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based on competing risks grouped data**

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# Bayesian estimation of the Weibull parameters based on competing risks grouped data

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Based on the competing risks grouped data, Bayesian estimation approach is considered for the parameters of the Weibull distribution and the related specific hazard and survival functions. The estimation procedures are carried out under the square error loss (SELF) and linear exponential loss (LINEX) functions. High posterior (HPD) credible intervals for the specified parameters are also obtained. The derived estimators are in explicit closed forms. Their properties and performance are illustrated through an application to real lifetime's data and an extended simulation study. Overall results indicate that, the Bayesian estimators are dominated other estimators obtained by other methods and are recommended when continuous life testing is not available.

**keywords:** Weibull distribution, competing risks, grouped data, loss function, HPD credible interval.

## 1 Introduction

In reliability and survival analysis subjects may be at risk of failure due to more than one cause, giving rise of what is known as competing risks analysis. Problems related with competing risks are extensively involved in reliability systems, medicine, engineering, economics and many other fields of studies that concerns with lifetime distribution of a

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unit (individual, item, system) subject to several failure modes. Statistical inference for the parameters of the lifetime models using different censoring schemes with competing risks data are considered by many authors. Examples are Sarhan (2007); Alwaseel (2009); Josmar and Jorge (2011); Shai and Wu (2016); Lai and Murthy (2003).

In many real practical settings, continuous monitoring the test units to have the required lifetimes data is not available, incorporate specific measurement errors, costly and needs hard efforts or not feasible in some situations. Therefore, it is more probable to inspect the units periodically for failure. Hence, the time line is initially divided into adjacent intervals to have the interval grouped data which consists of the numbers of failed or censored units in the given intervals. This type of data is frequently used in many areas of reliability and survival analysis. The Maximum likelihood estimation using a general interactive optimizer and grouped data is considered in Gove and Fairweather (1989). Pipper and Ritz (1989) have checked the grouped data for the Cox model. Aludaat et al. (2008) derived estimators of the Burr type X distribution parameters using the grouped data. Migdadi and Al-Batah (2014) investigated the Bayesian approach for the Weibull distribution based on the interval grouped data.

The Weibull distribution proposed initially by Weibull (1951), for describing the fatigue failures from the wear out materials. Recently, it has extensive applications in modeling a variety of real lifetimes data. Applications of the Weibull distribution are mainly addressed in Lowe and Lewis (1983); Yazhou et al. (1995); Lai et al. (2017); Rinne (2009); Mudholkar and Asubonteng (2010).

Consider the life testing experiment in which  $n$  units are put in the test for failure and are exposed to  $m$  possible risks. If the  $i^{th}$  cause of failure comes from the Weibull model with common shape parameter  $\gamma$  and scale parameters  $\lambda_i$ ,  $i = 1, 2, \dots, m$ . Then the specific survival and hazard function for the  $i^{th}$  mode are:

$$S_i(t) = e^{-\lambda_i t^\gamma} \quad (1)$$

$$h_i(t) = \gamma \lambda_i t^{\gamma-1}, \gamma > 0, \lambda_i > 0, i = 1, 2, \dots, m \quad (2)$$

If the lifetime of the unit comes from only one of the independent competing risks, then the overall survival and hazard functions are:

$$S(t) = \prod_{i=1}^m S_i(t) = e^{-\sum_{i=1}^m \lambda_i t^\gamma} = e^{-\lambda t^\gamma} \quad (3)$$

$$h(t) = \sum_{i=1}^m h_i(t) = \gamma (\sum_{i=1}^m \lambda_i) t^{\gamma-1} = \gamma \lambda t^{\gamma-1} \quad (4)$$

where  $\lambda = \sum_{i=1}^m \lambda_i$ .

Maximum likelihood and type moment Estimators of the Weibull parameters using competing risks grouped data are studied by David and Moeschberger (1978) and Lianfen and Jose (2003). Yanez et al. (2014) have studied the characteristics of two competing risks models with Weibull distributed risks. Iskandar and Gondokaryono (2016) considered Bayesian analysis approach for the competing risk models in reliability systems

using a Weibull distribution. Dey et al. (2016) considered Bayesian analysis of the modified Weibull distribution under progressively censored competing risk model. Bayesian inferences for the Weibull and other lifetimes models are also included in Prakash (2014), Pak and Chatrabgoun (2016), Tahir et al. (2017) and Pak and Rastogi (2018).

Statistical selection procedures are used in a variety of applications to select the best of a finite set of alternatives. “Best” is defined with respect to the (largest or smallest) mean, where the mean is inferred with statistical sampling, as in simulation optimization. Many sequential selection procedures are proposed to select a good design when the number of alternatives is large, see Alrefaei and Almomani (2007); Almomani and Alrefaei (2012); Almomani and R.AbdulRahman (2012); Almomani and Alrefaei (2016); Al-Salem et al. (2017); Almomani et al. (2018).

The aim of this paper is to obtain Bayesian estimators of the Weibull parameters using the competing risks grouped data. In the next section based on the grouped data, the likelihood function of the parameters is formulated. In Section 3 the specific priors of the parameters are proposed to construct the posterior functions and in Section 4 the loss functions are defined. The Bayesian estimation procedures are performed under the squared loss function in Section 5 and under the linear exponential loss function in Section 6. High posterior credible intervals for the specific parameters are obtained in Section 7. To illustrate the properties and performance of the Bayesian estimators, real lifetimes data are applied to the theoretical results with a simulation study in Section 8. Finally, conclusions about the overall work are explored in Section 9.

