Note di Matematica Note Mat. 29 (2009), n. 2, 33-39 ISSN 1123-2536, e-ISSN 1590-0932 DOI 10.1285/i15900932v29n2p33 http://siba-ese.unisalento.it, © 2009 Università del Salento

On the Generalized Bertrand Curves in Euclidean N-spaces

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Received: 23/09/2008; accepted: 12/02/2009.

Abstract. In this article, we give a necessary condition for a C^{∞} -special Frenet curve in \mathbb{R}^N being a generalized Bertrand curve.

Keywords: generalized Bertrand curves

MSC 2000 classification: 53A04

1 Introduction

A curve $C: I \to \mathbb{R}^N$ is called a C^{∞} -special Frenet curve in \mathbb{R}^N if it is a smooth and regular curve with well-defined Frenet frames $\{t, n_1, \cdots, n_{N-1}\}$ and non-zero curvatures (i.e., curvatures never vanish at any point of curves) along the curve. On the other hand, in literature, a C^{∞} -special Frenet curve in \mathbb{R}^3 is called a Bertrand curve if there exists a distinct curve $\bar{C}(s) = C(s) + r(s) \cdot n_1(s)$, where n_1 is well-defined along C, such that the 1-normal lines of C(s) and $\bar{C}(s)$ are equal for all $s \in I$. Furthermore, \bar{C} is called the Bertrand mate of C.

Bertrand curves in \mathbb{R}^3 have many interesting geometric properties (e.g., see p.26 in [1] for more details). These types of curves have also been applied in computer-aided geometric design (CAGD) (e.g., see [5], [7]). In [3] Hayden has suggested to extend the definition of Bertrand curves in \mathbb{R}^3 to those in \mathbb{R}^N or Riemannian manifolds. However, Pears in [6] showed that a Bertrand curve in \mathbb{R}^N must belong to a three-dimensional subspace in \mathbb{R}^N , since its curvatures of higher order must be identically equal to zero, i.e., $k_j = 0$ for all $j \geq 3$. This implies that a Bertrand curve in \mathbb{R}^N can't be a C^{∞} -special Frenet curve in \mathbb{R}^N . Notice that a C^{∞} -special Frenet curve in \mathbb{R}^N can not be confined in

ⁱThis work was partially supported by the Grant NSC 95-2115-M-003-002.

a lower dimensional subspace of \mathbb{R}^N because all of its curvatures are nonzero. Thus the classical definition of Bertrand curves is not suitable for C^{∞} -special Frenet curves in \mathbb{R}^N . This phenomenon motivates us to extend the notion of Bertrand curves to C^{∞} -special Frenet curves in \mathbb{R}^N when $N \geq 4$. To the authors' knowledge, [4] is the only article extending the notion of Bertrand curves to Euclidean spaces of higher dimensions. The reader is referred to [4] for explicit examples of the so-called (1,3)-Bertrand curves in \mathbb{R}^4 (which is a type of generalized Bertrand curves).

In this article, we generalize the definition of classical Bertrand curves in \mathbb{R}^3 and (1,3)-Bertrand curves in \mathbb{R}^4 (see [4]) by defining the so-called generalized Bertrand curves for the class of C^{∞} -special Frenet curves in \mathbb{R}^N , where $N \ge 4$ (see Definition 1). Our main result gives a necessary condition for existence of the generalized Bertrand curve in \mathbb{R}^N . We found that only a particular type of generalized Bertrand curves exists in \mathbb{R}^N .

1 Definition (The Generalized Bertrand Curves). Assume $C: I \to \mathbb{R}^N$ is a C^{∞} -special Frenet curve. Let $i_p \in \{1, 2, \ldots, N-1\}$, where $p \in \{1, \ldots, m\}$ and $m \in \{1, 2, \ldots, N-1\}$. Denote by n_{i_p} the i_p -th unit normal vector field of the curve C. Then, the curve C is called a (i_1, \ldots, i_m) -Bertrand curve if there exists a distinct C^{∞} -special Frenet curve,

$$\bar{C}(s) = C(s) + \sum_{p=1}^{m} \alpha_{i_p}(s) \cdot n_{i_p}(s),$$
(1)

such that the Frenet (i_1, \ldots, i_m) -normal planes at C(s) and $\overline{C}(s)$ coincide for all $s \in I$.

For our convenience, we call a (i_1, \ldots, i_m) -Bertrand curve the generalized Bertrand curves, and we always let $1 \le i_1 < i_2 < \ldots < i_m \le N-1$.

