathbb{Z}^{5}$ are obtained from the above formulas (1) ${ }^{\prime} \sim(5)^{\prime}$ :

We now say that $p$ and $q$ are called $k$-adjacent if $q \in N_{k}(p)$ in $\mathbb{Z}^{5}$, where $k \in\{242,210,130,50,10\}$.

Similarly, by the same method above, we get 4 kinds of $k$ - adjacency relations in $\mathbb{Z}^{4}$ are followed. Namely, for two 4 -xels $p=\left(p_{1}, p_{2}, p_{3}, p_{4}\right), q=\left(q_{1}, q_{2}, q_{3}, q_{4}\right) \in$ $\mathbb{Z}^{4}$, the following equations are considered,
(6) $d_{4}(p, q)=4, d_{*}(p, q)=1 \Rightarrow$ then $p$ shares a point with $q$,
(7) $d_{4}(p, q)=3, d_{*}(p, q)=1 \Rightarrow$ then $p$ shares an edge with $q$,
(8) $d_{4}(p, q)=2, d_{*}(p, q)=1 \Rightarrow$ then $p$ shares a face with $q$,
(9) $d_{4}(p, q)=1, d_{*}(p, q)=1 \Rightarrow$ then $p$ shares a cube with $q$.

From $(6) \sim(9)$ above, the following equations are taken by the same method as $\mathbb{Z}^{5}$.

We now say that $p$ and $q$ are called $k$-adjacent if $q \in N_{k}(p)$ in $\mathbb{Z}^{4}$, where $k \in\{80,64,32,8\}$.

Consequently, we get the following:
1 Proposition. There are 4 kinds of $k$-adjacency relations in $\mathbb{Z}^{4}, k \in\{80$, $64,32,8\}$ and 5 kinds of $k$-adjacency relations in $\mathbb{Z}^{5}, k \in\{242,210,130,50,10\}$.

Thus in $\mathbb{Z}^{4}$, the digital pictures $\left(\mathbb{Z}^{4}, k, \bar{k}, X\right)$ are considered for the following cases: $(k, \bar{k}) \in\{(80,8),(8,80),(64,8),(8,64),(32,8),(8,32)\}$.

Furthermore, in $\mathbb{Z}^{5}$, the digital pictures $\left(\mathbb{Z}^{5}, k, \bar{k}, X\right)$ are obtained for the following cases as follows: $(k, \bar{k}) \in\{(242,10),(10,242),(210,10),(10,210),(130,10)$, $(10,130),(50,10),(10,50)\}$.

For a digital image $X\left(\subset \mathbb{Z}^{n}\right)$, two points $x(\neq) y(\in X)$ are called $k$-connected $[1,6]$ if there is a $k$-path $f:[0, m]_{\mathbb{Z}} \rightarrow X$ where the image is a sequence $\left(x_{0}, x_{1}, \ldots, x_{m}\right)$ from the set of points $\left\{f(0)=x_{0}=x, f(1)=x_{1}, \ldots, f(m)=\right.$ $\left.x_{m}=y\right\}$ such that $x_{i}$ and $x_{i+1}$ are $k$-adjacent, $i \in\{0,1, \ldots, m-1\}, m \geq 1[1,10]$.

And a simple closed $k$-curve is considered as a sequence $\left(x_{0}, x_{1}, \ldots, x_{m}\right)$ of the $k$-path where $x_{i}$ and $x_{j}$ are $k$-adjacent if and only if $j=i+1(\bmod m)$ or $i=j-1(\bmod m)[1,3]$.

## 2 Digital ( $k_{0}, k_{1}$ )-homotopy

On the basis of the digital continuity and the digital $\left(k_{0}, k_{1}\right)$-continuity [ 1 , 10], the convenient digital $\left(k_{0}, k_{1}\right)$-continuity in terms of the digital $k$-connectedness was introduced in [2]. But for the study of pointed digital homotopy
theory, we need some reformations. Furthermore, the former digital $\left(k_{0}, k_{1}\right)$ continuity with the standard $k_{i}$-adjacency relations will be generalized to the digital $\left(k_{0}, k_{1}\right)$-continuity with the $n$ types of $k_{i}$-adjacency relations in $\mathbb{Z}^{n}$, $i \in\{0,1\}, n \in\{4,5\}$.

