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# Bivariate Basu-Dhar geometric model for survival data with a cure fraction 

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Under a context of survival lifetime analysis, we introduce in this paper Bayesian and maximum likelihood approaches for the bivariate Basu-Dhar geometric model in the presence of covariates and a cure fraction. This distribution is useful to model bivariate discrete lifetime data. In the Bayesian estimation, posterior summaries of interest were obtained using standard Markov Chain Monte Carlo methods in the OpenBUGS software. Maximum likelihood estimates for the parameters of interest were computed using the "maxLik" package of the R software. Illustrations of the proposed approaches are given for two real data sets.
keywords: Basu-Dhar distribution, cure fraction, discrete distributions, MCMC methods, lifetime data.

## 1. Introduction

Discrete-time survival analysis has been applied in many contexts including educational research (Singer and Willett, 1993), clinical psychology (Herzog et al., 1997) and medical studies (Scheike and Jensen, 1997). These analyses treat time to event data not as a continuous variable. Instead, it is considered discrete values in which the event of interest could occur. In this way, let $T$ be a discrete random variable that takes positive integer values $k, k=1,2,3, \ldots$, with probabilities $P(T=k)$. The survival function at time $k$ is thus defined as

$$
S(k)=P(T \geq k)=\sum_{j=k}^{\infty} P(T=j) .
$$

[^0]The discrete Weibull distribution (Nakagawa and Osaki, 1975) is widely employed in modeling and analyzing lifetime data, but a large number of new discrete distributions has been proposed by several researchers (Almalki and Nadarajah, 2014; Dewan et al., 2016; Kulasekera and Tonkyn, 1992; Roy, 2004). In a special case, we may suppose that the data consists of two lifetimes $T_{1}$ and $T_{2}$ associated with each unit. The assumption of independence between these random variables can be unrealistic since the value of one variable can influence value of the other variable. In this context, a considerable number of parametric distributions assuming continuous bivariate lifetimes is found in the literature (Block and Basu, 1974; Freund, 1961; Hawkes, 1972; Sarkar, 1987), including the presence of censoring. Considering discrete lifetimes in place of continuous lifetime observations, Basu and Dhar (1995) derived the bivariate geometric distribution as an analogue to the bivariate distribution introduced by Marshall and Olkin (1967). Achcar et al. (2016) considered the parameter estimation of the Basu-Dhar distribution using Bayesian and maximum-likelihood methods in the presence of covariates and censored data. A discussion about computational issues related to the use of the Basu-Dhar distribution in applications with complete and censored datasets is provided by Oliveira and Achcar (2018).

In the present article we consider the bivariate Basu-Dhar geometric model for survival data in presence of a cure fraction. The cure fraction models are useful to model lifetime data with long-term survivors (Boag, 1949), where it is believed that a proportion of individuals will not experience the event of interest (Lambert et al., 2007). The presence of these individuals in a data set is suggested by a Kaplan-Meier plot of the survival function showing a long and stable plateau with heavy censoring at the extreme right of the plot (Martinez et al., 2013). We implemented the statistical model under a Bayesian framework with parameter estimation based on Markov Chain Monte Carlo (MCMC) methods. In a similar context, Davarzani et al. (2015) introduced a Bayesian analysis for the bivariate geometric distribution proposed by Arnold (1975) in the presence of covariates, censored data and cure fraction using MCMC methods. Although the distribution introduced by Arnold (1975) is also derived from the bivariate distribution by Marshall and Olkin, its joint mass probability has a different formulation from the Basu-Dhar geometric distribution.