2 Theorem. If a C^{∞} -special Frenet curve in \mathbb{R}^N is a generalized Bertrand curve, then it must be the type of $(1, i_2, \ldots, i_m)$ -Bertrand curve.

3 Remark. The generalized Bertrand curves still keep certain geometric properties. For example, by a straightforward computation, one can verify that the distance between a generalized Bertrand curve and its mate (offset) along the curve remains constant. For geometric properties of (1,3)-Bertrand curves in \mathbb{R}^4 , the reader is referred to [4]. For generalized Bertrand curves in \mathbb{R}^N , we leave the discussion to our future work.

2 Proofs

We will argue by contradiction. Namely, we assume that the C^{∞} -special Frenet curve C in \mathbb{R}^N is a (i_1, \ldots, i_m) -Bertrand curve with $i_1 \geq 2$, then a

contradiction would happen.

Denote by $\bar{s} = \varphi(s)$ the arc-length parameter of \bar{C} . Let

$$K_{j,i}(s) = -k_i(s)\delta_j^{i-1} + k_{i+1}(s)\delta_j^{i+1},$$
(2)

where δ_j^i is the Kronecker's delta and k_i are higher curvatures of \mathbb{R}^N if $i \in \{1, \ldots, N-1\}$; otherwise $k_i = 0$ (see [2]). Then the Frenet equations can be written as

$$n_i'(s) = \sum_{j=0}^{N-1} K_{j,i}(s) n_j(s),$$
(3)

where $n_0(s) = t(s)$ and $i \in \{0, ..., N-1\}$. By differentiating (1) with respect to s, we obtain

$$\varphi'(s) \cdot \bar{n}_0(s) = \bar{C}'(s)$$

$$= n_0(s) + \sum_{p=1}^m \alpha'_{i_p}(s) \cdot n_{i_p}(s) + \sum_{j=0}^{N-1} \sum_{p=1}^m K_{j,i_p}(s) \cdot \alpha_{i_p}(s) \cdot n_j(s)$$

$$= \sum_{j=0}^{N-1} \beta_j(s) n_j(s),$$
(4)

where n_0 and \bar{n}_0 denote the unit tangent vectors of C and \bar{C} respectively. Since by assumption the normal plane spanned by $\bar{n}_{i_1}(s), \ldots, \bar{n}_{i_m}(s)$ coincides with the one spanned by $n_{i_1}(s), \ldots, n_{i_m}(s)$, there exists a matrix $T(s) \in O(m)$ such that

$$(\bar{n}_{i_1}(s),\ldots,\bar{n}_{i_m}(s))^t = T(s)(n_{i_1}(s),\ldots,n_{i_m}(s))^t,$$

for all $s \in I$. In other words,

$$\bar{n}_{i_q}(s) = \sum_{p=1}^{m} T_{qp}(s) n_{i_p}(s),$$
(5)

where T_{qp} is the (q, p)-th entry of the matrix T. Thus by (4) and (5), we have

$$0 = \langle \varphi'(s) \cdot \bar{n}_0(s), \bar{n}_{i_q}(s) \rangle = \sum_{p=1}^m T_{qp}(s) \langle \sum_{j=0}^{N-1} \beta_j(s) \cdot n_j(s), n_{i_p}(s) \rangle$$

= $\sum_{p=1}^m T_{qp}(s) \beta_{i_p}(s),$ (6)

for each fixed $q \in \{1, 2, ..., m\}$. Since det $T(s) = \pm 1 \neq 0$, it follows from (4) and (6) that

$$0 = \beta_{i_q}(s) = \alpha'_{i_q}(s) + \sum_{p=1}^{m} K_{i_q, i_p}(s) \cdot \alpha_{i_p}(s),$$
(7)

for each $q \in \{1, 2, ..., m\}$. By (4),

$$\bar{n}_{0}(s) = \frac{1}{\varphi'(s)} n_{0}(s) + \sum_{p=1}^{m} \frac{1}{\varphi'(s)} \alpha'_{i_{p}}(s) \cdot n_{i_{p}}(s) + \sum_{j=0}^{N-1} \sum_{p=1}^{m} \frac{1}{\varphi'(s)} K_{j,i_{p}}(s) \cdot \alpha_{i_{p}}(s) \cdot n_{j}(s).$$
(8)

