# On Norden-Walker 4-manifolds 

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#### Abstract

A Walker 4-manifold is a semi-Riemannian manifold ( $M_{4}, g$ ) of neutral signature, which admits a field of parallel null 2-plane. The main purpose of the present paper is to study almost Norden structures on 4-dimensional Walker manifolds with respect to a proper and opposite almost complex structures. We discuss sequently the problem of integrability, Kähler (holomorphic), isotropic Kähler and quasi-Kähler conditions for these structures. The curvature properties for Norden-Walker metrics is also investigated. Also, we give counterexamples to Goldberg's conjecture in the case of neutral signature.


Keywords: Walker 4-manifolds, Proper almost complex structure, Opposite almost complex structure, Norden metrics, Holomorphic metrics, Goldberg conjecture

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## 1 Introduction

Let $M_{2 n}$ be a Riemannian manifold with neutral metric, i.e., with pseudo-Riemannian metric $g$ of signature $(n, n)$. We denote by $\Im_{q}^{p}\left(M_{2 n}\right)$ the set of all tensor fields of type $(p, q)$ on $M_{2 n}$. Manifolds, tensor fields and connections are always assumed to be differentiable and of class $C^{\infty}$.

Let $\left(M_{2 n}, \varphi\right)$ be an almost complex manifold with almost complex structure $\varphi$. Such a structure is said to be integrable if the matrix $\varphi=\left(\varphi_{j}^{i}\right)$ is reduced to constant form in a certain holonomic natural frame in a neighborhood $U_{x}$ of every point $x \in M_{2 n}$. In order that an almost complex structure $\varphi$ be integrable, it is necessary and sufficient that there exists a torsion-free affine connection $\nabla$ with respect to which the structure tensor $\varphi$ is covariantly constant, i.e., $\nabla \varphi=0$. It is also know that the integrability of $\varphi$ is equivalent to the vanishing

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of the Nijenhuis tensor $N_{\varphi} \in \Im_{2}^{1}\left(M_{2 n}\right)$. If $\varphi$ is integrable, then $\varphi$ is a complex structure and, moreover, $M_{2 n}$ is a $C$-holomorphic manifold $X_{n}(C)$ whose transition functions are holomorphic mappings.

### 1.1 Norden metrics

A metric $g$ is a Norden metric [18] if

$$
g(\varphi X, \varphi Y)=-g(X, Y)
$$

or equivalently

$$
g(\varphi X, Y)=g(X, \varphi Y)
$$

for any $X, Y \in \Im_{0}^{1}\left(M_{2 n}\right)$. Metrics of this type have also been studied under the other names: pure metrics, anti-Hermitian metrics and B-metrics (see [5], [6], [10], [17], [19], [23], [25]). If $\left(M_{2 n}, \varphi\right)$ is an almost complex manifold with Norden metric $g$, we say that $\left(M_{2 n}, \varphi, g\right)$ is an almost Norden manifold. If $\varphi$ is integrable, we say that $\left(M_{2 n}, \varphi, g\right)$ is a Norden manifold.

### 1.2 Holomorphic (almost holomorphic) tensor fields

Let $\stackrel{*}{t}$ be a complex tensor field on a $C$-holomorphic manifold $X_{n}(C)$. The real model of such a tensor field is a tensor field on $M_{2 n}$ of the same order irrespective of whether its vector or covector arguments is subject to the action of the affinor structure $\varphi$. Such tensor fields are said to be pure with respect to $\varphi$. They were studied by many authors (see, e.g., [10], [20], [21], [23], [24], [25], [27]). In particular, for a $(0, q)$-tensor field $\omega$, the purity means that for any $X_{1}, \ldots, X_{q} \in \Im_{0}^{1}\left(M_{2 n}\right)$, the following conditions should hold:

$$
\omega\left(\varphi X_{1}, X_{2}, \ldots, X_{q}\right)=\omega\left(X_{1}, \varphi X_{2}, \ldots, X_{q}\right)=\ldots=\omega\left(X_{1}, X_{2}, \ldots, \varphi X_{q}\right)
$$

We define an operator

$$
\Phi_{\varphi}: \Im_{q}^{0}\left(M_{2 n}\right) \rightarrow \Im_{q+1}^{0}\left(M_{2 n}\right)
$$

applied to a pure tensor field $\omega$ by (see [27])

$$
\begin{aligned}
\left(\Phi_{\varphi} \omega\right)\left(X, Y_{1}, Y_{2}, \ldots, Y_{q}\right)= & (\varphi X)\left(\omega\left(Y_{1}, Y_{2}, \ldots, Y_{q}\right)\right)-X\left(\omega\left(\varphi Y_{1}, Y_{2}, \ldots, Y_{q}\right)\right) \\
& +\omega\left(\left(L_{Y_{1}} \varphi\right) X, Y_{2}, \ldots, Y_{q}\right)+\ldots+\omega\left(Y_{1}, Y_{2}, \ldots,\left(L_{Y_{q}} \varphi\right) X\right)
\end{aligned}
$$

where $L_{Y}$ denotes the Lie differentiation with respect to $Y$.
When $\varphi$ is a complex structure on $M_{2 n}$ and the tensor field $\Phi_{\varphi} \omega$ vanishes, the complex tensor field $\stackrel{*}{\omega}$ on $X_{n}(C)$ is said to be holomorphic (see [10], [23], [27]). Thus, a holomorphic tensor field $\stackrel{*}{\omega}$ on $X_{n}(C)$ is realized on $M_{2 n}$ in the form of a pure tensor field $\omega$, such that

$$
\left(\Phi_{\varphi} \omega\right)\left(X, Y_{1}, Y_{2}, \ldots, Y_{q}\right)=0
$$

for any $X, Y_{1}, \ldots, Y_{q} \in \Im_{0}^{1}\left(M_{2 n}\right)$. Such a tensor field $\omega$ on $M_{2 n}$ is also called holomorphic tensor field. When $\varphi$ is an almost complex structure on $M_{2 n}$, a tensor field $\omega$ satisfying $\Phi_{\varphi} \omega=0$ is said to be almost holomorphic.

### 1.3 Holomorphic Norden (Kähler-Norden or anti-Kähler) metrics

On a Norden manifold, a Norden metric $g$ is called a holomorphic if

$$
\begin{equation*}
\left(\Phi_{\varphi} g\right)(X, Y, Z)=-g\left(\left(\nabla_{X} \varphi\right) Y, Z\right)+g\left(\left(\nabla_{Y} \varphi\right) Z, X\right)+g\left(\left(\nabla_{Z} \varphi\right) X, Y\right)=0 \tag{1}
\end{equation*}
$$

for any $X, Y, Z \in \Im_{0}^{1}\left(M_{2 n}\right)$.
By setting $X=\partial_{k}, Y=\partial_{i}, Z=\partial_{j}$ in equation (1), we see that the components $\left(\Phi_{\varphi} g\right)_{k i j}$ of $\Phi_{\varphi} g$ with respect to a local coordinate system $x^{1}, \ldots, x^{n}$ can be expressed as follows:

$$
\left(\Phi_{\varphi} g\right)_{k i j}=\varphi_{k}^{m} \partial_{m} g_{i j}-\varphi_{i}^{m} \partial_{k} g_{m j}+g_{m j}\left(\partial_{i} \varphi_{k}^{m}-\partial_{k} \varphi_{i}^{m}\right)+g_{i m} \partial_{j} \varphi_{k}^{m} .
$$

If $\left(M_{2 n}, \varphi, g\right)$ is a Norden manifold with holomorphic Norden metric, we say that $\left(M_{2 n}, \varphi, g\right)$ is a holomorphic Norden manifold.

In some aspects, holomorphic Norden manifolds are similar to Kähler manifolds. The following theorem is an analogue to the next known result: an almost Hermitian manifold is Kähler if and only if the almost complex structure is parallel with respect to the Levi-Civita connection.

Theorem 1. [8] (For a paracomplex version see [22]) For an almost complex manifold with Norden metric $g$, the condition $\Phi_{\phi} g=0$ is equivalent to $\nabla \varphi=0$, where $\nabla$ is the LeviCivita connection of $g$.

A Kähler-Norden manifold can be defined as a triple $\left(M_{2 n}, \varphi, g\right)$ which consists of a manifold $M_{2 n}$ endowed with an almost complex structure $\varphi$ and a pseudo-Riemannian metric $g$ such that $\nabla \varphi=0$, where $\nabla$ is the Levi-Civita connection of $g$ and the metric $g$ is assumed to be a Norden one. Therefore, there exists a one-to-one correspondence between Kähler-Norden manifolds and Norden manifolds with holomorphic metric. Recall that the Riemannian curvature tensor of such a manifold is pure and holomorphic, and the scalar curvature is locally holomorphic function (see [8], [19]).

Remark 1. We know that the integrability of an almost complex structure $\varphi$ is equivalent to the existence of a torsion-free affine connection with respect to which the equation $\nabla \varphi=0$ holds. Since the Levi-Civita connection $\nabla$ of $g$ is a torsion-free affine connection, we have: if $\Phi_{\varphi} g=0$, then $\varphi$ is integrable. Thus, almost Norden manifold with conditions $\Phi_{\varphi} g=0$ and $N_{\varphi} \neq 0$, i.e., almost holomorphic Norden manifolds (analogues of almost Kähler manifolds with closed Kähler form) do not exist.