## 2. Methods

### 2.1. The Basu-Dhar bivariate geometric distribution

Let $T_{1}$ and $T_{2}$ be two random variables that represent the time to events of interest. The joint survival function of the Basu-Dhar bivariate geometric (BDBG) distribution is given by

$$
S\left(t_{1}, t_{2}\right)=P\left(T_{1}>t_{1}, T_{2}>t_{2}\right)=p_{1}^{t_{1}} p_{2}^{t_{2}} p_{3}^{\max \left(t_{1}, t_{2}\right)}
$$

where $t_{1} \geq 1$ and $t_{2} \geq 1$ are respectively discrete observations of $T_{1}$ and $T_{2}, 0<p_{1}<1$, $0<p_{2}<1$ and $0<p_{3} \leq 1$. Achcar et al. (2016) described that this function satisfies
the loss of memory property without any additional parameter restrictions, or say, for any integer $\delta>0$,

$$
P\left(T_{1}>s_{1}+\delta, T_{2}>s_{2}+\delta \mid T_{1}>s_{1}, T_{2}>s_{2}\right)=P\left(T_{1}>\delta, T_{2}>\delta\right)=\left(p_{1} p_{2} p_{3}\right)^{\delta}
$$

The respective bivariate mass function is given by

$$
P\left(T_{1}=t_{1}, T_{2}=t_{2}\right)=\left\{\begin{array}{cl}
p_{1}^{t_{1}-1}\left(1-p_{1}\right)\left(p_{2} p_{3}\right)^{t_{2}-1}\left(1-p_{2} p_{3}\right) & \text { for } T_{1}<T_{2} \\
p_{2}^{t_{2}-1}\left(1-p_{2}\right)\left(p_{1} p_{3}\right)^{t_{1}-1}\left(1-p_{1} p_{3}\right) & \text { for } T_{1}>T_{2} \\
\left(p_{1} p_{2} p_{3}\right)^{t_{1}-1}\left(1-p_{1} p_{3}-p_{2} p_{3}+p_{1} p_{2} p_{3}\right) & \text { for } T_{1}=T_{2}
\end{array}\right.
$$

The marginal distributions for $T_{k}$ are given by

$$
\begin{equation*}
P\left(T_{k}=t_{k}\right)=\left(1-p_{k} p_{3}\right)\left(p_{k} p_{3}\right)^{t_{k}-1}, \quad k=1,2 \tag{1}
\end{equation*}
$$

and the respective means are given by

$$
\begin{equation*}
E\left(T_{k}\right)=\sum_{j=1}^{\infty}\left[j \times P\left(T_{k}=j\right)\right]=\frac{1}{1-p_{k} p_{3}}, \quad k=1,2 \tag{2}
\end{equation*}
$$

We can observe that

$$
P\left(T_{1}=t_{1}, T_{2}>t_{2}\right)=\left\{\begin{array}{cll}
p_{1}^{t_{1}-1}\left(1-p_{1}\right)\left(p_{2} p_{3}\right)^{t_{2}} & \text { for } & T_{1} \leq T_{2} \\
p_{2}^{t_{2}}\left(p_{1} p_{3}\right)^{t_{1}-1}\left(1-p_{1} p_{3}\right) & \text { for } & T_{1}>T_{2}
\end{array}\right.
$$

and

$$
P\left(T_{1}>t_{1}, T_{2}=t_{2}\right)=\left\{\begin{array}{cll}
p_{1}^{t_{1}}\left(p_{2} p_{3}\right)^{t_{2}-1}\left(1-p_{2} p_{3}\right) & \text { for } & T_{1}<T_{2} \\
p_{2}^{t_{2}-1}\left(1-p_{2}\right)\left(p_{1} p_{3}\right)^{t_{1}} & \text { for } & T_{1} \geq T_{2}
\end{array}\right.
$$