## 2 The Likelihood Function

Let the time scale line divided into  $k$  non overlapping intervals by the cut points  $\tau_0 < \tau_1 < \dots < \tau_k$  to form the intervals  $I_j = [\tau_{j-1}, \tau_j)$ ,  $j = 1, 2, \dots, k$  where  $\tau_0$  is the initial time of the life testing experiment and  $\tau_k$  is the termination time. Let  $f_{ij}$  be the number of failure units in the intervals  $I_j$ ,  $j = 1, 2, \dots, k$  from mode  $i$ ,  $i = 1, 2, \dots, m$ . Define;  $P_{ij}(\lambda_i) = P(\text{unit fails due to the } i^{\text{th}} \text{ risk in } I_j), j = 1, 2, \dots, k$ . Then

$$P_{ij}(\lambda_i) = \int_{\tau_{j-1}}^{\tau_j} h_i(t)S(t)dt = e^{-\lambda_i\tau_{j-1}^\gamma} - e^{-\lambda_i\tau_j^\gamma}, \tag{5}$$

where  $i = 1, 2, \dots, m$  and  $j = 1, 2, \dots, k$ .

This implies the contribution of  $f_{ij}$  to the likelihood function of  $\lambda_i$ ,  $i = 1, 2, \dots, m$  is

$$L_1(\lambda_1, \lambda_2, \dots, \lambda_m \setminus f_{ij}) \propto \prod_{i=1}^m \prod_{j=1}^k (P_{ij}(\lambda_i))^{f_{ij}}$$

Let  $c_{ij}$  be the number of units lost to follow up or censored in the interval  $I_j$  from mod  $i$ ,  $i = 1, 2, \dots, m$  and  $j = 1, 2, \dots, k$  (These units are assumed to be survival at least half of the giving interval). This implies  $R = n - \sum_{j=1}^k \sum_{i=1}^m (f_{ij} + c_{ij})$  is the total number of units still alive at the termination time  $\tau_k$ . The contribution of  $c_{ij}$ ,  $i = 1, 2, \dots, m$ ,  $j = 1, 2, \dots, k$  and  $R$  to the likelihood function of  $\lambda_i$ ,  $i = 1, 2, \dots, m$  is

$$L_2(\lambda_1, \lambda_2, \dots, \lambda_m \setminus c_j, R) \propto \left( \prod_{i=1}^m \prod_{j=1}^k e^{-c_{ij} \lambda_i m_j^\gamma} \right) e^{-\lambda R \tau_k^\gamma}$$

$$= e^{-\sum_{i=1}^m \sum_{j=1}^k \lambda_i c_{ij} m_j^\gamma - \lambda R \tau_k^\gamma}$$

Where  $m_j, j = 1, 2, \dots, k$  are the mid interval times. Substituting for  $P_{ij}(\lambda_i)$  from (5), the overall likelihood function is

$$L(\lambda_1, \lambda_2, \dots, \lambda_m \setminus cgdata) \propto L_1(\lambda_1, \lambda_2, \dots, \lambda_m) L_2(\lambda_1, \lambda_2, \dots, \lambda_m) =$$

$$\prod_{i=1}^m \prod_{j=1}^k (e^{-\lambda_i \tau_{j-1}^\gamma} - e^{-\lambda_i \tau_j^\gamma}) f_{ij} e^{-\sum_{i=1}^m \sum_{j=1}^k \lambda_i c_{ij} m_j^\gamma - \lambda R \tau_k^\gamma} \tag{6}$$

Where  $cgdata$  are the competing risks grouped data and consists of  $(f_{ij}, c_j, R, \tau_j, m_j), i = 1, 2, \dots, m$  and  $j = 1, 2, \dots, k$ .

### 3 The Prior and The Posterior functions

For each independent specific cause of failure, let the prior of the scale parameter  $\lambda_i$  be the *Gamma* $(a_i, b_i)$  distribution given by

$$\pi_i(\lambda_i) = \frac{b_i^{a_i}}{\Gamma(a_i)} (\lambda_i)^{a_i-1} e^{-b_i \lambda_i}, a_i \geq 1, b_i > 0, i = 1, 2, \dots, m$$

Then the joint prior of  $\lambda_i, i = 1, 2, \dots, m$  is

$$\pi(\lambda_1, \lambda_2, \dots, \lambda_m) = \prod_{i=1}^m \pi_i(\lambda_i) \propto \left( \prod_{i=1}^m (\lambda_i)^{a_i-1} \right) e^{-\sum_{i=1}^m b_i \lambda_i} \tag{7}$$

Combining the likelihood function and the joint prior, the joint posterior function of  $\lambda_i, i = 1, 2, \dots, m$  and the  $cgdata$  is

$$\pi(\lambda_1, \lambda_2, \dots, \lambda_m, cgdata) = \frac{L(\lambda_1, \lambda_2, \dots, \lambda_m \setminus cgdata) \pi(\lambda_1, \lambda_2, \dots, \lambda_m)}{M} \tag{8}$$

Where

$$M = \int_0^\infty \int_0^\infty \dots \int_0^\infty L(\lambda_1, \lambda_2, \dots, \lambda_m \setminus cgdata) \pi(\lambda_1, \lambda_2, \dots, \lambda_m) d\lambda_1 d\lambda_2 \dots d\lambda_m$$

is the marginal function of  $\lambda_i, i = 1, 2, \dots, m$ . Substituting for  $L(\lambda_1, \lambda_2, \dots, \lambda_m \setminus cgdata)$  and  $\pi(\lambda_1, \lambda_2, \dots, \lambda_m)$  in (8),  $\pi(\lambda_1, \lambda_2, \dots, \lambda_m, cgdata)$  involved highly complicated integrals. Therefore, we approximate  $\prod_{i=1}^m \prod_{j=1}^k (e^{-\lambda_i \tau_{j-1}^\gamma} - e^{-\lambda_i \tau_j^\gamma}) f_{ij}$  mathematically in both numerator and denominator of (8) as the following:

$$\prod_{i=1}^m \prod_{j=1}^k (e^{-\lambda_i \tau_{j-1}^\gamma} - e^{-\lambda_i \tau_j^\gamma})^{f_{ij}} = \prod_{i=1}^m \prod_{j=1}^k (e^{-\lambda_i \tau_{j-1}^\gamma} (1 - e^{-\lambda_i (\tau_j^\gamma - \tau_{j-1}^\gamma)}))^{f_{ij}}$$