Now we define a digital $\left(k_{0}, k_{1}\right)$-continuity as a generalization of the digital $\left(k_{0}, k_{1}\right)$-continuity of [2]; such an approach is essential in studying the pointed digital $\left(k_{0}, k_{1}\right)$-homotopy theory [2].

2 Definition. For two digital pictures $\left(\mathbb{Z}^{n_{0}}, k_{0}, \bar{k}_{0}, X\right)$ and $\left(\mathbb{Z}^{n_{1}}, k_{1}, \bar{k}_{1}, Y\right)$, we say that a map $f: X \rightarrow Y$ is digitally $\left(k_{0}, k_{1}\right)$-continuous at the point $x \in X$ if for every $k_{0}$-connected subset $O_{k_{0}}(x)$ containing $x, f\left(O_{k_{0}}(x)\right)$ is $k_{1}$-connected, where $k_{i} \in\{242,210,130,50,10\}$ in $\mathbb{Z}^{5}, k_{i} \in\{80,64,32,8\}$ in $\mathbb{Z}^{4}, k_{i} \in\{26,18,6\}$ in $\mathbb{Z}^{3}, k_{i} \in\{8,4\}$ in $\mathbb{Z}^{2}$ and so on.

If $f$ is digitally $\left(k_{0}, k_{1}\right)$-continuous at any point $x \in X$ then $f$ is called a digitally $\left(k_{0}, k_{1}\right)$-continuous map.

From now on, all spaces are considered under the following $k_{i}$-adjacency relations,
$k_{i} \in\{242,210,130,50,10\}$ in $\mathbb{Z}^{5}, k_{i} \in\{80,64,32,8\}$ in $\mathbb{Z}^{4}, k_{i} \in\{26,18,6\}$ in $\mathbb{Z}^{3}, k_{i} \in\{8,4\}$ in $\mathbb{Z}^{2}$ and so on.

For two digital pictures $\left(\mathbb{Z}^{n_{0}}, k_{0}, \bar{k}_{0},(X, A)\right)$ and $\left(\mathbb{Z}^{n_{1}}, k_{1}, \bar{k}_{1},(Y, B)\right)$, we say that a map $f:(X, A) \rightarrow(Y, B)$ is digitally $\left(k_{0}, k_{1}\right)$-continuous if $f: X \rightarrow Y$ is digitally $\left(k_{0}, k_{1}\right)$-continuous and $f(A) \subset B$, respectively.

In $[1,2]$, the digital homotopy was introduced. Now we define the generalized digital $\left(k_{0}, k_{1}\right)$-homotopy.

For digital pictures $\left(\mathbb{Z}^{n_{0}}, k_{0}, \bar{k}_{0}, X\right)$ and $\left(\mathbb{Z}^{n_{1}}, k_{1}, \bar{k}_{1}, Y\right)$, let $f, g: X \rightarrow Y$ be digitally $\left(k_{0}, k_{1}\right)$-continuous functions. And suppose that there are a positive integer $m$ and a function, $F: X \times[0, m]_{\mathbb{Z}} \rightarrow Y$ such that

- for all $x \in X, F(x, 0)=f(x)$ and $F(x, m)=g(x)$,
- for all $x \in X$, the induced map $F_{x}:[0, m]_{\mathbb{Z}} \rightarrow Y$ defined by $F_{x}(t)=F(x, t)$ for all $t \in[0, m]_{\mathbb{Z}}$ is digitally $\left(2, k_{1}\right)$-continuous, and
- for all $t \in[0, m]_{\mathbb{Z}}$, the induced map $F_{t}$ which is defined by $F_{t}(x)=F(x, t)$ : $X \rightarrow Y$ is digitally $\left(k_{0}, k_{1}\right)$-continuous for all $x \in X$.

If, further, $F\left(x_{0}, t\right)=y_{0}$ for some $\left(x_{0}, y_{0}\right) \in X \times Y$ and all $t \in[0, m]_{\mathbb{Z}}$, we say $F$ is a pointed $\left(k_{0}, k_{1}\right)$-homotopy.