Since

$$
P\left(T_{k}<t_{k}\right)=\left(1-p_{k} p_{3}\right) \sum_{j=1}^{t_{k}-1}\left(p_{k} p_{3}\right)^{j-1}=1-\left(p_{k} p_{3}\right)^{t_{k}-1}, \quad k=1,2
$$

we obtain the marginal survival function for the lifetime $k$ given by

$$
\begin{equation*}
S_{k}\left(t_{k}\right)=1-P\left(T_{k}<t_{k}\right)=\left(p_{k} p_{3}\right)^{t_{k}-1}, \quad k=1,2 \tag{3}
\end{equation*}
$$

and, from (1), the respective marginal hazard function is given by

$$
h_{k}\left(t_{k}\right)=\frac{P\left(T_{k}=t_{k}\right)}{S_{k}(t)}=\frac{\left(1-p_{k} p_{3}\right)\left(p_{k} p_{3}\right)^{t_{k}-1}}{\left(p_{k} p_{3}\right)^{t_{k}-1}}=\left(1-p_{k} p_{3}\right), \quad k=1,2
$$

Thus, the BDBG distribution is characterized by a constant hazard function.

### 2.2. Presence of right-censored data

Let us suppose that either $T_{1}$ and $T_{2}$ can be censored and that censoring is independent of the time to the events considered by the study researchers. Let us define two indicator variables, denoted by $d_{1 i}$ and $d_{2 i}$, where $d_{k i}=1$ if $t_{k i}$ is an observed lifetime and $d_{k i}=0$ if $t_{k i}$ is a censored observation, $k=1,2$ and $i=1, \ldots, n$. In this way, if a sample of size $n$ is sampled from a population of interest, the likelihood function is given by

$$
\begin{aligned}
L(\mathbf{p})= & \prod_{i=1}^{n}\left[P\left(T_{1 i}=t_{1 i}, T_{2 i}=t_{2 i}\right)\right]^{d_{1 i} d_{2 i}}\left[P\left(T_{1 i}=t_{1 i}, T_{2 i}>t_{2 i}\right)\right]^{d_{1 i}\left(1-d_{2 i}\right)} \\
& \times\left[P\left(T_{1 i}>t_{1 i}, T_{2 i}=t_{2 i}\right)\right]^{\left(1-d_{1 i}\right) d_{2 i}}\left[S\left(t_{1 i}, t_{2 i}\right)\right]^{\left(1-d_{1 i}\right)\left(1-d_{2 i}\right)},
\end{aligned}
$$

where $\mathbf{p}=\left(p_{1}, p_{2}, p_{3}\right)^{\prime}$ is the vector of parameters. Let us consider that the sample is partioned into three subsets, where $I_{0}:\left\{i \mid t_{1 i}=t_{2 i}=t_{i}\right\}, I_{1}:\left\{i \mid t_{1 i}<t_{2 i}\right\}$ and $I_{2}$ : $\left\{i \mid t_{1 i}>t_{2 i}\right\}$. The likelihood function can be thus written by

$$
\begin{equation*}
L(\mathbf{p})=\prod_{i \in I_{0}} L_{0}\left(\mathbf{p}, \mathbf{w}_{i}\right) \prod_{i \in I_{1}} L_{1}\left(\mathbf{p}, \mathbf{w}_{i}\right) \prod_{i \in I_{2}} L_{2}\left(\mathbf{p}, \mathbf{w}_{i}\right), \tag{4}
\end{equation*}
$$

where $\mathbf{w}_{i}=\left(t_{1 i}, d_{1 i}, t_{2 i}, d_{2 i}\right)^{\prime}$ and the components $L_{0}\left(\mathbf{p}, \mathbf{w}_{i}\right), L_{1}\left(\mathbf{p}, \mathbf{w}_{i}\right)$ and $L_{2}\left(\mathbf{p}, \mathbf{w}_{i}\right)$ are respectively given by