### 1.4 Quasi-Kähler manifolds

The basis class of non-integrable almost complex manifolds with Norden metric is the class of the quasi-Kähler manifolds. An almost Norden manifold $\left(M_{2 n}, \varphi, g\right)$ is called a quasiKähler [17], if

$$
\underset{X, Y, Z}{\sigma} g\left(\left(\nabla_{X} \varphi\right) Y, Z\right)=0
$$

where $\sigma$ is the cyclic sum by three arguments.
From (1) and the last equation we have

$$
\left(\Phi_{\varphi} g\right)(X, Y, Z)+2 g\left(\left(\nabla_{X} \varphi\right) Y, Z\right)=\underset{X, Y, Z}{\sigma} g\left(\left(\nabla_{X} \varphi\right) Y, Z\right)=0
$$

which is satisfied by the Norden metric in the quasi-Kähler manifold.

### 1.5 Twin Norden metrics

Let $\left(M_{2 n}, \varphi, g\right)$ be an almost Norden manifold. The associated Norden metric of almost Norden manifold is defined by

$$
G(X, Y)=(g \circ \varphi)(X, Y)
$$

for all vector fields $X$ and $Y$ on $M_{2 n}$. One can easily prove that $G$ is a new Norden metric, which is also called the twin(or dual) Norden metric of $g$.

We denote by $\nabla_{g}$ the covariant differentiation of the Levi-Civita connection of Norden metric $g$. Then, we have

$$
\nabla_{g} G=\left(\nabla_{g} g\right) \circ \varphi+g \circ\left(\nabla_{g} \varphi\right)=g \circ\left(\nabla_{g} \varphi\right),
$$

which implies $\nabla_{g} G=0$ by virtue of Theorem 1 . Therefore we have: the Levi-Civita connection of Kähler-Norden metric $g$ coincides with the Levi-Civita connection of twin metric G (i.e. nonuniqueness of the metric for the Levi-Civita connection in Kähler-Norden manifolds).

## 2 Norden-Walker metrics

In the present paper, we shall focus our attention to Norden manifolds of dimension four. Using a Walker metric we construct new Norden-Walker metrics together with a proper and opposite almost complex structures.

### 2.1 Walker metric $g$

A neutral metric $g$ on a 4-manifold $M_{4}$ is said to be a Walker metric if there exists a 2-dimensional null distribution $D$ on $M_{4}$, which is parallel with respect to $g$. From Walker's theorem [26], there is a system of coordinates $(x, y, z, t)$ with respect to which $g$ takes the following local canonical form

$$
g=\left(g_{i j}\right)=\left(\begin{array}{cccc}
0 & 0 & 1 & 0  \tag{2}\\
0 & 0 & 0 & 1 \\
1 & 0 & a & c \\
0 & 1 & c & b
\end{array}\right)
$$

where $a, b, c$ are smooth functions of the coordinates $(x, y, z, t)$. The paralel null 2-plane $D$ is spanned locally by $\left\{\partial_{x}, \partial_{y}\right\}$, where $\partial_{x}=\frac{\partial}{\partial x}, \partial_{y}=\frac{\partial}{\partial y}$.

### 2.2 Almost Norden-Walker manifolds

Let $F$ be an almost complex structure on a Walker manifold $M_{4}$, which satisfies
i) $F^{2}=-I$,
ii) $g(F X, Y)=g(X, F Y)$ (Nordenian property),
iii) $F \partial_{x}=\partial_{y}, F \partial_{y}=-\partial_{x}\left(F\right.$ induces a positive $\frac{\pi}{2}-$ rotation on $\left.D\right)$.

We easily see that these three properties define $F$ non-uniquely, i.e.,

$$
\left\{\begin{array}{l}
F \partial_{x}=\partial_{y} \\
F \partial_{y}=-\partial_{x} \\
F \partial_{z}=\alpha \partial_{x}+\frac{1}{2}(a+b) \partial_{y}-\partial_{t} \\
F \partial_{t}=-\frac{1}{2}(a+b) \partial_{x}+\alpha \partial_{y}+\partial_{z}
\end{array}\right.
$$

and $F$ has the local components

$$
F=\left(F_{j}^{i}\right)=\left(\begin{array}{cccc}
0 & -1 & \alpha & -\frac{1}{2}(a+b) \\
1 & 0 & \frac{1}{2}(a+b) & \alpha \\
0 & 0 & 0 & 1 \\
0 & 0 & -1 & 0
\end{array}\right)
$$

with respect to the natural frame $\left\{\partial_{x}, \partial_{y}, \partial_{z}, \partial_{t}\right\}$, where $\alpha=\alpha(x, y, z, t)$ is an arbitrary function.

Therefore, we now put $\alpha=c$. Then $g$ defines a unique almost complex structure

$$
\varphi=\left(\varphi_{j}^{i}\right)=\left(\begin{array}{cccc}
0 & -1 & c & -\frac{1}{2}(a+b)  \tag{3}\\
1 & 0 & \frac{1}{2}(a+b) & c \\
0 & 0 & 0 & 1 \\
0 & 0 & -1 & 0
\end{array}\right)
$$

The triple $\left(M_{4}, \varphi, g\right)$ is called almost Norden-Walker manifold. In conformity with the terminology of [3], [4], [14], [15] we call $\varphi$ the proper almost complex structure.

We note that the typical examples of Norden-Walker metrics with proper almost complex structure

$$
J=\left(J_{j}^{i}\right)=\left(\begin{array}{cccc}
0 & -1 & -c & \frac{1}{2}(a-b) \\
1 & 0 & \frac{1}{2}(a-b) & c \\
0 & 0 & 0 & -1 \\
0 & 0 & 1 & 0
\end{array}\right)
$$

are studied in [2].

### 2.3 Isotropic Kähler-Norden-Walker structures

A proper almost complex structure $\varphi$ on Norden-Walker manifold $\left(M_{4}, \varphi, g\right)$ is said to be isotropic Kähler if $\|\nabla \varphi\|^{2}=0$, but $\nabla \varphi \neq 0$. Examples of isotropic Kähler structures were given first in [7] in dimension 4, subsequently in [1] in dimension 6 and in [3] in dimension 4. Our purpose in this section is to show that a proper almost complex structure on almost Norden-Walker manifold $\left(M_{4}, \varphi, g\right)$ is isotropic Kähler as we will see Theorem 2.

The inverse of the metric tensor $(2), g^{-1}=\left(g^{i j}\right)$, given by

$$
g^{-1}=\left(\begin{array}{cccc}
-a & -c & 1 & 0  \tag{4}\\
-c & -b & 0 & 1 \\
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0
\end{array}\right)
$$

For the covariant derivative $\nabla \varphi$ of the almost complex structure put $(\nabla \varphi)_{i j}^{k}=\nabla_{i} \varphi_{j}^{k}$. Then, after some calculations we obtain

$$
\begin{align*}
\nabla_{x} \varphi_{z}^{x} & =\nabla_{x} \varphi_{t}^{y}=c_{x}, \nabla_{y} \varphi_{z}^{x}=\nabla_{y} \varphi_{t}^{y}=c_{y}  \tag{5}\\
\nabla_{z} \varphi_{x}^{x} & =-\nabla_{z} \varphi_{y}^{y}=\nabla_{z} \varphi_{z}^{z}=-\nabla_{z} \varphi_{t}^{t}=\frac{1}{2} a_{y}+\frac{1}{2} c_{x} \\
\nabla_{z} \varphi_{x}^{y} & =\nabla_{z} \varphi_{y}^{x}=\nabla_{z} \varphi_{z}^{t}=\nabla_{z} \varphi_{t}^{z}=-\frac{1}{2} a_{x}+\frac{1}{2} c_{y}, \\
\nabla_{z} \varphi_{z}^{x} & =2 c_{z}+c a_{x}-a_{t}-\frac{1}{2} c c_{y}-\frac{1}{2} a c_{x}+\frac{1}{2} b a_{y}, \\
\nabla_{z} \varphi_{z}^{y} & =a_{z}+\frac{1}{4} a c_{y}-\frac{1}{4} b c_{y}+c a_{y}+\frac{3}{4} a a_{x}+\frac{1}{4} b a_{x}, \\
\nabla_{z} \varphi_{t}^{x} & =\frac{1}{4} a a_{x}-\frac{1}{4} b a_{x}+c a_{y}+\frac{3}{4} b c_{y}+c c_{x}+\frac{1}{4} a c_{y} \\
\nabla_{z} \varphi_{z}^{y} & =a_{z}+\frac{1}{4} a c_{y}-\frac{1}{4} b c_{y}+c a_{y}+\frac{3}{4} a a_{x}+\frac{1}{4} b a_{x}, \\
\nabla_{z} \varphi_{t}^{x} & =\frac{1}{4} a a_{x}-\frac{1}{4} b a_{x}+c a_{y}+\frac{3}{4} b c_{y}+c c_{x}+\frac{1}{4} a c_{y},
\end{align*}
$$

$$
\begin{aligned}
\nabla_{z} \varphi_{t}^{y} & =2 c_{z}+\frac{1}{2} c c_{y}-a_{t}+\frac{1}{2} b a_{y}+\frac{1}{2} c a_{x}-\frac{1}{2} a c_{x}, \\
\nabla_{t} \varphi_{x}^{x} & =-\nabla_{t} \varphi_{y}^{y}=\nabla_{t} \varphi_{z}^{z}=-\nabla_{t} \varphi_{t}^{t}=\frac{1}{2} c_{y}+\frac{1}{2} b_{x}, \\
\nabla_{t} \varphi_{x}^{y} & =\nabla_{t} \varphi_{y}^{x}=\nabla_{t} \varphi_{z}^{t}=\nabla_{t} \varphi_{t}^{z}=-\frac{1}{2} c_{x}+\frac{1}{2} b_{y}, \\
\nabla_{t} \varphi_{z}^{x} & =\frac{3}{2} c c_{x}+b_{z}-\frac{1}{2} c b_{y}-\frac{1}{2} a b_{x}+\frac{1}{2} b c_{y}, \\
\nabla_{t} \varphi_{z}^{y} & =\frac{1}{4} a b_{y}-\frac{1}{4} b b_{y}-\frac{1}{4} a c_{x}+\frac{1}{4} b c_{x}, \\
\nabla_{t} \varphi_{t}^{x} & =\frac{1}{4} a c_{x}-\frac{1}{4} b c_{x}+c c_{y}+\frac{1}{4} b b_{y}+c b_{x}-\frac{1}{4} a b_{y} \\
\nabla_{t} \varphi_{t}^{y} & =\frac{1}{2} c b_{y}+b_{z}+\frac{1}{2} b c_{y}+\frac{1}{2} c c_{x}-\frac{1}{2} a b_{x} .
\end{aligned}
$$