Using the local linear approximation:

$$\prod_{j=1}^k (1 - e^{-\lambda_i (\tau_j^\gamma - \tau_{j-1}^\gamma)})^{f_{ij}} \approx \prod_{j=1}^k (\lambda_i (\tau_j^\gamma - \tau_{j-1}^\gamma))^{f_{ij}}$$

Setting:

$$Z_j = \tau_j^\gamma - \tau_{j-1}^\gamma, Y_i = \sum_{j=1}^k f_{ij} \tau_j, N_i = \sum_{j=1}^k f_{ij}, W_i = c_{ij} m_j^\gamma + R \tau_k^\gamma$$

$$W = \left( \sum_{i=1}^m \sum_{j=1}^k c_{ij} m_j^\gamma \right) + R \tau_k^\gamma$$

Implies, the joint posterior function becomes

$$\pi(\lambda_1, \lambda_2, \dots, \lambda_m, cgdata) \propto \frac{\prod_{i=1}^m (\lambda_i)^{N_i+a_i-1} e^{-\sum_{i=1}^m (b_i+Y_i)\lambda_i} e^{-\lambda W}}{\int_0^\infty \int_0^\infty \dots \int_0^\infty \prod_{i=1}^m (\lambda_i)^{N_i+a_i-1} e^{-\sum_{i=1}^m (b_i+Y_i)\lambda_i} e^{-\lambda W} d\lambda_1 d\lambda_2 \dots d\lambda_m} \tag{9}$$

Integrating the numerator and denominator of  $\pi(\lambda_1, \lambda_2, \dots, \lambda_m, cgdata)$  with respect to  $\lambda_i, j \neq i, 1, 2, \dots, (m - 1)$  the marginal posterior function of each of the parameters  $\lambda_i, i = 1, 2, \dots, m$  is

$$\pi_i(\lambda_i, cgdata) \propto \frac{(\lambda_i)^{N_i+a_i-1} e^{-(b_i+Y_i+W_i)\lambda_i}}{\int_0^\infty (\lambda_i)^{N_i+a_i-1} e^{-(b_i+Y_i+W_i)\lambda_i} d\lambda_i} \tag{10}$$

Clearly,  $\pi(\lambda_1, \lambda_2, \dots, \lambda_m, cgdata) = \prod_{i=1}^m \pi_i(\lambda_i, cgdata)$  and  $\pi_i(\lambda_i, cgdata)$  is the Gamma  $(N_i + a_i, b_i + Y_i + W_i)$  distribution. Thus  $\pi_i(\lambda_i)$  can be considered as a specific conjugate prior of  $\lambda_i, i = 1, 2, \dots, m$ .

### 4 Loss functions

One of the basic elements to perform Bayesian estimation procedures is to precisely identify the loss function. In this paper two loss functions will be considered. The first is the squared error loss function denoted as (SELF). This loss function is symmetric and frequently used in Bayesian estimation. The squared loss function is defined by

$$L(\delta, \theta) = (\delta - \theta)^2 \tag{11}$$

Where  $\delta$  is the Bayesian estimator of  $\theta$  and given by Berger (1985) as  $\delta = E_\theta(\Pi(\theta, data))$ .

The second symmetric loss function to be considered is the linear exponential function denoted as (LINEX) defined by

$$L(\delta, \theta) = e^{c(\delta-\theta)} - c(\delta - \theta) - 1, c \neq 0 \quad (12)$$

This loss function comes as a modification of SELF by Hamada et al. (2008) and Varian (1975). The Bayesian estimator under LINEX is given by Zellner (1986) as  $\delta = \frac{-1}{c} \ln(E_{\Pi}(e^{-c\theta}))$ .

## 5 Bayesian estimation under SELF

Based on the marginal posterior defined in (9), the Bayesian estimator of  $\lambda_i$  under SELF is the posterior mean given by

$$\widehat{\lambda}_{iBS} = \frac{\int_0^{\infty} (\lambda_i)^{N_i+a_i} e^{-(b_i+Y_i+W_i)\lambda_i} d\lambda_i}{\int_0^{\infty} (\lambda_i)^{N_i+a_i-1} e^{-(b_i+Y_i+W_i)\lambda_i} d\lambda_i} = \frac{N_i + a_i}{b_i + Y_i + W_i}, i = 1, 2, \dots, m \quad (13)$$

Consequently, the Bayesian estimators for the specific survival and hazard functions at a given time  $t$  are given respectively by

$$\widehat{S}_{iBS}(t) = \left( \frac{b_i + Y_i + W_i}{b_i + Y_i + W_i + t^\gamma} \right)^{N_i+a_i}$$

$$\widehat{h}_{iBS}(t) = \gamma t^{\gamma-1} \left( \frac{N_i + a_i}{b_i + Y_i + W_i} \right)$$