$$
\begin{aligned}
& L_{0}\left(\mathbf{p}, \mathbf{w}_{i}\right)= p_{1}^{t_{i}-d_{1 i}} p_{2}^{t_{i}-d_{2 i}} p_{3}^{t_{i}-d_{1 i} d_{2 i}}\left(1-p_{1}\right)^{d_{1 i}\left(1-d_{2 i}\right)}\left(1-p_{2}\right)^{\left(1-d_{1 i}\right) d_{2 i}} \\
& \times\left(1-p_{1} p_{3}-p_{2} p_{3}+p_{1} p_{2} p_{3}\right)^{d_{1 i} d_{2 i}}, \\
& L_{1}\left(\mathbf{p}, \mathbf{w}_{i}\right)=p_{1}^{t_{1 i}-d_{1 i}}\left(1-p_{1}\right)^{d_{1 i}}\left(p_{2} p_{3}\right)^{t_{2 i}-d_{2 i}}\left(1-p_{2} p_{3}\right)^{d_{2 i}}
\end{aligned}
$$

and

$$
L_{2}\left(\mathbf{p}, \mathbf{w}_{i}\right)=p_{2}^{t_{2 i}-d_{2 i}}\left(1-p_{2}\right)^{d_{2 i}}\left(p_{1} p_{3}\right)^{t_{1 i}-d_{1 i}}\left(1-p_{1} p_{3}\right)^{d_{1 i}}
$$

From (4), the log-likelihood function is given by

$$
\ln L(\mathbf{p})=\sum_{i \in I_{0}} \ln L_{0}\left(\mathbf{p}, \mathbf{w}_{i}\right)+\sum_{i \in I_{1}} \ln L_{1}\left(\mathbf{p}, \mathbf{w}_{i}\right)+\sum_{i \in I_{2}} \ln L_{2}\left(\mathbf{p}, \mathbf{w}_{i}\right) .
$$

Based on this expression, maximum likelihood and Bayesian estimators of the parameters $p_{1}, p_{2}$ and $p_{3}$ were developed and compared by Achcar et al. (2016).

### 2.3. The cure fraction model

The survival function of the standard mixture cure fraction model has the form

$$
\begin{equation*}
S_{C}(t)=\theta+(1-\theta) S(t)=1-(1-\theta) F(t), \tag{5}
\end{equation*}
$$

where $\theta$ is a parameter which represents the proportion of "long-term survivors" or "cured" individuals, regarding the event of interest $(0<\theta<1), S(t)$ is the baseline survival function for the susceptible or "non-cured" individuals and $F(t)=1-S(t)$ is
the respective cumulative distribution function (Boag, 1949). A generalization of (5) considering bivariate lifetimes $T_{1}$ and $T_{2}$ is given by

$$
\begin{align*}
S_{C}\left(t_{1}, t_{2}\right) & =P_{C}\left(T_{1}>t_{1}, T_{2}>t_{2}\right) \\
& =\phi_{00}+\phi_{11} S_{12}\left(t_{1}, t_{2}\right)+\phi_{10} S_{1}\left(t_{1}\right)+\phi_{01} S_{2}\left(t_{2}\right) \tag{6}
\end{align*}
$$

where $S_{12}\left(t_{1}, t_{2}\right)$ is the joint survival function for the susceptible individuals to both events, $S_{k}\left(t_{k}\right)$ is the baseline marginal survival function for $T_{k}, k=1,2$, and $\phi_{00}, \phi_{11}$, $\phi_{10}$ and $\phi_{01}$ are parameters to be estimated. Let $V_{1}$ and $V_{2}$ be two indicator variables such that $V_{k}=1$ for a susceptible individual in the lifetime $T_{k}$ and $V_{k}=0$ for a immune individual in $T_{k}, k=1,2$. Thus, $P\left(V_{k}=0\right)=\theta_{k}$ and $P\left(V_{k}=1\right)=1-\theta_{k}$. Let $\omega$ be the covariance between $V_{1}$ and $V_{2}$. Thus,

$$
\begin{gathered}
\phi_{00}=P\left(V_{1}=0, V_{2}=0\right)=P\left(V_{1}=0\right) P\left(V_{2}=0\right)+\omega=\theta_{1} \theta_{2}+\omega, \\
\phi_{10}=P\left(V_{1}=1, V_{2}=0\right)=P\left(V_{1}=1\right) P\left(V_{2}=0\right)-\omega=\left(1-\theta_{1}\right) \theta_{2}-\omega, \\
\phi_{01}=P\left(V_{1}=0, V_{2}=1\right)=P\left(V_{1}=0\right) P\left(V_{2}=1\right)-\omega=\theta_{1}\left(1-\theta_{2}\right)-\omega
\end{gathered}
$$