If $X=\left[0, m_{X}\right]_{\mathbb{Z}}$ and for all $t \in[0, m]_{\mathbb{Z}}$ we have $F(0, t)=F(0,0)$ and $F\left(m_{X}, t\right)=F\left(m_{X}, 0\right)$, we say $F$ holds the endpoints fixed.

We say an image $X$ is $k$-contractible [2] if the identity map $1_{X}$ is $(k, k)$ homotopic in $X$ to a constant map with image consisting of some $x_{0} \in X$. If such a homotopy is a pointed homotopy, we say $\left(X, x_{0}\right)$ is pointed $k$-contractible.

We say that $f$ and $g$ are digitally pointed homotopic and then we use a notation $f \simeq_{d \cdot\left(k_{0}, k_{1}\right) \cdot h} g$.

Especially, for the case of the digital pointed $(k, k)$-homotopy, we call it a digital pointed $k$-homotopy and use the notation: $f \simeq_{d \cdot k \cdot h} g$ instead of $f \simeq_{d \cdot(k, k) \cdot h} g$.

For the digital image $X$ with a $k$-adjacency and its subimage $A$, we call $(X, A)$ a digital image pair with a $k$-adjacency. Furthermore, if $A$ is a singleton set $\{p\}$ then $(X, p)$ is called a pointed digital image.

For a digital image ( $X, A$ ) with a $k$-adjacency, we say that $X$ is $k$-deformable into $A$ if there is a digital pointed $k$-homotopy $D: X \times[0, m]_{\mathbb{Z}} \rightarrow X$ such that $D(x, 0)=x$ and $D(x, m) \subset A, x \in X$. The above digital pointed $k$-homotopy is called a digital $k$-deformation. The current pointed $k$-homotopy means that $D\left(x_{0}, t\right)=x_{0}$ for $x_{0} \in A$ and all $t \in[0, m]_{\mathbb{Z}}$.

Actually, the digital fundamental group was developed for the digital image in dimension at most three image in $\mathbb{Z}^{3}[6]$ and was derived from an approach to algebraic topology under the standard $k$-adjacency in $\mathbb{Z}^{n}$, where $k \in\left\{3^{n}-1(n \geq\right.$ $2), 2 n(n \geq 1), 18(n=3)\}[5]$.

Now we make a reformation in terms of the generalized pointed digital homotopy without any restriction to the dimension and the $k$-adjacency of the image. The $k$-type digital fundamental group is induced via the generalized pointed $k$-homotopy. Namely, we study the image in $\mathbb{Z}^{n}$ with the $n$-kinds of the $k$-adjacency in $\mathbb{Z}^{n}, k \in\{242,210,130,50,10\}$ in $\mathbb{Z}^{5}, k \in\{80,64,32,8\}$ in $\mathbb{Z}^{4}$, $k \in\{26,18,6\}$ in $\mathbb{Z}^{3}, k \in\{8,4\}$ in $\mathbb{Z}^{2}$ and $k \in\left\{3^{n}-1(n \geq 2), 2 n(n \geq 1)\right\}$ in $\mathbb{Z}^{n}, n \geq 6$.

Since the preservation of the base point is essential in studying the pointed digital ( $k_{0}, k_{1}$ )-homotopy theory, the digital ( $k_{0}, k_{1}$ )-continuity is very meaningful.

Thus the $k$-type digital fundamental group is a generalization of the digital fundamental group of $[2,5,6]$ relative to the adjacency and the dimension of the image.

Concretely, for a pointed digital image $(X, p)$, a $k$-loop $f$ based at $p$ is a $k$-path in $X$ with $f(0)=p=f(m)$. And we put $F_{1}^{k}(X, p)=\{f \mid f$ is a $k$-loop based at $p\}$.