By differentiating (8) with respect to s, we obtain

$$\begin{aligned} \varphi'(s) \cdot \bar{k}_{1}(s) & \cdot \bar{n}_{1}(s) \\ &= \left(\frac{1}{\varphi'(s)}\right)' n_{0}(s) + \frac{1}{\varphi'(s)} k_{1}(s) n_{1}(s) + \sum_{p=1}^{m} \left(\frac{1}{\varphi'(s)} \alpha'_{i_{p}}(s)\right)' n_{i_{p}}(s) \\ &+ \sum_{j=1}^{N-1} \left(\sum_{p=1}^{m} \frac{1}{\varphi'(s)} K_{j,i_{p}}(s) \cdot \alpha'_{i_{p}}(s)\right) \cdot n_{j}(s) \\ &+ \sum_{j=1}^{N-1} \left(\sum_{p=1}^{m} \frac{1}{\varphi'(s)} K_{j,i_{p}}(s) \cdot \alpha_{i_{p}}(s)\right)' \cdot n_{j}(s) \\ &+ \sum_{j=0}^{N-1} \left(\sum_{p=1}^{m} \frac{1}{\varphi'(s)} [K_{j-1,i_{p}}(s) \cdot k_{j}(s) - K_{j+1,i_{p}}(s) \cdot k_{j+1}(s)] \cdot \alpha_{i_{p}}(s)\right) \cdot n_{j}(s) \end{aligned}$$

$$= \sum_{j=0}^{N-1} \gamma_{j}(s) \cdot n_{j}(s), \end{aligned}$$
(9)

where $k_N = 0$. By (9), (5) and assuming $i_q \ge 2$ for all $q \in \{1, 2, \dots, m\}$, we have

$$0 = \langle \varphi'(s)\bar{k}_1(\varphi(s))\bar{n}_1(\varphi(s)), \bar{n}_{i_q}(\varphi(s)) \rangle = \sum_{p=1}^m T_{qp}(s)\gamma_{i_p}(s).$$
(10)

Since det $T(s) = \pm 1 \neq 0$, it follows from (9) and (10) that

$$0 = \gamma_{i_q}(s) = \left(\frac{1}{\varphi'(s)}\alpha'_{i_q}(s)\right)' + \sum_{p=1}^{m}\frac{1}{\varphi'(s)}K_{i_q,i_p}(s)\alpha'_{i_p}(s) + \sum_{p=1}^{m}\left(\frac{1}{\varphi'(s)}K_{i_q,i_p}(s)\alpha_{i_p}(s)\right)' + \sum_{p=1}^{m}\frac{1}{\varphi'(s)}\left(K_{-1+i_q,i_p}(s)k_{i_q} - K_{1+i_q,i_p}(s)k_{1+i_q}\right)\alpha_{i_p}(s),$$
(11)

for all $q \in \{1, 2, ..., m\}$. Below we omit the arc-length parameter s of C without confusion. Denote by $A = (\alpha_{i_1}, ..., \alpha_{i_m})^t$, and let $B = (B_{lp})$, and $R = (R_{lp})$ to be

$$B_{lp} = K_{i_l, i_p},\tag{12}$$

$$R_{lp} = K_{-1+i_l, i_p} k_{i_l} - K_{1+i_l, i_p} k_{1+i_l}.$$
(13)

Then (7) and (11) can be written respectively as

$$A' + BA = 0, \tag{14}$$

$$\left(\frac{1}{\varphi'}A'\right)' + \frac{1}{\varphi'}BA' + \left(\frac{1}{\varphi'}BA\right)' + \frac{1}{\varphi'}RA = 0.$$
(15)

Substituting A' by -BA in (15), we can simplify (15) as

$$(R - B^2)A = 0. (16)$$

4 Lemma. The $m \times m$ matrix $R - B^2$ is symmetric and can be written as

$$\begin{pmatrix} D_1 + F_1 & N_1 & 0 & \cdots & \cdots & 0 \\ N_1 & D_2 + F_2 & N_2 & \ddots & \ddots & \vdots \\ 0 & N_2 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & N_{m-2} & 0 \\ \vdots & \ddots & \ddots & N_{m-2} & D_{m-1} + F_{m-1} & N_{m-1} \\ 0 & \cdots & \cdots & 0 & N_{m-1} & D_m + F_m \end{pmatrix},$$

where

$$\begin{cases}
D_q = K_{i_{q-1},i_q}^2 - k_{i_q}^2, \\
F_q = K_{i_q,i_{q+1}}^2 - k_{1+i_q}^2, \\
N_q = K_{-1+i_{q+1},i_q} k_{i_{q+1}},
\end{cases}$$
(17)

and we let $K_{i_p,i_q} = 0$, if i_p or i_q is not defined.