and

$$
\phi_{11}=P\left(V_{1}=1, V_{2}=1\right)=P\left(V_{1}=1\right) P\left(V_{2}=1\right)+\omega=\left(1-\theta_{1}\right)\left(1-\theta_{2}\right)+\omega .
$$

Note that $\phi_{00}+\phi_{11}+\phi_{10}+\phi_{01}=1$. In addition, $\theta_{1}=\phi_{00}+\phi_{01}$ and $\theta_{2}=\phi_{00}+\phi_{10}$ are interpreted as the cure fractions related to the lifetimes $T_{1}$ and $T_{2}$, respectively. Let us consider that each $i$ th set of observations $\left(t_{1 i}, d_{1 i}, t_{2 i}, d_{2 i}\right), i=1, \ldots, n$, can be classified into one of four groups:
(a) $C_{1}$ : both $t_{1 i}$ and $t_{2 i}$ are complete observations, or say, they are uncensored lifetimes;
(b) $C_{2}: t_{1 i}$ is a complete observation and $t_{2 i}$ is a censored lifetime;
(c) $C_{3}: t_{1 i}$ is a censored lifetime and $t_{2 i}$ is a complete observation;
(d) $C_{4}$ : both $t_{1 i}$ and $t_{2 i}$ are censored lifetimes.

Therefore, the likelihood function in presence of cure function and right censoring is given by

$$
\begin{equation*}
L\left(\mathbf{p}, \theta_{1}, \theta_{2}, \omega\right)=\prod_{i \in C_{1}} P_{1}\left(t_{1 i}, t_{2 i}\right) \prod_{i \in C_{2}} P_{2}\left(t_{1 i}, t_{2 i}\right) \prod_{i \in C_{3}} P_{3}\left(t_{1 i}, t_{2 i}\right) \prod_{i \in C_{4}} P_{4}\left(t_{1 i}, t_{2 i}\right), \tag{7}
\end{equation*}
$$

where $\mathbf{p}=\left(p_{1}, p_{2}, p_{3}\right)^{\prime}$,

$$
P_{1}\left(t_{1 i}, t_{2 i}\right)=\phi_{11} P\left(T_{1 i}=t_{1 i}, T_{2 i}=t_{2 i}\right), \quad i \in C_{1},
$$

$$
\begin{gathered}
P_{2}\left(t_{1 i}, t_{2 i}\right)=\phi_{10} P\left(T_{1 i}=t_{1 i}\right)+\phi_{11} P\left(T_{1 i}=t_{1 i}, T_{2 i}>t_{2 i}\right), \quad i \in C_{2}, \\
P_{3}\left(t_{1 i}, t_{2 i}\right)=\phi_{01} P\left(T_{2 i}=t_{2 i}\right)+\phi_{11} P\left(T_{1}>t_{1}, T_{2}=t_{2}\right), \quad i \in C_{3},
\end{gathered}
$$

and, from (6),

$$
P_{4}\left(t_{1 i}, t_{2 i}\right)=S_{C}\left(t_{1 i}, t_{2 i}\right), \quad i \in C_{4} .
$$