For maps $f, g\left(\in F_{1}^{k}(X, p)\right)$, i.e., $f:\left[0, m_{1}\right]_{\mathbb{Z}} \rightarrow(X, p)$ with $f(0)=p=f\left(m_{1}\right)$ and $g:\left[0, m_{2}\right]_{\mathbb{Z}} \rightarrow(X, p)$ with $g(0)=p=g\left(m_{2}\right)$, we get a map $f * g:\left[0, m_{1}+\right.$ $\left.m_{2}\right]_{\mathbb{Z}} \rightarrow(X, p)$ as follows [5]:
$f * g:\left[0, m_{1}+m_{2}\right]_{\mathbb{Z}} \rightarrow(X, p)$ is defined by $f * g(t) f(t),\left(0 \leq t \leq m_{1}\right)$ and $g\left(t-m_{1}\right),\left(m_{1} \leq t \leq m_{1}+m_{2}\right)$. Then $f * g \in F_{1}^{k}(X, p)$.

We denote the digital $k$-homotopy class of $f$ by $[f]$. Obviously, the homotopy class $[f * g]$ depends on the homotopy classes $[f]$ and $[g]$.

Furthermore, for any $f_{1}, f_{2}, g_{1}, g_{2} \in F_{1}^{k}(X, p)$ such that $f_{1} \in\left[f_{2}\right], g_{1} \in\left[g_{2}\right]$
we get the map $f_{1} * g_{1} \in\left[f_{2} * g_{2}\right]$, i.e., $\left[f_{1} * g_{1}\right]=\left[f_{2} * g_{2}\right]$.
Consequently, we put $\pi_{1}^{k}(X, p)=\left\{[f] \mid f \in F_{1}^{k}(X, p)\right\}$. And we take an operation $\cdot$ on $\pi_{1}^{k}(X, p)$ as follows: $[f] \cdot[g]=[f * g]$.

The group structure on $\pi_{1}^{k}(X, p)$ is checked by the same method as in [1] with respect to the digital $(2, k)$-continuity.

For our emphasizing on the $k$-connectivity of the digital image $X$, we use the superscript $k$ like $\pi_{1}^{k}(X, p)$.

Consequently, we get a group $\pi_{1}^{k}(X, p)$ with the above operation $\cdot$, which is called the $k$-type digital fundamental group of a pointed digital image ( $X, p$ ).

Actually, if $p$ and $q$ belong to the same $k$-connected component of $X$, then $\pi_{1}^{k}(X, p)$ is isomorphic to $\pi_{1}^{k}(X, q)$ [1].

For digital pictures $\left(\mathbb{Z}^{n_{0}}, k_{0}, \bar{k}_{0}, X\right)$, $\left(\mathbb{Z}^{n_{1}}, k_{1}, \bar{k}_{1}, Y\right)$ and a digitally $\left(k_{0}, k_{1}\right)$ continuous based map $h:(X, p) \rightarrow(Y, q)$, the map $h$ induces a digital fundamental group $\left(k_{0}, k_{1}\right)$-homomorphism as follows.

Define $\pi_{1}^{\left(k_{0}, k_{1}\right)}(h)=h_{*}: \pi_{1}^{k_{0}}(X, p) \rightarrow \pi_{1}^{k_{1}}(Y, q)$ by the equation $h_{*}\left(\left[f_{1}\right]\right)=$ $\left[h \circ f_{1}\right]$, where $\left[f_{1}\right] \in \pi_{1}^{k_{0}}(X, p)$, which is well defined. Particularly, if $k_{0}=k_{1}$, we use the following notation, $\pi_{1}^{k_{0}}(h)[1]$.

For digital pictures $\left(\mathbb{Z}^{n_{0}}, k_{0}, \bar{k}_{0}, X\right)$, $\left(\mathbb{Z}^{n_{1}}, k_{1}, \bar{k}_{1}, Y\right)$ and $\left(\mathbb{Z}^{n_{2}}, k_{2}, \bar{k}_{2}, Z\right)$, let $f: X \rightarrow Y$ be digitally $\left(k_{0}, k_{1}\right)$-continuous based map and $g: Y \rightarrow Z$ be digitally $\left(k_{1}, k_{2}\right)$-continuous function. Then obviously $\pi_{1}^{\left(k_{0}, k_{2}\right)}(g \circ f)=\pi_{1}^{\left(k_{1}, k_{2}\right)}(g) \circ$ $\pi_{1}^{\left(k_{0}, k_{1}\right)}(f)[1]$. In particular, if $k_{0}=k_{1}=k_{2}, \pi_{1}^{k_{0}}(g \circ f)=\pi_{1}^{k_{0}}(g) \circ \pi_{1}^{k_{0}}(f)$. Actually, if a pointed image $(X, p)$ is $k$-connected, for any point $q \in X$ there is an isomorphism $\phi: \pi_{1}^{k}(X, p) \cong \pi_{1}^{k}(X, q)[1]$.