Based on the posterior in (8), the Bayesian estimator for any given function  $g(\lambda_1, \lambda_2, \dots, \lambda_m)$  under SELF is given by

$$\widehat{BS} = (E_{\Pi}(g(\lambda_1, \lambda_2, \dots, \lambda_m)))$$

Since, the population survival and the hazard functions at given time  $t$  and the parameter  $\lambda$  are all functions of  $\lambda_i, i = 1, 2, \dots, m$ . This implies their Bayesian estimators are given respectively by

$$\widehat{S}_{BS}(t) = \prod_{i=1}^m \left( \frac{b_i + Y_i + W_i}{b_i + Y_i + W_i + t^\gamma} \right)^{N_i+a_i},$$

$$\widehat{h}_{BS}(t) = \gamma t^{\gamma-1} \sum_{i=1}^m \left( \frac{N_i + a_i}{b_i + Y_i + W_i} \right), \quad (14)$$

$$\widehat{\lambda}_{BS} = \sum_{i=1}^m \left( \frac{N_i + a_i}{b_i + Y_i + W_i} \right).$$

## 6 Bayesian Estimation Under LINEX

Assuming the LINEX function with parameter  $c \neq 0$ , based on the posterior given in (8) the Bayesian estimator for any function  $g(\lambda_1, \lambda_2, \dots, \lambda_m)$  is given by

$$\widehat{BL} = \frac{-1}{c} (\ln(E_{\Pi}(e^{-cg(\lambda_1, \lambda_2, \dots, \lambda_m)})))$$

This implies, Bayesian estimators for hazard function at a given time  $t$  and the parameter  $\lambda$  are

$$\begin{aligned} \widehat{h}_{BL}(t) &= \frac{-1}{c} \sum_{i=1}^m \ln \left( \frac{b_i + Y_i + W_i}{b_i + Y_i + W_i + c\gamma t^{\gamma-1}} \right)^{N_i+a_i}, \\ \widehat{\lambda}_{BL}(t) &= \frac{-1}{c} \sum_{i=1}^m \ln \left( \frac{b_i + Y_i + W_i}{b_i + Y_i + W_i + c} \right)^{N_i+a_i}. \end{aligned} \tag{15}$$

Based on the marginal posterior given in (9), Bayesian estimators of the specific hazard functions at a given time and of the parameters  $\lambda_i, i = 1, 2, \dots, m$  are respectively

$$\begin{aligned} \widehat{h}_{iBL}(t) &= \frac{-(N_i + a_i)}{c} \ln \left( \frac{b_i + Y_i + W_i}{b_i + Y_i + W_i + c\gamma t^{\gamma-1}} \right), \\ \widehat{\lambda}_{iBL}(t) &= \frac{-(N_i + a_i)}{c} \ln \left( \frac{b_i + Y_i + W_i}{b_i + Y_i + W_i + c} \right). \end{aligned} \tag{16}$$

Clearly,  $\widehat{h}_{BL}(t) = \sum_{i=1}^m \widehat{h}_{iBL}(t), \widehat{\lambda}_{BL}(t) = \sum_{i=1}^m \widehat{\lambda}_{iBL}(t), \widehat{S}_{BS}(t) = \prod_{i=1}^m \widehat{S}_{iBS}(t), \widehat{h}_{BS}(t) = \sum_{i=1}^m \widehat{h}_{iBS}(t), \widehat{\lambda}_{BS} = \sum_{i=1}^m \widehat{\lambda}_{iBS}$ .

## 7 Credible Intervals

Another common Bayesian approach is to construct intervals for which the unknown parameters are most probably to lie. Given the marginal posterior in (9), the  $(1 - \alpha)\%$  credible interval in the form  $(c_1, c_2)$  can be obtained by solving the equation:

$$\int_{c_1}^{c_2} \Pi_i(\lambda_i, cgdata) d\lambda_i = (1 - \alpha) \tag{17}$$

To choose credible intervals for  $\lambda_i, i = 1, 2, \dots, m$ , it is desirable to minimize its size subject to condition (16) to have high posterior credible intervals (HPD). This requires

$$\Pi_i(c_1, cgdata) = \Pi_i(c_2, cgdata) \tag{18}$$

Setting  $Y = b_i + Y_i + W$ , making the transformation  $u = Y\lambda_i$  and substituting for  $\Pi_i(\lambda_i, cgdata)$  in (16) and (17). Implies  $(1 - \alpha)\%$  HPD credible intervals for  $\lambda_i$ ,



$i = 1, 2, \dots, m$  can be obtained by solving the following two equations simultaneously with respect to  $c_1, c_2$

$$I_g(Yc_2, N_i + a_i) - I_g(Yc_1, N_i + a_i) = (1 - \alpha)\Gamma(N_i + a_i)Y^{N_i + a_i} \quad (19)$$

$$\left(\frac{c_1}{c_2}\right)^{N_i + a_i - 1} = e^{-Y(c_1 - c_2)} \quad (20)$$

Where  $I_g(x, y)$  is the incomplete gamma function defined as :

$$I_g(x, y) = \frac{1}{\Gamma(y)} \int_0^x t^{y-1} e^{-t} dt$$

## 8 Application and Simulation Study

To illustrate found out theoretical results, the Bayesian estimation is applied to real lifetime's data. Furthermore an extended simulation study with different settings is also conducted.

### 8.1 Application to Real Lifetimes Data

The following data are times to failure measured in millions of operations of 42 Mechanical devises from Chambers et al. (1983) in two types of switches.

**Type 1:** 1.499 1.667 1.695 1.710 1.965 2.109 2.135 2.197 2.227 2.254 2.369 2.547 2.548 2.794 2.883\* 2.910\* 3.015\* 3.017 3.793\*

**Type 2:** 1.151 1.170 1.248 1.331 1.381 1.508 1.534 1.577 1.584 2.012 2.051 2.076 2.116 2.119 2.199 2.250 2.261 2.349 2.738 2.883\* 2.883\* 3.793\*

where the  $n^*$  numbers represents censored life times.