Now a long but straightforward calculation shows that

$$
\|\nabla \varphi\|^{2}=g^{i j} g^{k l} g_{m s}(\nabla \varphi)_{i k}^{m}(\nabla \varphi)_{j l}^{s}=0 .
$$

Theorem 2. A proper almost complex structure on almost Norden-Walker manifold ( $M_{4}$, $\varphi, g)$ is isotropic Kähler.

### 2.4 Integrability of $\varphi$

We consider the general case.
The almost complex structure $\varphi$ of an almost Norden-Walker manifold is integrable if and only if

$$
\begin{equation*}
\left(N_{\varphi}\right)_{j k}^{i}=\varphi_{j}^{m} \partial_{m} \varphi_{k}^{i}-\varphi_{k}^{m} \partial_{m} \varphi_{j}^{i}-\varphi_{m}^{i} \partial_{j} \varphi_{k}^{m}+\varphi_{m}^{i} \partial_{k} \varphi_{j}^{m}=0 . \tag{6}
\end{equation*}
$$

From (3) and (6) find the following integrability condition.
Theorem 3. The proper almost complex structure $\varphi$ of an almost Norden-Walker manifold is integrable if and only if the following PDEs hold:

$$
\left\{\begin{array}{l}
a_{x}+b_{x}+2 c_{y}=0,  \tag{7}\\
a_{y}+b_{y}-2 c_{x}=0
\end{array}\right.
$$

From this theorem, we see that, in the case $a=-b$ and $c=0, \varphi$ is integrable.
Let $\left(M_{4}, \varphi, g\right)$ be a Norden-Walker manifolds $\left(N_{\varphi}=0\right)$ and $a=b$. Then the equation (7) reduces to

$$
\left\{\begin{array}{l}
a_{x}=-c_{y},  \tag{8}\\
a_{y}=c_{x},
\end{array}\right.
$$

from which follows

$$
\begin{align*}
& a_{x x}+a_{y y}=0,  \tag{9}\\
& c_{x x}+c_{y y}=0,
\end{align*}
$$

e.g., the functions $a$ and $c$ are harmonic with respect to the arguments $x$ and $y$.

Thus we have
Theorem 4. If the triple $\left(M_{4}, \varphi, g\right)$ is Norden-Walker and $a=b$, then $a$ and $c$ are all harmonic with respect to the arguments $x, y$.

### 2.5 Example of Norden-Walker metric

We now apply the Theorem 4 to establish the existence of special types of Norden-Walker metrics. In our arguments, the harmonic function plays an important part.

Let $a=b$ and $h(x, y)$ be a harmonic function of variables $x$ and $y$, for example $h(x, y)=$ $e^{x} \cos y$. We put

$$
a=a(x, y, z, t)=h(x, y)+\alpha(z, t)=e^{x} \cos y+\alpha(z, t)
$$

where $\alpha$ is an arbitrary smooth function of $z$ and t . Then, $a$ is also hormonic with respect to $x$ and $y$. We have

$$
\begin{aligned}
& a_{x}=e^{x} \cos y \\
& a_{y}=-e^{x} \sin y
\end{aligned}
$$

From (8), we have PDE's for $c$ to satisfy as

$$
\begin{aligned}
& c_{x}=a_{y}=-e^{x} \sin x \\
& c_{y}=-a_{x}=-e^{x} \cos y
\end{aligned}
$$

For these PDE's, we have solutions

$$
c=-e^{x} \sin y+\beta(z, t)
$$

where $\beta$ is arbitrary smooth function of $z$ and $t$. Thus the Norden-Walker metric has components of the form

$$
g=\left(g_{i j}\right)=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & e^{x} \cos y+\alpha(z, t) & -e^{x} \sin y+\beta(z, t) \\
0 & 1 & -e^{x} \sin y+\beta(z, t) & e^{x} \cos y+\alpha(z, t)
\end{array}\right)
$$

## 3 Holomorphic Norden-Walker(Kähler-NordenWalker) and quasi-Kähler-Norden-Walker metrics on $\left(M_{4}, \varphi, g\right)$

Let $\left(M_{4}, \varphi, g\right)$ be an almost Norden-Walker manifold. If

$$
\begin{equation*}
\left(\Phi_{\phi} g\right)_{k i j}=\phi_{k}^{m} \partial_{m} g_{i j}-\phi_{i}^{m} \partial_{k} g_{m j}+g_{m j}\left(\partial_{i} \phi_{k}^{m}-\partial_{k} \phi_{i}^{m}\right)+g_{i m} \partial_{j} \phi_{k}^{m}=0 \tag{10}
\end{equation*}
$$

then, by virtue of Theorem $1, \varphi$ is integrable and the triple $\left(M_{4}, \varphi, g\right)$ is called a holomorphic Norden-Walker or a Kähler-Norden-Walker manifold. Taking into account Remark 1, we see that an almost Kähler-Norden-Walker manifold with conditions $\Phi_{\varphi} g=0$ and $N_{\varphi} \neq 0$ does not exist.

Substitute (2) and (3) into (10), we see that the non-vanishing components of $\left(\Phi_{\varphi} g\right)_{k i j}$
are

$$
\begin{align*}
\left(\Phi_{\varphi} g\right)_{x z z} & =a_{y},\left(\Phi_{\varphi} g\right)_{x z t}=\left(\Phi_{\varphi} g\right)_{x t z}=\frac{1}{2}\left(b_{x}-a_{x}\right)+c_{y},  \tag{11}\\
\left(\Phi_{\varphi} g\right)_{x t t} & =b_{y}-2 c_{x}, \quad\left(\Phi_{\varphi} g\right)_{y z z}=-a_{x}, \\
\left(\Phi_{\varphi} g\right)_{y z t} & =\left(\Phi_{\varphi} g\right)_{y t z}=\frac{1}{2}\left(b_{y}-a_{y}\right)-c_{x},\left(\Phi_{\varphi} g\right)_{y t t}=-b_{x}-2 c_{y}, \\
\left(\Phi_{\varphi} g\right)_{z x z} & =\left(\Phi_{\varphi} g\right)_{z z x}=\left(\Phi_{\varphi} g\right)_{t x t}=\left(\Phi_{\varphi} g\right)_{t t x}=c_{x}, \\
\left(\Phi_{\varphi} g\right)_{z x t} & =\left(\Phi_{\varphi} g\right)_{z t x}=-\left(\Phi_{\varphi} g\right)_{t x z}=-\left(\Phi_{\varphi} g\right)_{t z x}=\frac{1}{2}\left(a_{x}+b_{x}\right), \\
\left(\Phi_{\varphi} g\right)_{z y z} & =\left(\Phi_{\varphi} g\right)_{z z y}=\left(\Phi_{\varphi} g\right)_{t y t}=\left(\Phi_{\varphi} g\right)_{t t y}=c_{y}, \\
\left(\Phi_{\varphi} g\right)_{z y t} & =\left(\Phi_{\varphi} g\right)_{z t y}=-\left(\Phi_{\varphi} g\right)_{t y z}=-\left(\Phi_{\varphi} g\right)_{t z y}=\frac{1}{2}\left(a_{y}+b_{y}\right), \\
\left(\Phi_{\varphi} g\right)_{z z z} & =c a_{x}-a_{t}+2 c_{z}+\frac{1}{2}(a+b) a_{y}, \\
\left(\Phi_{\varphi} g\right)_{z z t} & =\left(\Phi_{\varphi} g\right)_{z t z}=c c_{x}+b_{z}+\frac{1}{2}(a+b) c_{y}, \\
\left(\Phi_{\varphi} g\right)_{z t t} & =c b_{x}+a_{t}-2 c_{z}+\frac{1}{2}(a+b) b_{y},\left(\Phi_{\varphi} g\right)_{t z z}=c a_{y}-b_{z}-\frac{1}{2}(a+b) a_{x}, \\
\left(\Phi_{\varphi} g\right)_{t z t} & =\left(\Phi_{\varphi} g\right)_{t t z}=c c_{y}-a_{t}+2 c_{z}-\frac{1}{2}(a+b) c_{x}, \\
\left(\Phi_{\varphi} g\right)_{t t t} & =c b_{y}+b_{z}-\frac{1}{2}(a+b) b_{x} .
\end{align*}
$$

From the above equations, we have
Theorem 5. A triple $\left(M_{4}, \varphi, g\right)$ is a Kähler-Norden-Walker manifold if and only if the following PDEs hold:

$$
\begin{equation*}
a_{x}=a_{y}=b_{x}=b_{y}=b_{z}=c_{x}=c_{y}=0, \quad a_{t}-2 c_{z}=0 . \tag{12}
\end{equation*}
$$

A Norden-Walker manifold $\left(M_{4}, \varphi, g\right)$ satisfying the condition $\Phi_{k} g_{i j}+2 \nabla_{k} G_{i j}$ to be zero is called a quasi-Kähler manifold, where $G$ is defined by $G_{i j}=\varphi_{i}^{m} g_{m j}$.