3 Theorem. For a digital image picture $\left(\mathbb{Z}^{n}, k, \bar{k},(X, A)\right)$, if $(X, p)$ is $k$ deformable into $(A, p)$ then $\pi_{1}^{k}(X, p) \cong \pi_{1}^{k}(A, p)$.

Proof. First, from the digital $k$-deformation $D: X \times[0, m]_{\mathbb{Z}} \rightarrow X$ such that $D(X \times\{m\}) \subset A$, let $r:(X, p) \rightarrow(A, p)$ be defined as follows: $(i \circ r)(x)=$ $D(x, m), x \in X$ and $i:(A, p) \rightarrow(X, p)$ is the inclusion map. Then $D$ makes $1_{(X, p)}$ be digitally pointed $k$-homotopic to $i \circ r$. And further, $D\left(x_{0}, t\right)=x_{0}$ for some $x_{0} \in A$. Thus $r$ is a right digital $k$-homotopy inverse of $i$. Namely, $i \circ r \simeq_{d \cdot k \cdot h} 1_{(X, p)}$. Therefore $\pi_{1}^{k}(i \circ r)=\pi_{1}^{k}(i) \circ \pi_{1}^{k}(r)=1_{\pi_{1}^{k}(X, p)}$. Thus $\pi_{1}^{k}(r)$ is a monomorphism.

Second, for any $[g] \in \pi_{1}^{k}(A, p)$, there are a $k$-path $f \in F_{1}^{k}(X, p)$ and a set of $k$-paths $\left\{g_{1}, g_{2}, \cdots, g_{c}\right\} \subset F_{1}^{k}(X, p)$, such that $f \simeq_{d \cdot k \cdot h} g_{1}, g_{i} \simeq_{d \cdot k \cdot h} g_{i+1}$ for $i \in\{1,2, \cdots, c-1\}$ and $g_{c} \simeq_{d \cdot k \cdot h} g$. Thus $\pi_{1}^{k}(r)([f])=[g]$. Therefore $\pi_{1}^{k}(r)$ is an epimorphism.

4 Corollary. [1] If $X$ is pointed $k$-contractible then $\pi_{1}^{k}(X, p)$ is trivial.

## 3 Digital ( $k_{0}, k_{1}$ )-homeomorphism

For our classification of digital images, we need special relations among digital images with $k_{i}$-adjacencies $i \in\{0,1\}$. One of them is the digital $\left(k_{0}, k_{1}\right)$ homeomorphism as follows:

5 Definition. [1, 3, 4] For digital pictures ( $\mathbb{Z}^{n_{0}}, k_{0}, \bar{k}_{0}, X$ ) and ( $\mathbb{Z}^{n_{1}}, k_{1}, \bar{k}_{1}$, $Y)$, a map $h: X \rightarrow Y$ is called a digital $\left(k_{0}, k_{1}\right)$-homeomorphism if $h$ is digitally $\left(k_{0}, k_{1}\right)$-continuous and bijective and further $h^{-1}: Y \rightarrow X$ is digitally $\left(k_{1}, k_{0}\right)$ continuous. Then we write it by $X \approx_{d \cdot\left(k_{0}, k_{1}\right) \cdot h} Y$. If $k_{0}=k_{1}$, we say that $h$ is a digital homeomorphism [1].

The minimal simple closed curves in $\mathbb{Z}^{2}$ with three types which are not digital homeomorphic to each other are $M S C_{8}, M S C_{4}$ and $M S C_{8}^{\prime}\left(\subset \mathbb{Z}^{2}\right)[3,4]$.