Considering the BDBG distribution, we have

$$
\begin{gathered}
P_{1}\left(t_{1 i}, t_{2 i}\right)=\left\{\begin{array}{cll}
\phi_{11} p_{1}^{t_{1 i}-1}\left(1-p_{1}\right)\left(p_{2} p_{3}\right)^{t_{2 i}-1}\left(1-p_{2} p_{3}\right) & \text { for } T_{1 i}<T_{2 i} \\
\phi_{11} p_{2 i}^{t_{2 i}-1}\left(1-p_{2}\right)\left(p_{1} p_{3}\right)^{t_{1 i}-1}\left(1-p_{1} p_{3}\right) & \text { for } T_{1 i}>T_{2 i} \\
\phi_{11}\left(p_{1} p_{2} p_{3}\right)^{t_{1 i}-1}\left(1-p_{1} p_{3}-p_{2} p_{3}+p_{1} p_{2} p_{3}\right) & \text { for } T_{1 i}=T_{2 i}
\end{array}\right. \\
P_{2}\left(t_{1 i}, t_{2 i}\right)=\left\{\begin{array}{cll}
\phi_{10} P\left(T_{1 i}=t_{1 i}\right)+\phi_{11} p_{1}^{t_{1 i}-1}\left(1-p_{1}\right)\left(p_{2} p_{3}\right)^{t_{2 i}} & \text { for } T_{1 i} \leq T_{2 i} \\
\phi_{10} P\left(T_{1 i}=t_{1 i}\right)+\phi_{11} p_{2}^{t_{2 i}}\left(p_{1} p_{3}\right)^{t_{1 i}-1}\left(1-p_{1} p_{3}\right) & \text { for } T_{1 i}>T_{2 i}
\end{array},\right. \\
P_{3}\left(t_{1 i}, t_{2 i}\right)=\left\{\begin{array}{cl}
\phi_{01} P\left(T_{2 i}=t_{2 i}\right)+\phi_{11} p_{1}^{t_{1 i}}\left(p_{2} p_{3}\right)^{t_{2 i}-1}\left(1-p_{2} p_{3}\right) & \text { for } T_{1 i}<T_{2 i} \\
\phi_{01} P\left(T_{2 i}=t_{2 i}\right)+\phi_{11} p_{2}^{t_{2 i}-1}\left(1-p_{2}\right)\left(p_{1} p_{3}\right)^{t_{1 i}} & \text { for } T_{1 i} \geq T_{2 i}
\end{array},\right.
\end{gathered}
$$

where, from (1), $P\left(T_{k i}=t_{k i}\right)=\left(1-p_{k} p_{3}\right)\left(p_{k} p_{3}\right)^{t_{k i}-1}, k=1,2$, and

$$
\begin{aligned}
P_{4}\left(t_{1 i}, t_{2 i}\right) & =\phi_{00}+\phi_{11} P\left(T_{1 i}>t_{1 i}, T_{2 i}>t_{2 i}\right)+\phi_{10} S_{1}\left(t_{1 i}\right)+\phi_{01} S_{2}\left(t_{2 i}\right) \\
& =\phi_{00}+\phi_{11} p_{1}^{t_{1 i}} p_{2}^{t_{2 i}} p_{3}^{\max \left(t_{1 i}, t_{2 i}\right)}+\phi_{10} S_{1}\left(t_{1 i}\right)+\phi_{01} S_{2}\left(t_{2 i}\right) .
\end{aligned}
$$

From (3), we have that

$$
P_{4}\left(t_{1 i}, t_{2 i}\right)=\phi_{00}+\phi_{11} p_{1}^{t_{1 i}} p_{2}^{t_{2 i}} p_{3}^{\max \left(t_{1 i}, t_{2 i}\right)}+\phi_{10}\left(p_{1} p_{3}\right)^{t_{1 i}-1}+\phi_{01}\left(p_{2} p_{3}\right)^{t_{2 i}-1} .
$$

Maximum-likelihood estimates for the parameters of interest are given by deriving the logarithm of the likelihood function $L\left(\mathbf{p}, \theta_{1}, \theta_{2}\right)$ with respect to each parameter and by equalizing the obtained expressions to zero. Considering that the resulting equations does not have an explicit solution, the estimates of $p_{1}, p_{2}, p_{3}, \theta_{1}$ and $\theta_{2}$ could be found using numerical methods.