Remark 2. From (2) and (3) we easily see that, the twin Norden metric $G$ is non-Walker.
For the covariant derivative $\nabla G$ of the associated metric $G$ put $(\nabla G)_{i j k}=\nabla_{i} G_{j k}$. The non-vanishing components of $\nabla_{i} G_{j k}$ are

$$
\begin{align*}
\nabla_{x} G_{z z} & =\nabla_{x} G_{t t}=c_{x}, \nabla_{y} G_{z z}=\nabla_{y} G_{t t}=c_{y},  \tag{13}\\
\nabla_{z} G_{x z} & =\nabla_{z} G_{z x}=-\nabla_{z} G_{y t}=-\nabla_{z} G_{t y}=\frac{1}{2}\left(a_{y}+c_{x}\right), \\
\nabla_{z} G_{x t} & =\nabla_{z} G_{t x}=\nabla_{z} G_{y z}=\nabla_{z} G_{z y}=\frac{1}{2}\left(c_{y}-a_{x}\right), \\
\nabla_{z} G_{z z} & =2 c_{z}-a_{t}+\frac{1}{2} a_{y}(a+b)+c a_{x}, \\
\nabla_{z} G_{z t} & =\nabla_{z} G_{t z}=\frac{1}{2}\left(c a_{y}+c c_{x}\right)-\frac{1}{4}\left((a+b)\left(a_{x}-c_{y}\right)\right), \\
\nabla_{z} G_{t t} & =2 c_{z}-a_{t}-\frac{1}{2} c_{x}(a+b)+c c_{y}, \\
\nabla_{t} G_{x z} & =\nabla_{t} G_{z x}=-\nabla_{t} G_{y t}=-\nabla_{t} G_{t y}=\frac{1}{2}\left(b_{x}+c_{y}\right), \\
\nabla_{t} G_{x t} & =\nabla_{t} G_{t x}=\nabla_{t} G_{y z}=\nabla_{t} G_{z y}=\frac{1}{2}\left(b_{y}-c_{x}\right),
\end{align*}
$$

$$
\begin{aligned}
\nabla_{t} G_{z z} & =b_{z}+c c_{x}+\frac{1}{2} c_{y}(a+b) \\
\nabla_{t} G_{z t} & =\nabla_{t} G_{t z}=\frac{1}{2} c\left(b_{x}+c_{y}\right)-\frac{1}{4}\left(\left(c_{x}-b_{y}\right)(a+b)\right) \\
\nabla_{t} G_{t t} & =b_{z}+c b_{y}-\frac{1}{2} b_{x}(a+b)
\end{aligned}
$$

From (11) and (13) we have
Theorem 6. A triple $\left(M_{4}, \varphi, g\right)$ is a quasi-Kähler Norden-Walker manifold if and only if the following PDEs hold:

$$
b_{x}=b_{y}=b_{z}=0, a_{y}-2 c_{x}=0, a_{x}-2 c_{y}=0, c a_{x}-a_{t}+2 c_{z}-(a+b) c_{x}=0
$$

## 4 Curvature properties of Norden-Walker manifolds

If $R$ and $r$ are respectively the curvature and the scalar curvature of the Walker metric, then the components of $R$ and $r$ have, respectively, expressions (see [15], Appendix A and C)

$$
\begin{align*}
R_{x z x z}= & -\frac{1}{2} a_{x x}, R_{x z x t}=-\frac{1}{2} c_{x x}, R_{x z y z}=-\frac{1}{2} a_{x y}, R_{x z y t}=-\frac{1}{2} c_{x y},  \tag{14}\\
R_{x z z t}= & \frac{1}{2} a_{x t}-\frac{1}{2} c_{x z}-\frac{1}{4} a_{y} b_{x}+\frac{1}{4} c_{x} c_{y}, R_{x t x t}=-\frac{1}{2} b_{x x}, R_{x t y z}=-\frac{1}{2} c_{x y}, \\
R_{x t y t}= & -\frac{1}{2} b_{x y}, R_{x t z t}=\frac{1}{2} c_{x t}-\frac{1}{2} b_{x z}-\frac{1}{4}\left(c_{x}\right)^{2}+\frac{1}{4} a_{x} b_{x}-\frac{1}{4} b_{x} c_{y}+\frac{1}{4} b_{y} c_{x}, \\
R_{y z y z}= & -\frac{1}{2} a_{y y}, R_{y z y t}=-\frac{1}{2} c_{y y}, \\
R_{y z z t}= & \frac{1}{2} a_{y t}-\frac{1}{2} c_{y z}-\frac{1}{4} a_{x} c_{y}+\frac{1}{4} a_{y} c_{x}-\frac{1}{4} a_{y} b_{y}+\frac{1}{4}\left(c_{y}\right)^{2}, R_{y t y t}=-\frac{1}{2} b_{y y}, \\
R_{y t z t}= & \frac{1}{2} c_{y t}-\frac{1}{2} b_{y z}-\frac{1}{4} c_{x} c_{y}+\frac{1}{4} a_{y} b_{x}, \\
R_{z t z t}= & c_{z t}-\frac{1}{2} a_{t t}-\frac{1}{2} b_{z z}-\frac{1}{4} a\left(c_{x}\right)^{2}+\frac{1}{4} a a_{x} b_{x}+\frac{1}{4} c a_{x} b_{y}-\frac{1}{2} c c_{x} c_{y}-\frac{1}{2} a_{t} c_{x} \\
& +\frac{1}{2} a_{x} c_{t}-\frac{1}{4} a_{x} b_{z}+\frac{1}{4} c a_{y} b_{x}+\frac{1}{4} b a_{y} b_{y}-\frac{1}{4} b\left(c_{y}\right)^{2}-\frac{1}{2} b_{z} c_{y} \\
& +\frac{1}{4} a_{y} b_{t}+\frac{1}{4} a_{z} b_{x}+\frac{1}{2} b_{y} c_{z}-\frac{1}{4} a_{t} b_{y} .
\end{align*}
$$

and

$$
r=a_{x x}+2 c_{x y}+b_{y y} .
$$

Suppose that the triple $\left(M_{4}, \varphi, g\right)$ is Kähler-Norden-Walker. Then from the last equation in (12) and (14), we see that

$$
R_{z t z t}=c_{z t}-\frac{1}{2} a_{t t}=-\frac{1}{2}\left(a_{t}-2 c_{z}\right)_{t}=0
$$

From (12) we easily we see that the another components of $R$ in (14) directly all vanish. Thus we have

Theorem 7. If a Norden-Walker manifold $\left(M_{4}, \varphi, g\right)$ is Kähler-Norden-Walker, then $M_{4}$ is flat.

Remark 3. We note that a Kähler-Norden manifold is non-flat, in such manifold curvature tensor pure and holomorphic [8].

Let $\left(M_{4}, \varphi, g\right)$ be a Norden-Walker manifold with the integrable proper structure $\varphi$, i.e., $N_{\varphi}=0$. If $a=b$, then from proof of the Theorem 4 we see that the equation (8) hold. If $c=c(y, z, t)$ and $c=c(x, z, t)$, then $c_{x y}=\left(c_{x}\right)_{y}=\left(c_{y}\right)_{x}=0$. In these cases, by virtue of (8) we find $a=a(x, z, t)$ and $a=(y, z, t)$ respectively. Using of $c_{x y}=0$ and $a_{x x}+b_{y y}=0$ (see (9)), we from (15) obtain $r=0$. Thus we have

Theorem 8. If $\left(M_{4}, \varphi, g\right)$ is a Norden-Walker non-Kähler manifold with metrics

$$
g=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & a(x, z, t) & c(y, z, t) \\
0 & 1 & c(y, z, t) & a(x, z, t)
\end{array}\right), \tilde{g}=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & a(y, z, t) & c(x, z, t) \\
0 & 1 & c(x, z, t) & a(y, z, t)
\end{array}\right),
$$

then $M_{4}$ is scalar flat.

## 5 On the Goldberg conjecture

Let $\left(M_{2 n}, J, g\right)$ be an almost Hermitian manifold. Then, Goldberg's conjecture states that an almost Hermitian manifold must be Kähler if the following three conditions are imposed: $\left(G_{1}\right)$ the manifold $M_{2 n}$ is compact; $\left(G_{2}\right)$ the Riemannian metric $g$ is Einstein; $\left(G_{3}\right)$ the fundamental 2-form $\Omega$ defined by $\Omega(X, Y)=g(J X, Y)$ is closed $(d \Omega=0)$.

It should be noted that no progress has been made on the Goldberg conjecture, and the orginal conjecture is stil an open problem.