Let $M S C_{8}$ be the set which is digitally 8 -homeomorphic to the image [4],
$\left\{\left(x_{1}, y_{1}\right),\left(x_{1}-1, y_{1}+1\right),\left(x_{1}-2, y_{1}\right),\left(x_{1}-2, y_{1}-1\right),\left(x_{1}-1, y_{1}-2\right),\left(x_{1}, y_{1}-1\right)\right\}$.
Let $M S C_{4}$ be the set which is digitally 4-homeomorphic to the image,

$$
\begin{aligned}
&\left\{\left(x_{1}, y_{1}\right),\left(x_{1}, y_{1}+1\right),\left(x_{1}-1, y_{1}+1\right),\left(x_{1}-2, y_{1}+1\right)\right. \\
&\left.\left(x_{1}-2, y_{1}\right),\left(x_{1}-2, y_{1}-1\right),\left(x_{1}-1, y_{1}-1\right),\left(x_{1}, y_{1}-1\right)\right\},
\end{aligned}
$$

i.e., $M S C_{4} \approx_{d \cdot 4 \cdot h} N_{8}\left(p_{3}\right), p_{3} \in \mathbb{Z}^{2}[3,4]$.

Let $M S C_{8}^{\prime}$ be the set which is digitally 8 -homeomorphic to the image,

$$
\left\{\left(x_{1}, y_{1}\right),\left(x_{1}-1, y_{1}+1\right),\left(x_{1}-2, y_{1}\right),\left(x_{1}-1, y_{1}-1\right)\right\}
$$

[1, 3].
We can classify digital images from the following induced digital fundamental group ( $k_{0}, k_{1}$ )- isomorphism.

6 Theorem. Let $\left(\mathbb{Z}^{n_{0}}, k_{0}, \bar{k}_{0},\left(X, x_{0}\right)\right)$ and $\left(\mathbb{Z}^{n_{1}}, k_{1}, \bar{k}_{1},\left(Y, y_{0}\right)\right)$ be digital pictures, where $k_{i} \in\{242,210,130,50,10\}$ in $\mathbb{Z}^{5}, k_{i} \in\{80,64,32,8\}$ in $\mathbb{Z}^{4}, k_{i} \in$ $\{26,18,6\}$ in $\mathbb{Z}^{3}, k_{i} \in\{8,4\}$ in $\mathbb{Z}^{2}$ and $k_{i} \in\left\{3^{n}-1,2 n\right\}$ in $\mathbb{Z}^{n}, n \geq 6, i \in\{0,1\}$. If $h:\left(X, x_{0}\right) \rightarrow\left(Y, y_{0}\right)$ is a digital $\left(k_{0}, k_{1}\right)$-homeomorphism then the induced map $h_{*}: \pi_{1}^{k_{0}}(X, p) \rightarrow \pi_{1}^{k_{1}}(Y, q)$ defined by $h_{*}([f])=[h \circ f],[f] \in \pi_{1}^{k_{0}}(X, p)$ is a digital fundamental group isomorphism.

Proof. First, $h_{*}$ is well-defined. If $f^{\prime} \in[f] \in \pi_{1}^{k_{0}}(X, p)$, let $F:(X, p) \times$ $[0, m]_{\mathbb{Z}} \rightarrow(X, p)$ be a digital $k_{0}$-homotopy between $f$ and $f^{\prime}$. Then $h \circ F$ is a digital $k_{1}$-homotopy between the $k_{1}$-loops $h \circ f$ and $h \circ f^{\prime}$. Thus $h \circ f^{\prime} \in[h \circ f]$.

Second, the induced map $h_{*}$ is a homomorphism.
For any maps $f, g \in F_{1}^{k_{0}}(X, p)$, the digitally $\left(2, k_{0}\right)$-continuous maps $f$ : $\left[0, m_{1}\right]_{\mathbb{Z}} \rightarrow(X, p)$ and $g:\left[0, m_{2}\right]_{\mathbb{Z}} \rightarrow(X, p)$, the map $h \circ(f * g):\left[0, m_{1}+m_{2}\right]_{\mathbb{Z}} \rightarrow$
$(Y, q)$ is defined as follows:

$$
\begin{aligned}
h \circ(f * g):\left[0, m_{1}+m_{2}\right]_{\mathbb{Z}} & \rightarrow(Y, q) \\
h \circ(f * g)(t) & = \begin{cases}h(f(t)), & \left(0 \leq t \leq m_{1}\right), \\
h\left(g\left(t-m_{1}\right)\right), & \left(m_{1} \leq t \leq m_{1}+m_{2}\right)\end{cases}
\end{aligned}
$$