PROOF. From (12), it is obvious that $B^t = -B$, thus B^2 is symmetric. By applying (13), (12) and (2), it is easy to verify that the matrix R is symmetric and to compute all entries of $R - B^2$. We leave it to the reader.

We can decompose the matrix $R - B^2$ into a sum of matrices. Namely,

$$R - B^{2} = \sum_{q=1}^{m+1} E_{q}$$

$$= \begin{pmatrix} D_{1} & 0 & \cdots & \cdots & 0\\ 0 & 0 & \ddots & \ddots & \vdots\\ \vdots & \ddots & \ddots & \ddots & \vdots\\ 0 & \cdots & \cdots & 0 \end{pmatrix} + \begin{pmatrix} 0 & \cdots & \cdots & 0\\ \vdots & \ddots & \ddots & \ddots & \vdots\\ \vdots & \ddots & \ddots & \ddots & \vdots\\ \vdots & \ddots & \ddots & 0 & 0\\ 0 & \cdots & \cdots & 0 & F_{m} \end{pmatrix}$$

$$+ \sum_{q=2}^{m} \begin{pmatrix} 0 & \cdots & \cdots & \cdots & \cdots & 0\\ \vdots & \vdots & \cdots & \cdots & \ddots & \vdots\\ \vdots & \vdots & F_{q-1} & N_{q-1} & \vdots & \vdots\\ \vdots & \vdots & N_{q-1} & D_{q} & \vdots & \vdots\\ \vdots & \ddots & \cdots & \cdots & 0 \end{pmatrix}.$$

5 Lemma. For each fixed $q \in \{1, ..., m+1\}$ and $X = (x_1, ..., x_m)^t$,

$$\langle E_q X, X \rangle \le 0.$$
 (18)

PROOF. It is easy to verify (18) by using (17) and (2). We leave it to the reader. \$\$QED\$

Observe that Lemma 5 and (16) imply

$$\langle E_q A, A \rangle = 0,$$

for each fixed q.

6 Lemma. (i) Assume $i_{q+1} - i_q \ge 3$. Then, $\alpha_{i_q} = 0 = \alpha_{i_{q+1}}$.

- (ii) Assume $i_{q+1} i_q = 2$. Then, $\alpha_{i_q} = 0$ if and only if $\alpha_{i_{q+1}} = 0$.
- (iii) Assume $i_{q+1} i_q = 1$. Then, $\alpha_{i_{q-1}} = 0 = \alpha_{i_q}$ implies $\alpha_{i_{q+1}} = 0$, where we set $\alpha_{i_0} = 0$.

PROOF. Case (i): $i_{q+1} - i_q \ge 3$. From

$$0 = \langle E_{q+1}A, A \rangle = -[(k_{1+i_q}\alpha_{i_q})^2 + (k_{i_{q+1}}\alpha_{i_{q+1}})^2],$$

it follows that

$$k_{1+i_q}\alpha_{i_q} = 0 = k_{i_{q+1}}\alpha_{i_{q+1}}.$$

Thus $\alpha_{i_q} = 0 = \alpha_{i_{q+1}}$.

Case (ii): $i_{q+1} - i_q = 2$. From

$$0 = \langle E_{q+1}A, A \rangle = -(k_{1+i_q}\alpha_{i_q} - k_{i_{q+1}}\alpha_{i_{q+1}})^2,$$

it follows that

$$k_{1+i_q}\alpha_{i_q} = k_{i_{q+1}}\alpha_{i_{q+1}}.$$

Thus $\alpha_{i_q} = 0$ if and only if $\alpha_{i_{q+1}} = 0$.

Case (iii): $i_{q+1} - i_q = 1$. By (7), we have

$$-\alpha'_{i_q} = K_{i_q, i_{q-1}} \alpha_{i_{q-1}} - k_{i_{q+1}} \alpha_{i_{q+1}}.$$

By assuming $\alpha_{i_{q-1}} = 0 = \alpha_{i_q}$, it follows that $\alpha_{i_{q+1}} = 0$.

QED

PROOF OF THEOREM 2. By $\langle E_1 A, A \rangle = 0$, we obtain $k_{i_1}^2 \alpha_{i_1}^2 = 0$. Hence, $\alpha_{i_1} = 0$. Then, by applying Lemma 6 inductively, we obtain $\alpha_{i_2} = \cdots = \alpha_{i_m} = 0$. This implies that \overline{C} coincides with C, which is a contradiction.

Acknowledgements. The authors would like to thank Prof. Yen-Chi Lin in our department for helpful suggestion.

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