Let $\left(M_{2 n}, \varphi, g\right)$ be an almost Norden manifold. Given an almost complex structure $\varphi$ on $M_{2 n}$, take any Riemannian metric $\tilde{g}$, which exists provided $M_{2 n}$ is compact (paracompact) [9, p. 60]. We obtain a Hermitian metric $h$ by setting

$$
h(X, Y)=\tilde{g}(X, Y)+\tilde{g}(\varphi X, \varphi Y)
$$

for any $X, Y \in \Im_{0}^{1}\left(M_{2 n}\right)$. The pair $(\varphi, \tilde{g})$ defines a fundamental 2-form $\Omega_{\varphi}$ by

$$
\Omega_{\varphi}(X, Y)=h(\varphi X, Y)
$$

We call it a $\varphi$-compatible 2 -form.
Let $\left(M_{2 n}, \varphi, g\right)$ be an almost Norden manifold, and choose a $\varphi$-compatible 2 -form $\Omega_{\varphi}$ on $M_{2 n}$. Then we can propose an almost Norden version of Goldberg conjecture as follows [16]: if $\left(G_{1}\right) M_{2 n}$ is compact, $\left(G_{2}\right) g$ is Einstein, and if $\left(G_{3}^{\prime}\right)$ a $\varphi$-compatible 2-form $\Omega_{\varphi}$ is closed, then $\varphi$ must be integrable.

Let now $\left(M_{4}, \varphi, g\right)$ be an almost Norden-Walker 4-manifold. The pair $(\varphi, g)$ defines as usual, a rank two tensor $G(X, Y)=g(\varphi X, Y)$, but $G$ is symmetric (in fact another neutral metric) and pure, rather than a 2 -form. We call it a twin Norden metric, which plays a role similar to the fundamental 2 -form $\Omega$ in Hermitian geometry. If we define an operator $\Phi_{\varphi}$ applied to a pure twin metric $G$, then we have

$$
\left(\Phi_{\varphi} G\right)(X, Y, Z)=\left(\Phi_{\varphi} g\right)(\varphi X, Y, Z)+g\left(N_{\varphi}(X, Y), Z\right)
$$

If $G \in \operatorname{Ker} \Phi_{\varphi}$, then by virtue of Theorem 1 , we have $\nabla_{G} \varphi=0$, where $\nabla_{G}$ is the Levi-Civita connection of the twin Norden metric $G$, which coincides with the Levi-Civita connection of the orginal Norden metric $g$ in Kähler-Norden-Walker manifolds. Since $\nabla_{G}$ is a torsion-free connection, then $\varphi$ must be integrable. Thus, we can propose a result concerning the Norden version of Goldberg conjecture as follows: $(N G)$ if $G \in \operatorname{Ker} \Phi_{\varphi}$, then $\varphi$ must be integrable.

## 6 Opposite almost complex structure $\varphi^{\prime}$

It is known that an oriented 4-manifold with a field of 2-planes, or equivalently endowed with a neutral indefinite metric, admits a pair of almost comlex structure $\varphi$ and an opposite almost complex structure $\varphi^{\prime}$, which satisfy the following properties ([11]-[13], [15]):
i) $\varphi^{2}=\varphi^{\prime 2}=-1$,
ii) $g(\varphi X, \varphi Y)=g\left(\varphi^{\prime} X, \varphi^{\prime} Y\right)=g(X, Y)$,
iii) $\varphi \varphi^{\prime}=\varphi^{\prime} \varphi$,
iv) the preferred orientation of $\varphi$ coincides with that of $M_{4}$,
v) the preferred orientation of $\varphi^{\prime}$ is opposite to that of $M_{4}$.

Let $\left(M_{4}, \varphi, g\right)$ be an almost Norden-Walker manifolds. For a Walker manifold $M_{4}$, with the proper almost complex structure $\varphi$, the $g$-orthogonal opposite almost complex structure $\varphi^{\prime}$ takes the form

$$
\begin{aligned}
\varphi^{\prime} \partial_{1} & =-\left(\theta_{1} c+\frac{\theta_{2}}{2} a\right) \partial_{1}-\frac{\theta_{1}}{2} b \partial_{2}+\theta_{2} \partial_{3}+\theta_{1} \partial_{4}, \\
\varphi^{\prime} \partial_{2} & =\left(-\frac{\theta_{1}}{2} a+\theta_{2} c\right) \partial_{1}+\frac{\theta_{2}}{2} b \partial_{2}+\theta_{1} \partial_{3}-\theta_{2} \partial_{4}, \\
\varphi^{\prime} \partial_{3} & =-\left(\frac{\theta_{1}}{2} a c+\frac{\theta_{2}}{4} a^{2}+\frac{\theta_{2}}{\theta_{1}^{2}+\theta_{2}^{2}}\right) \partial_{1}-\left(\frac{\theta_{1}}{4} a b+\frac{\theta_{1}}{\theta_{1}^{2}+\theta_{2}^{2}}\right) \partial_{2}+\frac{\theta_{2}}{2} a \partial_{3}+\frac{\theta_{1}}{2} a \partial_{4}, \\
\varphi^{\prime} \partial_{4} & =-\left(\theta_{1} c^{2}+\frac{\theta_{1}}{4} a b+\frac{\theta_{1}}{\theta_{1}^{2}+\theta_{2}^{2}}+\frac{\theta_{2}}{2}(a c-b c)\right) \partial_{1}+\left(-\frac{\theta_{1}}{2} b c+\frac{\theta_{2}}{4} b^{2}+\frac{\theta_{2}}{\theta_{1}^{2}+\theta_{2}^{2}}\right) \partial_{2} \\
& +\left(\frac{\theta_{1}}{2} b+\theta_{2} c\right) \partial_{3}+\left(\theta_{1} c-\frac{\theta_{2}}{2} b\right) \partial_{4},
\end{aligned}
$$

where $\theta_{1}$ and $\theta_{2}$ are two parameters.
In the present paper, we shall focus our attention to one of explicit forms of $\varphi^{\prime}$, obtained by fixing two parameters as $\theta_{1}=1$ and $\theta_{2}=0$ (only for simplicity), as follows:

$$
\begin{align*}
& \varphi^{\prime} \partial_{1}=-c \partial_{1}-\frac{1}{2} b \partial_{2}+\partial_{4}, \quad \varphi^{\prime} \partial_{2}=-\frac{1}{2} a \partial_{1}+\partial_{3}, \\
& \varphi^{\prime} \partial_{3}=-\frac{1}{2} a c \partial_{1}-\left(\frac{1}{4} a b+1\right) \partial_{2}+\frac{1}{2} a \partial_{4},  \tag{16}\\
& \varphi^{\prime} \partial_{4}=-\left(c^{2}+\frac{1}{4} a b+1\right) \partial_{1}-\frac{1}{2} b c \partial_{2}+\frac{1}{2} b \partial_{3}+c \partial_{4},
\end{align*}
$$

and $\varphi^{\prime}$ has the local components

$$
\varphi^{\prime}=\left(\varphi_{j}^{\prime i}\right)=\left(\begin{array}{cccc}
-c & -\frac{1}{2} a & -\frac{1}{2} a c & -\left(c^{2}+\frac{1}{4} a b+1\right)  \tag{17}\\
-\frac{1}{2} b & 0 & -\left(\frac{1}{4} a b+1\right) & -\frac{1}{2} b c \\
0 & 1 & 0 & \frac{1}{2} b \\
1 & 0 & \frac{1}{2} a & c
\end{array}\right)
$$

For the covariant derivative $\nabla \varphi^{\prime}$ of the opposite almost complex structure $\varphi^{\prime}$, the nonvanishing components of which are
$\nabla_{x} \varphi_{x}^{\prime x}=-\nabla_{x} \varphi_{y}^{\prime y}=\nabla_{x} \varphi_{z}^{\prime z}=-\nabla_{x} \varphi_{t}^{\prime t}=\frac{1}{2} \nabla_{z} \varphi_{x}^{\prime z}=-\frac{1}{2} c_{x}$,
$\nabla_{y} \varphi_{x}^{\prime x}=-\nabla_{y} \varphi_{y}^{\prime y}=\nabla_{y} \varphi_{z}^{\prime z}=-\nabla_{y} \varphi_{t}^{\prime t}=\frac{1}{2} \nabla_{t} \varphi_{y}^{\prime t}=-\frac{1}{2} c_{y}$,
$\nabla_{x} \varphi_{t}^{\prime x}=-c c_{x}, \nabla_{y} \varphi_{t}^{\prime x}=-c c_{y}, \nabla_{z} \varphi_{x}^{\prime x}=-c_{z}-\frac{1}{4} b a_{y}+\frac{1}{2} a_{t}+\frac{1}{2} c c_{y}+\frac{3}{4} a c_{x}$,
$\nabla_{z} \varphi_{x}^{\prime y}=\frac{1}{4} b c_{y}+\frac{1}{4} b a_{x}, \nabla_{z} \varphi_{x}^{\prime t}=\nabla_{z} \varphi_{y}^{\prime z}=-\frac{1}{2} c_{y}-\frac{1}{2} a_{x}$,
$\nabla_{z} \varphi_{y}^{\prime x}=\frac{1}{4} a a_{x}+c a_{y}+\frac{1}{4} a c_{y}, \nabla_{z} \varphi_{y}^{\prime y}=c_{z}-\frac{1}{4} a c_{x}-\frac{1}{2} a_{t}+\frac{1}{2} c a_{x}+\frac{3}{4} b a_{y}$,
$\nabla_{z} \varphi_{y}^{\prime t}=-a_{y}, \nabla_{z} \varphi_{z}^{\prime x}=\frac{1}{4} a c a_{x}-a_{y}+\frac{1}{4} a c c_{y}+\frac{1}{4} a^{2} c_{x}$,
$\nabla_{z} \varphi_{z}^{\prime y}=\frac{1}{8} a b c_{y}+\frac{1}{8} a b a_{x}-\frac{1}{2} c_{y}-\frac{1}{2} a_{x}$,
$\nabla_{z} \varphi_{z}^{\prime z}=-c_{z}-\frac{1}{4} a c_{x}+\frac{1}{2} a_{t}-\frac{1}{2} c a_{x}-\frac{1}{4} b a_{y}, \nabla_{z} \varphi_{z}^{\prime t}=-\frac{1}{4} a c_{y}-\frac{1}{4} a a_{x}$,
$\nabla_{z} \varphi_{t}^{\prime x}=-2 c c_{z}+\left(\frac{1}{8} a b-\frac{1}{2} c^{2}+a c-\frac{1}{2}\right) a_{x}+c a_{t}+\left(\frac{1}{8} a b+\frac{1}{2} c^{2}-\frac{1}{2}\right) c_{y}$,