Thus $h \circ(f * g)=(h \circ f) *(h \circ g)$ and $h_{*}([f] \cdot[g])=h_{*}([f * g])=[h \circ(f *$ $g)][(h \circ f) *(h \circ g)]=[h \circ f] \cdot[h \circ g]=h_{*}([f]) \cdot h_{*}([g])$.

The induced map $h_{*}$ depends not only on the digitally $\left(k_{0}, k_{1}\right)$-continuous map $h:(X, p) \rightarrow(Y, q)$ but also on the choice of the base points $p$ and $q$.

Second, $h_{*}$ is surjective: for any $[g] \in \pi_{1}^{k_{1}}(Y, q)$, we get $g:[0, m]_{\mathbb{Z}} \rightarrow(Y, q)$ is a digitally $\left(2, k_{1}\right)$-continuous map such that $g(0)=q=g(m)$. Because $h$ is a digital $\left(k_{0}, k_{1}\right)$-homeomorphism, there is a digitally $\left(2, k_{0}\right)$-continuous map: $f_{1}:[0, m]_{\mathbb{Z}} \rightarrow(X, p)$ such that $f_{1}(0)=p=f_{1}(m)$ and $h \circ f_{1}=g$. Thus $h_{*}\left(\left[f_{1}\right]\right)=\left[h \circ f_{1}\right]=[g]$.

Third, $h_{*}$ is injective: if $h_{*}\left(\left[f_{1}\right]\right)=\left[h \circ f_{1}\right]=c_{\{q\}} \in \pi_{1}^{k_{1}}(Y, q)$, we only prove that $f_{1} \simeq_{d \cdot k_{0} \cdot h} c_{\{p\}}$. Since $h \circ f_{1} \simeq_{d \cdot k_{1} \cdot h} c_{\{q\}}$, there is a digitally $\left(2, k_{0}\right)$-continuous map $f_{1}:[0, m]_{\mathbb{Z}} \rightarrow(X, p)$ such that $f_{1}(0)=p=f_{1}(m)$ and $f_{1} \simeq_{d \cdot k_{0} \cdot h} c_{\{p\}}$.

Fourth, $h_{*}$ is a homomorphism. For any $\left[f_{1}\right],\left[f_{2}\right] \in \pi_{1}^{k_{0}}(X, p), h_{*}\left(\left[f_{1}\right] \cdot\left[f_{2}\right]\right)=$ $h_{*}\left[f_{1} * f_{2}\right]=\left[h \circ\left(\left[f_{1} * f_{2}\right]\right)\right]=\left[\left(h \circ f_{1} * h \circ f_{2}\right)\right]=\left[\left(h \circ f_{1}\right] \cdot\left[h \circ f_{2}\right] h_{*}\left[f_{1}\right] \cdot h_{*}\left[f_{2}\right] . \quad\right.$ QED

A black point in a digital picture $P=\left(\mathbb{Z}^{n}, k, \bar{k}, X\right)$ is called a border point if it is $k$-adjacent to one or more white points. The border of $X$ in the above digital picture $P$ is the set of all border points and it is denoted by $\operatorname{Bd}(X)$.

7 Example. The group $\pi_{1}^{4}\left(M S C_{4}, x_{0}\right) \simeq \pi_{1}^{8}\left(B d\left(B_{2}(p, 2)\right)\right)$.
Proof. Since $B d\left(B_{2}(p, 2)\right)$ is ( 8,4 )-homeomorphic to $M S C_{4}$, the proof is completed.