The data are fit to Weibull distributions with common shape parameter  $\gamma = 2$  using Minitab, at significance level  $\alpha = 0.05$ , the maximum likelihood estimators using the complete ungrouped data are  $\hat{\lambda}_1 = 0.17009$  for Type 1 and  $\hat{\lambda}_2 = 0.22216$  for Type 2. The data are then grouped into 5 intervals with fixed length = 0.4 with initial time  $\tau_0 = 1$  and termination time  $\tau_5 = 3$ . After computing the number of failures and censored observations  $f_{ij}, c_{ij}, i = 1, 2, j = 1, 2, \dots, 5$  we identify the specific priors with parameters  $(a_1 = 3, b_1 = 1)$  for Type 1 and  $(a_2 = 4, b_2 = 1)$ . The following results are computed for the Bayesian estimators under SELF:  $\widehat{\lambda}_{1BS} = 0.17040$ ,  $\widehat{\lambda}_{2BS} = 0.21819$  and the Bayesian estimators under LINEX when  $c = 2$  are:  $\widehat{\lambda}_{1BL} = 0.16914$ ,  $\widehat{\lambda}_{2BL} = 0.21639$ . Clearly the Bayesian estimators using the grouped data are very close to their corresponding maximum likelihood estimators using the ungrouped data, the maximum absolute difference between their values not exceeds 0.00573 when we use LINEX and 0.00397 when we use SELF. Using Minitab, the 95% asymptotic confidence intervals for  $\lambda_1, \lambda_2$  are (0.109728, 0.263625), (0.14763, 0.34051) respectively. The 95% HPD credible intervals for  $\lambda_1, \lambda_2$  are (0.112781, 0.263726), (0.147832, 0.33981) which are better than their correspondence asymptotic confidence intervals with respect to

their lengths. Table 1 and Table 2 represent the Bayesian estimators for the specific survival and hazard functions with their corresponding maximum likelihood estimators of the hazard functions  $\hat{h}_{1mle}$ ,  $\hat{h}_{2mle}$  and the survival functions  $\hat{S}_{1mle}$ ,  $\hat{S}_{2mle}$  using the ungrouped data at the end interval points for the two types of mechanical devices.

As it appears from the Tables 1 and 2, the Bayesian estimators for both the specific hazard and survival functions are also very close to their corresponding maximum likelihood estimators using the complete ungrouped data.

Taking into account that there is a specific loss of information in the exact life times when using the grouped data, the obtained Bayesian estimators indicates a high performance when using the competing risks grouped data.

## 8.2 Simulation

Because the maximum likelihood estimators using the complete ungrouped data incorporate specific standard errors rates. In this section, using Matlab a Monte Carlo simulation study by proposing the true values of the parameters is conducted. Three modes of failure are considered with common shape parameter  $\gamma = 1.5$  for the first setting,  $\gamma = 1$  for the second setting and  $\gamma = 0.8$  for the third setting. The proposed scale parameters are  $\lambda_1 = 0.1$ ,  $\lambda_2 = 0.15$ ,  $\lambda_3 = 0.20$  with sample sizes  $n = 45, 72, 102$  are generated from specific Weibull models; equal size subpopulations with rate of censoring 5%, 10% and 15% are considered. The generating data are grouped into 5 intervals with fixed length equal 1.5 and 7 intervals of fixed length equal 1 for the first setting, into 6 intervals with fixed length equal 3 and 8 intervals with fixed length equal 2.5 for the second setting and into 8 intervals with fixed length equal 5 and 10 intervals with fixed length equal 4 for the third setting. The prior scale parameter is fixed  $b = 2$ , and the shape parameters are  $a_1 = 1.764$ ,  $a_2 = 2.647$ ,  $a_3 = 3.529$  respectively, the LINEX loss parameter is fixed to be  $c = 2$  in all the indices, for each setting 1000 replications of the life testing experiments are performed. The performance of the Bayesian estimators is measured in terms of their mean squared errors (MSE) and the mean percentage errors (MPE) defined respectively as:

$$MSE(\hat{\lambda}_l) = \frac{1}{1000} \sum_{i=1}^{1000} (\lambda_i - \hat{\lambda}_l)^2$$

$$MPE(\hat{\lambda}_l) = \frac{1}{1000} \sum_{i=1}^{1000} \frac{|\lambda_i - \hat{\lambda}_l|}{\lambda_i}$$

where  $\hat{\lambda}_l$  is the Bayesian estimator of  $\lambda_i$ ,  $i = 1, 2, 3$ .

The MSEs and the MPEs of the Bayesian estimators at different settings are presented in the Tables 3, 4, 5, 6, 7 and 8 where we have the following results:

1. For fixed sample size, the MSEs and the MPEs of the Bayesian estimators uniformly increasing as the values of the parameters increasing. In Table 1, as the values of the parameter increasing from 0.1 to 0.2 the MSEs increasing from 0.0076 to 0.0083

using SELF and from 0.0081 to 0.0103 using LINEX. Similarly the MPEs increasing from 0.0243 to 0.0492 using SELF and from 0.0385 to 0.0508 using LINEX.