$$
\begin{aligned}
\nabla_{z} \varphi_{t}^{\prime y} & =-c_{x}+\frac{1}{4} b^{2} a_{y}+\frac{1}{4} b c c_{y}+\frac{1}{4} b c a_{x}, \nabla_{z} \varphi_{t}^{\prime z}=-c c_{x}-\frac{1}{4} b a_{x}-\frac{1}{4} b c_{y} \\
\nabla_{z} \varphi_{t}^{\prime t} & =c_{z}-\frac{1}{4} b a_{y}-\frac{1}{2} a_{t}-\frac{1}{2} c c_{y}-\frac{1}{4} a c_{x}, \nabla_{t} \varphi_{x}^{\prime x}=-\frac{1}{2} b_{z}-\frac{1}{4} b c_{y}+\frac{1}{2} c b_{y}+\frac{3}{4} a b_{x} \\
\nabla_{t} \varphi_{x}^{\prime y} & =\frac{1}{4} b b_{y}+\frac{1}{4} b c_{x}, \nabla_{t}{\varphi_{x}^{\prime}}_{x}^{z}=-b_{x}, \nabla_{t} \varphi_{x}^{\prime t}=\nabla_{t} \varphi_{y}^{\prime z}=-\frac{1}{2} b_{y}-\frac{1}{2} c_{x} \\
\nabla_{t} \varphi_{y}^{\prime x} & =\frac{1}{4} a c_{x}+c c_{y}+\frac{1}{4} a b_{y}, \nabla_{t} \varphi_{y}^{\prime y}=-\frac{1}{4} a b_{x}+\frac{1}{2} b_{z}+\frac{1}{2} c c_{x}+\frac{3}{4} b c_{y} \\
\nabla_{t} \varphi_{z}^{\prime x} & =\frac{1}{4} a c b_{y}-c_{y}+\frac{1}{4} a c c_{x}+\frac{1}{4} a^{2} b_{x}, \nabla_{t} \varphi_{z}^{\prime y}=\frac{1}{8} a b b_{y}+\frac{1}{8} a b c_{x}-\frac{1}{2} b_{y}-\frac{1}{2} c_{x} \\
\nabla_{t} \varphi_{z}^{\prime z} & =-\frac{1}{4} a b_{x}-\frac{1}{2} b_{z}-\frac{1}{4} b c_{y}-\frac{1}{2} c c_{x}, \nabla_{t} \varphi_{z}^{\prime t}=-\frac{1}{4} a b_{y}-\frac{1}{4} a c_{x} \\
\nabla_{t} \varphi_{t}^{\prime x} & =-c b_{z}+\left(\frac{1}{8} a b-\frac{1}{2} c^{2}-\frac{1}{2}\right) c_{x}+a c b_{x}+\left(\frac{1}{8} a b+\frac{1}{2} c^{2}-\frac{1}{2}\right) b_{y} \\
\nabla_{t} \varphi_{t}^{\prime y} & =-b_{x}+\frac{1}{4} b^{2} c_{y}+\frac{1}{4} b c c_{x}+\frac{1}{4} b c b_{y}, \nabla_{z} \varphi_{t}^{\prime z}=-c b_{x}-\frac{1}{4} b c_{x}-\frac{1}{4} b b_{y} \\
\nabla_{t} \varphi_{t}^{\prime t} & =-\frac{1}{4} b c_{y}-\frac{1}{2} c b_{y}+\frac{1}{2} b_{z}-\frac{1}{4} a b_{x} .
\end{aligned}
$$

From (2), (4) and (18) we have
Theorem 9. The opposite almost complex structure of an almost Norden-Walker manifold $\left(M_{4}, \varphi^{\prime}, g\right)$ is isotropic Kähler if and only if the following PDEs hold:

$$
\begin{equation*}
c_{x}\left(2 b a_{y}-2 a c_{x}+4 c_{z}-2 a_{t}+2 c a_{x}\right)+c_{y}\left(2 b_{z}-2 a b_{x}\right)=0 \tag{19}
\end{equation*}
$$

From (19) we have
Corollary 1. The triple $\left(M_{4}, \varphi^{\prime}, g\right)$ with metric

$$
g=\left(g_{i j}\right)=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & a(x, y, z, t) & c(z, t) \\
0 & 1 & c(z, t) & b(x, y, z, t)
\end{array}\right)
$$

is always isotropic Kähler.

### 6.1 Integrability of $\varphi^{\prime}$

The opposite almost complex structure $\varphi^{\prime}$ is integrable if the analogue of the PDE's (6) for $\varphi_{j}^{\prime}{ }^{i}$ in (17) vanish. From some calculation, we have explicitly the following theorem.

Theorem 10. The opposite almost complex structure $\varphi^{\prime}$ of an almost Norden-Walker manifold is integrable if and only if the following PDEs hold:

$$
\begin{align*}
& b_{y}=0, \quad a_{x}-2 c_{y}=0, \quad a b_{x}-2 b_{z}=0  \tag{20}\\
& b a_{y}-2 a_{t}-2 a c_{x}+4 c c_{y}+4 c_{z}=0
\end{align*}
$$

Let $\left(M_{4}, \varphi^{\prime}, g\right)$ be a Norden-Walker manifold with the integrable almost complex structure $\varphi^{\prime}$, i.e. $N_{\varphi^{\prime}}=0$. If $a=0$, then from (20) $b_{y}=b_{z}=c_{y}=c_{z}=0$.

Thus we have
Theorem 11. Let $a=0$. The triple $\left(M_{4}, \varphi^{\prime}, g\right)$ with metric

$$
g=\left(g_{i j}\right)=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & 0 & c(x, t) \\
0 & 1 & c(x, t) & b(x, t)
\end{array}\right)
$$

is always Norden-Walker.

## 7 Norden-Walker-Einstein metrics

We now turn our attention to the Einstein conditions for the Norden-Walker metric $g$ in (2).

Let $R_{i j}$ and $S$ denote the Ricci curvature and the scalar curvature of the metric $g$ in (2). The Einstein tensor is defined by $G_{i j}=R_{i j}-\frac{1}{4} S g_{i j}$ and has non zero components as follows (see [15], Appendix D):

$$
\begin{align*}
G_{x z} & =\frac{1}{4} a_{x x}-\frac{1}{4} b_{y y}, \quad G_{x t}=\frac{1}{2} c_{x x}+\frac{1}{2} b_{x y}, \\
G_{y z} & =\frac{1}{2} a_{x y}+\frac{1}{2} c_{y y}, \quad G_{y t}=\frac{1}{4} b_{y y}-\frac{1}{4} a_{x x}, \\
G_{z z} & =\frac{1}{4} a a_{x x}+c a_{x y}+\frac{1}{2} b a_{y y}-a_{y t}+c_{y z}-\frac{1}{2} a_{y} c_{x}+\frac{1}{2} a_{x} c_{y} \\
& +\frac{1}{2} a_{y} b_{y}-\frac{1}{2}\left(c_{y}\right)^{2}-\frac{1}{2} a c_{x y}-\frac{1}{4} a b_{y y},  \tag{21}\\
G_{z t} & =\frac{1}{2} a c_{x x}+\frac{1}{2} c c_{x y}+\frac{1}{2} a_{x t}-\frac{1}{2} c_{x z}-\frac{1}{2} a_{y} b_{x}+\frac{1}{2} c_{x} c_{y}+\frac{1}{2} b c_{y y} \\
& -\frac{1}{2} c_{y t}+\frac{1}{2} b_{y z}-\frac{1}{4} c a_{x x}-\frac{1}{4} c b_{y y} \\
G_{t t} & =\frac{1}{2} a b_{x x}+c b_{x y}+c_{x t}-b_{x z}-\frac{1}{2}\left(c_{x}\right)^{2}+\frac{1}{2} a_{x} b_{x}-\frac{1}{2} b_{x} c_{y}+\frac{1}{2} b_{y} c_{x} \\
& +\frac{1}{4} b b_{y y}-\frac{1}{4} b a_{x x}-\frac{1}{2} b c_{x y} .
\end{align*}
$$

The metric $g$ in (2) is almost Norden-Walker-Einstein if all the above components $G_{i j}$ vanish $\left(G_{i j}=0\right)$.

Theorem 12. Let $\left(M_{4}, \varphi^{\prime}, g\right)$ be a Norden-Walker manifold. If

$$
\begin{equation*}
a_{x}=b_{x}=c_{x}=c_{z}=0 \quad\left(\text { or } a_{x}=a_{y}=c_{x}=c_{z}=0\right) \tag{22}
\end{equation*}
$$

then $g$ is a Norden-Walker-Einstein.

Proof. Suppose that the triple $\left(M_{4}, \varphi^{\prime}, g\right)$ be a Norden-Walker manifold. Then from (20) and (22), we see that the assertion is clear, i.e., $G_{i j}=0$.