QED
8 Example. For the image $W_{1}=B_{2}\left(p_{1}, 2\right)-\left\{p_{1},\left(x_{1}+1, y_{1}\right)\right\} \cup N_{8}\left(p_{3}\right)$, where $p_{1}=\left(x_{1}, y_{1}\right), p_{2}=\left(x_{1}+2, y_{1}\right)$ and $p_{3}=\left(x_{1}+3, y_{1}\right), \pi_{1}^{8}\left(W_{1}, p_{2}\right) \cong$ $\pi_{1}^{8}\left(M S C_{8}\right)$. Assume that $N_{8}\left(p_{3}\right)=\left\{q_{0}=\left(x_{1}+4, y_{1}\right), q_{1}=\left(x_{1}+4, y_{1}+1\right), q_{2}=\right.$ $\left(x_{1}+3, y_{1}+1\right), q_{3}=\left(x_{1}+2, y_{1}+1\right), q_{4}=\left(x_{1}+2, y_{1}\right), q_{5}=\left(x_{1}+2, y_{1}-1\right), q_{6}=$ $\left.\left(x_{1}+3, y_{1}-1\right), q_{6}=\left(x_{1}+4, y_{1}-1\right)\right\}$.

Proof. (Step 1): Without loss of generality, assume that $M \mathrm{SC}_{8}$ is a subset of $B_{2}\left(p_{1}, 2\right)-\left\{p_{1},\left(x_{1}+1, y_{1}\right)\right\}$. We get easily $B_{2}\left(p_{1}, 2\right)-\left\{p_{1},\left(x_{1}+1, y_{1}\right)\right\}$ is 8-deformable into $W_{2}\left(\approx_{d \cdot 8 \cdot h} M S C_{8}\right)$, where $W_{2}=\left\{\left(x_{1}+2, y_{1}\right),\left(x_{1}+1, y_{1}+\right.\right.$ 1), $\left.\left(x_{1}, y_{1}+1\right),\left(x_{1}-1, y_{1}\right),\left(x_{1}, y_{1}-1\right),\left(x_{1}+1, y_{1}-1\right)\right\}$.
(Step 2): We prove that $N_{8}\left(p_{3}\right)$ is pointed 8 -contractible into $\left\{p_{2}\right\}$. Namely, there is a digital 8-homotopy $H: N_{8}\left(p_{3}\right) \times[0,3]_{\mathbb{Z}} \rightarrow N_{8}\left(p_{3}\right)$ as follows:

First, $H\left(q_{i}, 0\right)=q_{i}$, for any $q_{i} \in N_{8}\left(p_{3}\right)$.
Second, $H\left(q_{2 i+1}, 1\right)=q_{2 i}, H\left(q_{2 i}, 1\right)=q_{2 i}, i \in[0,3]_{\mathbb{Z}}$,

Third, $H\left(q_{i}, 2\right)=q_{4}, i \in\{2,3,4,5\}$ and $H\left(q_{j}, 2\right)=q_{6}, j \in\{0,1,6,7\}$.
Finally $H\left(q_{i}, 3\right)=q_{4}, i \in[0,7]_{\mathbb{Z}}$.
Therefore $\pi_{1}^{8}\left(W_{1}, p_{2}\right) \cong \pi_{1}^{8}\left(M S C_{8}\right)$ from (Step 1) and (Step 2).
9 Corollary. If there are $k_{0}, k_{1}$ such that $\pi_{1}^{k_{0}}(X, p)$ is not isomorphic to $\pi_{1}^{k_{1}}(Y, q)$ then $X$ and $Y$ are not digitally $\left(k_{0}, k_{1}\right)$-homeomorphic to each other.

Proof. A digital $\left(k_{0}, k_{1}\right)$-continuous map $h:(X, p) \rightarrow(Y, q)$ induces a digital fundamental group homomorphism $h_{*}: \pi_{1}^{k_{0}}(X, p) \rightarrow \pi_{1}^{k_{1}}(Y, q)$ defined by $h_{*}([f])=[h \circ f]$. It is easy to see that $h_{*}$ and $h_{*}^{-1}$ are bijective homomorphisms. Thus a digital $\left(k_{0}, k_{1}\right)$-homeomorphism $h:(X, p) \rightarrow(Y, q)$ induces a digital fundamental group isomorphism. By the contraposition of the above statement we get the proof.

QED

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