2. Following each column in the Tables, the MSEs and the MPEs of the Bayesian decreasing as the sample sizes are increasing. Observation results also show that, the Bayesian estimators under SELF have less MSEs than the Bayesian estimators under LINEX when the sample sizes  $n = 45$  and  $n = 72$ , the converse is not true when the sample size  $n = 102$ .
3. Comparing the simulation results in Table 3 with Table 4 , Table 5 with Table 6 and Table 7 with Table 8, we realize that as the lengths of the inspection intervals decreasing and the number of intervals increasing, the Bayesian estimators become more efficient because it incorporate less MSEs and MPEs.
4. Comparing the simulation results in Table 3 and Table 4 with their corresponding results in Tables 5 and 6 and Tables 7 and 8, the Bayesian estimators are better when the shape parameter  $\gamma = 1.5$  than the Bayesian estimators when  $\gamma = 1$  and  $\gamma = 0.8$ . This assigns that the Bayesian estimation approach is more preferable for the increasing failure rate process.
5. The rate of censoring can also be one of other factors affected performance of the Bayesian approach. Results with censoring rate 5% are significantly better than the results with censoring rates 10% and 15%.
6. Generally, simulation results show that, the derived Bayesian estimators are robust with respect to both scale and shape parameters and give a high performance as compared to the maximum likelihood and type moment estimators derived by Lianfen and Jose (2003).

## 9 Conclusion

In this article, Bayesian estimation approach is devoted for the Weibull parameters and related specific hazard and survival functions. Using the competing risks grouped data, the Bayesian estimators are obtained in explicit closed forms and not needed any numerical solutions. Applying the theoretical results to real lifetimes data manifest the performance of the Bayesian estimators as compared with their corresponding ordinary maximum likelihood estimators using the complete ungrouped data. Properties of the Bayesian estimators are studied through a simulation study which illustrates the factors that affected reliability of the estimation procedures. Being not having the exact failure times, the competing risks grouped data with the Bayesian estimation is recommended when continuous monitoring the test units is not feasible, costly or incorporates specific measurement errors.

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Table 1: The estimated hazard and survival functions of Type 1 mechanical devises.

$\tau_i$	$\widehat{h}_{1mle}$	$\widehat{h}_{1BS}(t)$	$\widehat{h}_{1BL}(t)$	$\widehat{S}_{1mle}$	$\widehat{S}_{1BS}(t)$
1.4	0.4670	0.4774	0.5147	0.7782	0.7144
1.8	0.6100	0.6138	0.6433	0.7363	0.6680
2.2	0.6800	0.7501	0.7701	0.6897	0.6248
2.6	0.8840	0.8865	0.8951	0.6427	0.5845
3	1.0200	1.0229	1.0184	0.6004	0.5469

Table 2: The estimated hazard and survival functions of Type 2 mechanical devises.

$\tau_i$	$\widehat{h}_{1mle}$	$\widehat{h}_{1BS}(t)$	$\widehat{h}_{1BL}(t)$	$\widehat{S}_{1mle}$	$\widehat{S}_{1BS}(t)$
1.4	0.5392	0.5737	0.5846	0.7642	0.7515
1.8	0.8086	0.7376	0.7463	0.6681	0.6934
2.2	0.9882	0.9015	0.9058	0.6109	0.6269
2.6	1.1679	1.0654	1.0631	0.5585	0.5899
3	1.3476	1.2293	1.2183	0.5168	0.5451

Table 3: The mean squared errors and the mean percentage errors of the Bayesian estimators when the common shape parameter  $\gamma = 1.5$ , number of intervals  $k = 5$ , fixed interval length = 1.5.

$n$	Error	$\widehat{\lambda}_{1BS}$	$\widehat{\lambda}_{2BS}$	$\widehat{\lambda}_{3BS}$	$\widehat{\lambda}_{1BL}$	$\widehat{\lambda}_{2BL}$	$\widehat{\lambda}_{3BL}$	Rate of Censoring
45	MSE	0.0076	0.0079	0.0083	0.0081	0.0087	0.0103	5%
	MPE	0.0243	0.0368	0.0492	0.0385	0.0421	0.0508	
	MSE	0.0094	0.0099	0.0112	0.0108	0.0123	0.0167	10%
	MBE	0.0252	0.0387	0.0511	0.0387	0.0433	0.0510	
	MSE	0.0099	0.0108	0.0188	0.0117	0.0129	0.0132	15%
	MBE	0.0264	0.0398	0.0547	0.0390	0.0446	0.0531	
72	MSE	0.0058	0.0062	0.0076	0.0061	0.0076	0.0089	5%
	MPE	0.0238	0.0357	0.0476	0.0258	0.0374	0.0562	
	MSE	0.0087	0.0092	0.0105	0.0098	0.0101	0.0126	10%
	MBE	0.0246	0.0361	0.0488	0.0287	0.0393	0.0552	
	MSE	0.0091	0.0094	0.0112	0.0104	0.0115	0.0138	15%
	MBE	0.0251	0.0369	0.0492	0.0294	0.0407	0.0561	
102	MSE	0.0039	0.0043	0.0053	0.0034	0.0041	0.0049	5%
	MPE	0.0164	0.0243	0.0321	0.0157	0.0233	0.0244	
	MSE	0.0062	0.0078	0.0091	0.0075	0.0075	0.0084	10%
	MBE	0.0173	0.0251	0.0335	0.0168	0.0247	0.0281	
	MSE	0.0083	0.0091	0.0106	0.0081	0.0089	0.0102	15%
	MBE	0.0176	0.0261	0.0342	0.0171	0.0258	0.0287	



Table 4: The mean squared errors and the mean percentage errors of the Bayesian estimators when the common shape parameter  $\gamma = 1.5$ , number of intervals  $k = 7$ , fixed interval length = 1.