Corollary 2. The triple $\left(M_{4}, \varphi^{\prime}, g\right)$ with metric

$$
g=\left(g_{i j}\right)=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & a(y, z, t) & c(t) \\
0 & 1 & c(t) & b(t)
\end{array}\right)
$$

is always Norden-Walker-Einstein.

## 8 Counterexamples to Goldberg's conjecture

1. Let $\left(M_{4}, \varphi, g\right)$ be an almost Norden-Walker manifold.

Consider the metric

$$
g=\left(g_{i j}\right)=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & a(x, y, z, t) & 0 \\
0 & 1 & 0 & a(x, y, z, t)
\end{array}\right)
$$

That is the metric is defined by putting $a=b, c=0$ in the generic canonical form (2). In this case, we see from (21) that the Einstein condition consist of the following PDE's:

$$
\begin{aligned}
& a_{x x}-a_{y y}=0, \quad a_{x y}=0, \quad a a_{x x}-2 a_{y t}+\left(a_{y}\right)^{2}=0 \\
& a_{x t}-a_{x} a_{y}+a_{y z}=0, \quad a a_{x x}-2 a_{x z}+\left(a_{x}\right)^{2}=0
\end{aligned}
$$

If $a$ is independent of $y$ and $t$, and if $a$ contains $x$ only linearly, the first four PDE's hold trivially, and the last one reduces to: $2 a_{x z}-\left(a_{x}\right)^{2}=0$. We see that $a=-\frac{2 x}{z}$ is a solution to the PDE, and therefore the metric

$$
g=\left(g_{i j}\right)=\left(\begin{array}{cccc}
0 & 0 & 1 & 0  \tag{23}\\
0 & 0 & 0 & 1 \\
1 & 0 & -\frac{2 x}{z} & 0 \\
0 & 1 & 0 & -\frac{2 x}{z}
\end{array}\right)
$$

is Einstein on the coordinate patch $z>0$ (or $z<0$ ). Thus, the second condition $\left(G_{2}\right)$ of Goldberg conjecture holds. We know that this metric admits a proper almost complex structure as follows:

$$
\begin{equation*}
\varphi \partial_{x}=\partial_{y}, \quad \varphi \partial_{y}=-\partial_{x}, \quad \varphi \partial_{z}=a \partial_{y}-\partial_{t}, \quad \varphi \partial_{t}=-a \partial_{x}+\partial_{z} \tag{24}
\end{equation*}
$$

For the Einstein metric (23), the proper almost complex structure $\varphi$ in (24) becomes

$$
\varphi \partial_{x}=\partial_{y}, \quad \varphi \partial_{y}=-\partial_{x}, \quad \varphi \partial_{z}=-\frac{2 x}{z} \partial_{y}-\partial_{t}, \quad \varphi \partial_{t}=\frac{2 x}{z} \partial_{x}+\partial_{z}
$$

Then, the integrability of $\varphi$, given in Theorem 3, becomes

$$
a_{x}+b_{x}+2 c_{y}=2 a_{x}=-\frac{4}{z} \neq 0, \quad a_{y}+b_{y}-2 c_{x}=2 a_{y}=0
$$

Thus, $\varphi$ cannot be integrable.
Similarly, the opposite almost complex structure $\varphi^{\prime}$ in (16) has the form

$$
\begin{aligned}
& \varphi^{\prime} \partial_{x}=-\frac{x}{z} \partial_{y}+\partial_{t}, \quad \varphi^{\prime} \partial_{y}=\frac{x}{z} \partial_{x}+\partial_{z} \\
& \varphi^{\prime} \partial_{z}=-\left(\left(\frac{x}{z}\right)^{2}+1\right) \partial_{y}-\frac{x}{z} \partial_{t}, \quad \varphi^{\prime} \partial_{t}=-\left(\left(\frac{x}{z}\right)^{2}+1\right) \partial_{x}-\frac{x}{z} \partial_{z}
\end{aligned}
$$

The $\varphi^{\prime}$ - integrability condition (20) in Theorem 10 becomes

$$
\begin{aligned}
& b_{y}=0, \quad a_{x}-2 c_{y}=a_{x}=-\frac{2}{z} \neq 0, \quad a b_{x}-2 b_{z}=a a_{x}=\frac{4 x}{z^{2}} \neq 0 \\
& b a_{y}-2 a_{t}-2 a c_{x}+4 c c_{y}+4 c_{z}=0
\end{aligned}
$$

Thus, $\varphi^{\prime}$ is not integrable.
2. Let $\left(M_{4}, \varphi^{\prime}, g\right)$ be an almost Norden-Walker manifold. We assume that $a, b, c$ does not depend on $x$ and $y$, i.e., $a=a(z, t), b=b(z, t), c=c(z, t)$. Therefore, the metric $g$ in (2) becomes

$$
g=\left(g_{i j}\right)=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & a(z, t) & c(z, t) \\
0 & 1 & c(z, t) & b(z, t)
\end{array}\right)
$$

In this case, we see from (21) that the metric $g$ is Norden-Walker-Einstein, i.e., $G_{i j}=0$. Thus, the second condition $\left(G_{2}\right)$ holds.

If $a, b$ and $c$ are independent of $x$ and $y$, the $\varphi^{\prime}$ - integrability condition (20) in Theorem 10 becomes

$$
b_{z}=0, \quad a_{t}-2 c_{z}=0
$$

On the other hand, since $b=b(z, t)$, we have $b_{z} \neq 0$. Thus, $\varphi^{\prime}$ is not integrable.

## 9 Holomorphic Norden-Walker (Kähler-NordenWalker) metrics on $\left(M_{4}, \varphi^{\prime}, g\right)$

Let $\left(M_{4}, \varphi^{\prime}, g\right)$ be an almost Norden-Walker manifold. Substituting (2) and (17) in (10), we find the following Kähler-Norden-Walker condition of $\left(M_{4}, \varphi^{\prime}, g\right)$.

$$
\begin{align*}
& \left(\Phi_{\varphi^{\prime}} g\right)_{x x z}=\left(\Phi_{\varphi^{\prime}} g\right)_{x z x}=-c_{x},\left(\Phi_{\varphi^{\prime}} g\right)_{x x t}=\left(\Phi_{\varphi^{\prime}} g\right)_{x t x}=-\left(\Phi_{\varphi^{\prime}} g\right)_{t x x}=-b_{x},  \tag{25}\\
& \left(\Phi_{\varphi^{\prime}} g\right)_{x y z}=\left(\Phi_{\varphi^{\prime}} g\right)_{x z y}=-c_{y}-\frac{1}{2} a_{x},\left(\Phi_{\varphi^{\prime}} g\right)_{x z z}=-c a_{x}-2 c_{z}-\frac{1}{2} b a_{y}+a_{t}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{x y t}=\left(\Phi_{\varphi^{\prime}} g\right)_{x t y}=-\left(\Phi_{\varphi^{\prime}} g\right)_{t x y}=-\left(\Phi_{\varphi^{\prime}} g\right)_{t y x}=-c_{x}-\frac{1}{2} b_{y}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{x z t}=\left(\Phi_{\varphi^{\prime}} g\right)_{x t z}=-c c_{x}-\frac{1}{2} b c_{y}-\frac{1}{2} b_{z}-\frac{1}{4} a b_{x}-\frac{1}{4} b a_{x}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{x t t}=-2 c b_{x}-b c_{x}-\frac{1}{2} b b_{y},\left(\Phi_{\varphi^{\prime}} g\right)_{y x t}=\left(\Phi_{\varphi^{\prime}} g\right)_{y t x}=-\frac{1}{2} b_{y}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{y x z}=\left(\Phi_{\varphi^{\prime}}\right)_{y z x}=-\left(\Phi_{\varphi^{\prime}} g\right)_{z x y}=-\left(\Phi_{\varphi^{\prime}} g\right)_{z y x}=-\frac{1}{2} a_{x}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{y y z}=\left(\Phi_{\varphi^{\prime}} g\right)_{y z y}=-\left(\Phi_{\varphi^{\prime}} g\right)_{z y y}=-a_{y}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{y y t}=\left(\Phi_{\varphi^{\prime}} g\right)_{y t y}=-\frac{1}{2}\left(\Phi_{\varphi^{\prime}} g\right)_{t y y}=-c_{y},\left(\Phi_{\varphi^{\prime}} g\right)_{y z z}=-\frac{1}{2} a a_{x}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{y z t}=\left(\Phi_{\varphi^{\prime}} g\right)_{y t z}=-\frac{1}{2} a c_{x}-\frac{1}{2} a_{t}-\frac{1}{4} a b_{y}-\frac{1}{4} b a_{y}+c_{z}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{y t t}=-\frac{1}{2} a b_{x}+b_{z}-c b_{y}-b c_{y},\left(\Phi_{\varphi^{\prime}} g\right)_{z x z}=\left(\Phi_{\varphi^{\prime}} g\right)_{z z x}=-\frac{1}{2} a c_{x}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{z x t}=\left(\Phi_{\varphi^{\prime}} g\right)_{z t x}=\frac{1}{4} b a_{x}-\frac{1}{4} a b_{x}-\frac{1}{2} b_{z}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{z y z}=\left(\Phi_{\varphi^{\prime}} g\right)_{z z y}=-\frac{1}{2} a c_{y}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{z y t}=\left(\Phi_{\varphi^{\prime}} g\right)_{z t y}=\frac{1}{4} b a_{y}-\frac{1}{4} a b_{y}-c_{z}+\frac{1}{2} a_{t}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{z z z}=-\frac{1}{2} a c a_{x}-a c_{z}-\frac{1}{4} a b a_{y}-a_{y}+\frac{1}{2} a a_{t}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{z z t}=\left(\Phi_{\varphi^{\prime}} g\right)_{z t z}=-\frac{1}{2} a c c_{x}-\frac{1}{4} a b c_{y}-c_{y}-\frac{1}{2} a b_{z}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{z t t}=-\frac{1}{2} a c b_{x}-\frac{1}{4} a b b_{y}-b_{y}-c b_{z}+\frac{1}{2} b a_{t}-b c_{z}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{t x z}=\left(\Phi_{\varphi^{\prime}} g\right)_{t z x}=-c c_{x}+\frac{1}{4} a b_{x}-\frac{1}{4} b a_{x}+\frac{1}{2} b_{z}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{t x t}=\left(\Phi_{\varphi^{\prime}} g\right)_{t t x}=-\frac{1}{2} b c_{x},\left(\Phi_{\varphi^{\prime}} g\right)_{t y t}=\left(\Phi_{\varphi^{\prime}} g\right)_{t t y}=\frac{1}{2} b c_{y}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{t y z}=\left(\Phi_{\varphi^{\prime}} g\right)_{t z y}=-c c_{y}+\frac{1}{4} a b_{y}-\frac{1}{4} b a_{y}-\frac{1}{2} a_{t}+c_{z}, \\
& \left(\Phi_{\varphi^{\prime}}\right)_{t z z}=-c^{2} a_{x}-\frac{1}{4} a b a_{x}-a_{x}-2 c c_{z}-\frac{1}{2} b c a_{y}+\frac{1}{2} a b_{z}+c a_{t}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{t z t}=\left(\Phi_{\varphi^{\prime}} g\right)_{t t z}=-c^{2} c_{x}-\frac{1}{4} a b c_{x}-c_{x}+b c_{z}-\frac{1}{2} b c c_{y}-\frac{1}{2} b a_{t}, \\
& \left(\Phi_{\varphi^{\prime}} g\right)_{t t t}=-c^{2} b_{x}-\frac{1}{4} a b b_{x}-b_{x}-\frac{1}{2} b c b_{y}+\frac{1}{2} b b_{z} .
\end{align*}
$$