$n$	Error	$\widehat{\lambda}_{1BS}$	$\widehat{\lambda}_{2BS}$	$\widehat{\lambda}_{3BS}$	$\widehat{\lambda}_{1BL}$	$\widehat{\lambda}_{2BL}$	$\widehat{\lambda}_{3BL}$	Rate of Censoring
45	<i>MSE</i>	0.0072	0.0076	0.0079	0.0077	0.0082	0.0094	5%
	<i>MPE</i>	0.0232	0.0289	0.0411	0.0362	0.0417	0.0501	
	<i>MSE</i>	0.0087	0.0088	0.0090	0.0089	0.0097	0.0098	10%
	<i>MBE</i>	0.0239	0.0295	0.0423	0.0373	0.0431	0.0552	
	<i>MSE</i>	0.0091	0.0096	0.0104	0.0095	0.0103	0.0108	15%
	<i>MBE</i>	0.0252	0.0311	0.0439	0.0386	0.0440	0.0562	
72	<i>MSE</i>	0.0055	0.0057	0.0064	0.0058	0.0065	0.0084	5%
	<i>MPE</i>	0.0227	0.0264	0.0381	0.0326	0.0408	0.0483	
	<i>MSE</i>	0.0074	0.0078	0.0081	0.0082	0.0083	0.0090	10%
	<i>MBE</i>	0.0278	0.0283	0.0389	0.0381	0.0412	0.0493	
	<i>MSE</i>	0.0087	0.0091	0.0095	0.0083	0.0094	0.0098	15%
	<i>MBE</i>	0.0285	0.0299	0.0391	0.0392	0.0426	0.0502	
102	<i>MSE</i>	0.0034	0.0039	0.0047	0.0032	0.0038	0.0042	5%
	<i>MPE</i>	0.0211	0.0243	0.0383	0.0208	0.0239	0.0366	
	<i>MSE</i>	0.0058	0.0059	0.0063	0.0044	0.0052	0.0056	10%
	<i>MBE</i>	0.0255	0.0269	0.0388	0.0246	0.0251	0.0375	
	<i>MSE</i>	0.0062	0.0065	0.0076	0.0060	0.0062	0.0073	15%
	<i>MBE</i>	0.0268	0.0271	0.0390	0.0257	0.0293	0.0384	

Table 5: The mean squared errors and the mean percentage errors of the Bayesian estimators when the common shape parameter  $\gamma = 1$ , number of intervals  $k = 6$ , fixed interval length = 3.

$n$	Error	$\widehat{\lambda}_{1BS}$	$\widehat{\lambda}_{2BS}$	$\widehat{\lambda}_{3BS}$	$\widehat{\lambda}_{1BL}$	$\widehat{\lambda}_{2BL}$	$\widehat{\lambda}_{3BL}$	Rate of Censoring
45	MSE	0.0080	0.0082	0.0087	0.0082	0.0089	0.0105	5%
	MPE	0.0265	0.0369	0.0501	0.0380	0.0429	0.0517	
	MSE	0.0083	0.0086	0.0108	0.0089	0.0095	0.0123	10%
	MBE	0.0274	0.0388	0.0519	0.0390	0.0431	0.0521	
	MSE	0.0087	0.0104	0.0166	0.0094	0.0112	0.0129	15%
	MBE	0.0278	0.0391	0.0523	0.0397	0.0438	0.0528	
72	MSE	0.0061	0.0064	0.0081	0.0068	0.0077	0.0089	5%
	MPE	0.0254	0.0364	0.0371	0.0374	0.0423	0.0508	
	MSE	0.0072	0.0082	0.0104	0.0083	0.0091	0.0117	10%
	MBE	0.0263	0.0379	0.0502	0.0381	0.0422	0.0514	
	MSE	0.0082	0.0100	0.0158	0.0089	0.0106	0.0115	15%
	MBE	0.0267	0.0372	0.0517	0.0382	0.0426	0.0516	
102	MSE	0.0059	0.0063	0.0079	0.0058	0.0062	0.0077	5%
	MPE	0.0251	0.0347	0.0365	0.0243	0.0342	0.0358	
	MSE	0.0064	0.0068	0.0081	0.0061	0.0066	0.0083	10%
	MBE	0.0261	0.0371	0.0500	0.0257	0.0379	0.0518	
	MSE	0.0084	0.0116	0.0161	0.0081	0.0113	0.0104	15%
	MBE	0.0275	0.0364	0.0508	0.0266	0.0357	0.0492	

Table 6: The mean squared errors and the mean percentage errors of the Bayesian estimators when the common shape parameter  $\gamma = 1$ , number of intervals  $k = 8$ , fixed interval length = 2.5.

$n$	Error	$\widehat{\lambda}_{1BS}$	$\widehat{\lambda}_{2BS}$	$\widehat{\lambda}_{3BS}$	$\widehat{\lambda}_{1BL}$	$\widehat{\lambda}_{2BL}$	$\widehat{\lambda}_{3BL}$	Rate of Censoring
45	<i>MSE</i>	0.0079	0.0081	0.0085	0.0081	0.0086	0.0101	5%
	<i>MPE</i>	0.0261	0.0358	0.0498	0.0375	0.0419	0.0506	
	<i>MSE</i>	0.0081	0.0081	0.0100	0.0085	0.0091	0.0117	10%
	<i>MBE</i>	0.0262	0.0372	0.0506	0.0383	0.0422	0.0514	
	<i>MSE</i>	0.0085	0.0089	0.0106	0.0088	0.0098	0.0121	15%
	<i>MBE</i>	0.0269	0.0384	0.0511	0.0391	0.0428	0.0520	
72	<i>MSE</i>	0.0059	0.0062	0.0074	0.0066	0.0072	0.0081	5%
	<i>MPE</i>	0.0248	0.0347	0.0368	0.0369	0.0407	0.0485	
	<i>MSE</i>	0.0071	0.0079	0.0081	0.0078	0.0084	0.0096	10%
	<i>MBE</i>	0.0257	0.0362	0.0481	0.0372	0.0416	0.0505	
	<i>MSE</i>	0.0065	0.0076	0.0079	0.0071	0.0080	0.0089	15%
	<i>MBE</i>	0.0268	0.0366	0.0485	0.0377	0.0420	0.0497	
102	<i>MSE</i>	0.0055	0.0060	0.0071	0.0058	0.0067	0.0076	5%
	<i>MPE</i>	0.0242	0.0318	0.0345	0.0235	0.0308	0.0337	
	<i>MSE</i>	0.0058	0.0061	0.0073	0.0058	0.0060	0.0071	10%
	<i>MBE</i>	0.0248	0.0320	0.0351	0.0247	0.0316	0.0318	
	<i>MSE</i>	0.0059	0.0063	0.0074	0.0059	0.0061	0.0073	15%
	<i>MBE</i>	0.0251	0.0329	0.0359	0.0250	0.0321	0.0334	

Table 7: The mean squared errors and the mean percentage errors of the Bayesian estimators when the common shape parameter  $\gamma = 0.8$ , number of intervals  $k = 8$ , fixed interval length = 5.

$n$	Error	$\widehat{\lambda}_{1BS}$	$\widehat{\lambda}_{2BS}$	$\widehat{\lambda}_{3BS}$	$\widehat{\lambda}_{1BL}$	$\widehat{\lambda}_{2BL}$	$\widehat{\lambda}_{3BL}$	Rate of Censoring
45	MSE	0.0083	0.0087	0.0091	0.0086	0.0093	0.1080	5%
	MPE	0.0282	0.0377	0.0514	0.0389	0.0431	0.0521	
	MSE	0.0079	0.0092	0.0103	0.0088	0.0101	0.0112	10%
	MBE	0.0297	0.0386	0.0527	0.0391	0.0442	0.0529	
	MSE	0.0084	0.0098	0.0115	0.0093	0.0114	0.0120	15%
	MBE	0.0318	0.0395	0.0532	0.0412	0.0458	0.0534	
72	MSE	0.0064	0.0069	0.0085	0.0070	0.0081	0.0093	5%
	MPE	0.0276	0.0371	0.0506	0.0402	0.0427	0.0529	
	MSE	0.0072	0.0079	0.0083	0.0085	0.0092	0.0104	10%
	MBE	0.0295	0.0387	0.0511	0.0408	0.0433	0.0531	
	MSE	0.0076	0.0086	0.0088	0.0093	0.0097	0.0116	15%
	MBE	0.0305	0.0392	0.0524	0.0411	0.0436	0.0544	
102	MSE	0.0051	0.0058	0.0064	0.0047	0.0049	0.0058	5%
	MPE	0.0262	0.0325	0.0487	0.0249	0.0315	0.0472	
	MSE	0.0056	0.0061	0.0073	0.0051	0.0059	0.0065	10%
	MBE	0.0275	0.0327	0.0482	0.0271	0.0318	0.0476	
	MSE	0.0061	0.0067	0.0075	0.0059	0.0060	0.0068	15%
	MBE	0.0283	0.0334	0.0491	0.0275	0.0324	0.0486	

Table 8: The mean squared errors and the mean percentage errors of the Bayesian estimators when the common shape parameter  $\gamma = 0.8$ , number of intervals  $k = 10$ , fixed interval length = 4.

$n$	Error	$\widehat{\lambda}_{1BS}$	$\widehat{\lambda}_{2BS}$	$\widehat{\lambda}_{3BS}$	$\widehat{\lambda}_{1BL}$	$\widehat{\lambda}_{2BL}$	$\widehat{\lambda}_{3BL}$	Rate of Censoring
45	<i>MSE</i>	0.0080	0.0085	0.0089	0.0082	0.0088	0.0102	5%
	<i>MPE</i>	0.0274	0.0370	0.0502	0.0376	0.0428	0.0518	
	<i>MSE</i>	0.0083	0.0094	0.0103	0.0084	0.0091	0.0105	10%
	<i>MBE</i>	0.0285	0.0376	0.0522	0.0384	0.0434	0.0521	
	<i>MSE</i>	0.0085	0.0098	0.0115	0.0091	0.0097	0.0113	15%
	<i>MBE</i>	0.0291	0.0386	0.0529	0.0392	0.0439	0.0534	
72	<i>MSE</i>	0.0062	0.0067	0.0084	0.0068	0.0072	0.0091	5%
	<i>MPE</i>	0.0264	0.0355	0.0486	0.0331	0.0395	0.0492	
	<i>MSE</i>	0.0076	0.0081	0.0087	0.0078	0.0075	0.0098	10%
	<i>MBE</i>	0.0270	0.0362	0.0493	0.0345	0.0410	0.0511	
	<i>MSE</i>	0.0078	0.0084	0.0091	0.0081	0.0087	0.0106	15%
	<i>MBE</i>	0.0279	0.0368	0.0500	0.0351	0.0418	0.0523	
102	<i>MSE</i>	0.0051	0.0055	0.0061	0.0046	0.0047	0.0054	5%
	<i>MPE</i>	0.0255	0.0294	0.0489	0.0252	0.0287	0.0477	
	<i>MSE</i>	0.0054	0.0063	0.0075	0.0052	0.0061	0.0066	10%
	<i>MBE</i>	0.0259	0.0317	0.0494	0.0255	0.0293	0.0482	
	<i>MSE</i>	0.0056	0.0065	0.0076	0.0053	0.0063	0.0070	15%
	<i>MBE</i>	0.0261	0.0321	0.0502	0.0260	0.0231	0.0493	