The following theorem is same to the Theorem 5.

Theorem 13. A triple $\left(M_{4}, \varphi^{\prime}, g\right)$ is a Kähler-Norden-Walker manifold if and only if the following PDEs hold:

$$
a_{x}=a_{y}=b_{x}=b_{y}=b_{z}=c_{x}=c_{y}=0, \quad a_{t}-2 c_{z}=0
$$

Corollary 3. The triple $\left(M_{4}, \varphi^{\prime}, g\right)$ with metric

$$
g=\left(g_{i j}\right)=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & a(z) & 0 \\
0 & 1 & 0 & b(t)
\end{array}\right)
$$

is always Kähler-Norden-Walker.
Let $\left(M_{4}, \varphi^{\prime}, g\right)$ be an almost Norden-Walker manifold. For the covariant derivative $\nabla G^{\prime}$ of the twin metric $G^{\prime}$ put $\left(\nabla G^{\prime}\right)_{i j k}=\nabla_{i} G_{j k}^{\prime}$, where $G^{\prime}$ is deffined by $G_{i j}^{\prime}=\varphi_{i}^{\prime m} g_{m j}$. Then, after some calculations we obtain

$$
\begin{align*}
& \nabla_{x} G_{x z}^{\prime}=\nabla_{x} G_{z x}^{\prime}=-\nabla_{x} G_{y t}^{\prime}=-\nabla_{x} G_{t y}^{\prime}=\frac{1}{2} \nabla_{z} G_{x x}^{\prime}=-\frac{1}{2} c_{x},  \tag{26}\\
& \nabla_{x} G_{z z}^{\prime}=-\frac{1}{2} a c_{x}, \nabla_{x} G_{z t}^{\prime}=\nabla_{x} G_{t z}^{\prime}=-\frac{1}{2} c c_{x}, \nabla_{x} G_{t t}^{\prime}=\nabla_{y} G_{t t}^{\prime}=\frac{1}{2} b c_{x}, \\
& \nabla_{y} G_{x z}^{\prime}=\nabla_{y} G_{z x}^{\prime}=-\nabla_{y} G_{y t}^{\prime}=-\nabla_{y} G_{t y}^{\prime}=\frac{1}{2} \nabla_{t} G_{y y}^{\prime}=-\frac{1}{2} c_{y}, \\
& \nabla_{y} G_{z z}^{\prime}=-\frac{1}{2} a c_{y}, \nabla_{y} G_{z t}^{\prime}=\nabla_{y} G_{t z}^{\prime}=-\frac{1}{2} c c_{y}, \\
& \nabla_{z} G_{x y}^{\prime}=\nabla_{z} G_{y x}^{\prime}=-\frac{1}{2} a_{x}-\frac{1}{2} c_{y}, \nabla_{z} G_{x t}^{\prime}=\nabla_{z} G_{t x}^{\prime}=-\frac{1}{4} b c_{y}-c c_{x}-\frac{1}{4} b a_{x}, \\
& \nabla_{z} G_{x z}^{\prime}=\nabla_{z} G_{z x}^{\prime}=-\frac{1}{4} a c_{x}-\frac{1}{2} c a_{x}-c_{z}+\frac{1}{2} a_{t}-\frac{1}{4} b a_{y} \\
& \nabla_{z} G_{y y}^{\prime}=-a_{y}, \nabla_{z} G_{y z}^{\prime}=\nabla_{z} G_{z y}^{\prime}=-\frac{1}{4} a a_{x}-\frac{1}{4} a c_{y}, \\
& \nabla_{z} G_{y t}^{\prime}=\nabla_{z} G_{t y}^{\prime}=c_{z}-\frac{1}{2} a_{t}-\frac{1}{4} a c_{x}-\frac{1}{2} c c_{y}-\frac{1}{4} b a_{y}, \\
& \nabla_{z} G_{z z}^{\prime}=-a c_{z}+\frac{1}{2} a a_{t}-\frac{1}{4} a b a_{y}-\frac{1}{2} a c a_{x}-a_{y}, \\
& \nabla_{z} G_{z t}^{\prime}=\nabla_{z} G_{t z}^{\prime}=-c c_{z}-\frac{1}{4} b c a_{y}+\frac{1}{2} c a_{t}-\left(\frac{1}{2} c^{2}+\frac{1}{8} a b+\frac{1}{2}\right) a_{x} \\
& -\frac{1}{4} a c c_{x}-\left(\frac{1}{4} a b-\frac{1}{8} a b+\frac{1}{2}\right) c_{y}, \\
& \nabla_{z} G_{t t}^{\prime}=b c_{z}-\frac{1}{2} b a_{t}-\frac{1}{2} b c c_{y}-\left(c^{2}+\frac{1}{4} a b+1\right) c_{x}, \\
& \nabla_{t} G_{x x}^{\prime}=-b_{x}, \nabla_{t} G_{x y}^{\prime}=\nabla_{t} G_{y x}^{\prime}=-\frac{1}{2} c_{x}-\frac{1}{2} b_{y}, \\
& \nabla_{t} G_{x z}^{\prime}=\nabla_{t} G_{z x}^{\prime}=-\frac{1}{4} a b_{x}-\frac{1}{2} b_{z}-\frac{1}{4} b c_{y}-\frac{1}{2} c c_{x}, \\
& \nabla_{t} G_{x t}^{\prime}=\nabla_{t} G_{t x}^{\prime}=-\frac{1}{4} b b_{y}-c b_{x}-\frac{1}{4} b c_{x}, \nabla_{t} G_{y z}^{\prime}=\nabla_{t} G_{z y}^{\prime}=-\frac{1}{4} a b_{y}-\frac{1}{4} a c_{x}, \\
& \nabla_{t} G_{y t}^{\prime}=\nabla_{t} G_{t y}^{\prime}=\frac{1}{2} b_{z}-\frac{1}{4} a b_{x}-\frac{1}{4} b c_{y}-\frac{1}{2} c b_{y}, \\
& \nabla_{t} G_{z z}^{\prime}=-\frac{1}{2} a b_{z}-\frac{1}{4} a b c_{y}-\frac{1}{2} a c c_{x}-c_{y}, \\
& \nabla_{t} G_{z t}^{\prime}=\nabla_{t} G_{t z}^{\prime}=-\left(\frac{1}{8} a b+\frac{1}{2}\right) b_{y}-\frac{1}{4} a c b_{x}-\frac{1}{4} b c c_{y}
\end{align*}
$$

$$
\begin{gathered}
-\frac{1}{2} c b_{z}-\left(\frac{1}{8} a b+\frac{1}{2} c^{2}+\frac{1}{2}\right) c_{x} \\
\nabla_{t} G_{t t}^{\prime}=\frac{1}{2} b b_{z}-\frac{1}{2} b c b_{y}-\frac{1}{4} a b b_{x}-c^{2} b_{x}-b_{x}
\end{gathered}
$$

From (25) and (26) we have
Theorem 14. A triple $\left(M_{4}, \varphi^{\prime}, g\right)$ is a quasi-Kähler Norden-Walker manifold if and only if the following PDE's hold:

$$
a_{x}=a_{y}=b_{x}=b_{y}=b_{z}=c_{x}=c_{y}=0, a_{t}-2 c_{z}=0 .
$$

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