The Akaike information criterion (AIC), given by AIC $=2 k-2 \ln L(\widehat{\beta})$, where $k$ is the number of parameters in $\widehat{\beta}$ included in the model and $\ln L(\widehat{\beta})$ is the maximum value of the log-likelihood function, is used to compare fits of the model under different formulations. The model with the lowest values of $A I C$ is selected as fitting the sample data better.

In this article, MLE for the parameters $p_{1}, p_{2}, p_{3}, \theta_{1}, \theta_{2}$ and $\omega$ were computed using the "maxLik" package of the R software (Henningsen and Toomet, 2011).

### 2.4. Estimating the mean lifetime

In applications of the model to real data, estimates of the mean lifetime with the respective precision can be very useful to the researcher. In the frequentist case, let us consider the application of the "delta method" in estimating the sampling variances of the mean of the lifetime $T_{k}, k=1,2$, considering only the susceptible individuals. From (2),

$$
g\left(p_{k}, p_{3}\right)=\frac{1}{1-p_{k} p_{3}}, \quad k=1,2,
$$

and an approximation of the variance of $g\left(p_{k}, p_{3}\right)$ is obtained by

$$
\operatorname{Var}\left[g\left(p_{k}, p_{3}\right)\right] \approx\left[\begin{array}{cc}
\frac{\partial}{\partial p_{k}} g\left(p_{k}, p_{3}\right) & \frac{\partial}{\partial p_{3}} g\left(p_{k}, p_{3}\right)
\end{array}\right] \boldsymbol{\Sigma}_{\left(p_{k}, p_{3}\right)}\left[\begin{array}{c}
\frac{\partial}{\partial p_{k}} g\left(p_{k}, p_{3}\right) \\
\frac{\partial}{\partial p_{3}} g\left(p_{k}, p_{3}\right)
\end{array}\right]
$$

where

$$
\begin{aligned}
\frac{\partial}{\partial p_{k}} g\left(p_{k}, p_{3}\right) & =\frac{p_{3}}{\left(p_{k} p_{3}-1\right)^{2}} \\
\frac{\partial}{\partial p_{3}} g\left(p_{k}, p_{3}\right) & =\frac{p_{k}}{\left(p_{k} p_{3}-1\right)^{2}}
\end{aligned}
$$

and $\boldsymbol{\Sigma}_{\left(p_{k}, p_{3}\right)}$ is the respective maximum-likelihood estimated variance-covariance matrix. Therefore, the Wald-type asymptotic $95 \%$ confidence limits for $E\left(T_{k}\right)$ are given by

$$
g\left(\widehat{p}_{k}, \widehat{p}_{3}\right)-1.96 \sqrt{\operatorname{Var}\left[g\left(\widehat{p}_{k}, \widehat{p}_{3}\right)\right]}, g\left(\widehat{p}_{k}, \widehat{p}_{3}\right)+1.96 \sqrt{\operatorname{Var}\left[g\left(\widehat{p}_{k}, \widehat{p}_{3}\right)\right]}
$$

where $g\left(\widehat{p}_{k}, \widehat{p}_{3}\right)$ is the point maximum likelihood estimate of the mean lifetime and $\widehat{p}_{k}$ and $\widehat{p}_{3}$ are the MLE for the parameters $p_{k}$ and $p_{3}$, respectively, for $k=1,2$. An estimate of the variance-covariance matrix $\boldsymbol{\Sigma}_{\left(p_{k}, p_{3}\right)}$ is obtained as the inverse of the Fisher information matrix, that is, the matrix of the expected second derivatives of the log-likelihood function.

### 2.5. Bayesian analysis

According to Bayes' theorem, the posterior knowledge about the parameters of interest is proportional to the product of the respective prior knowledge and the likelihood function. Thus, let us suppose that the parameters $p_{1}, p_{2}, p_{3}, \theta_{1}$ and $\theta_{2}$ follow independent beta distributions. In this case,

$$
p_{j} \sim \operatorname{Beta}\left(a_{j}, b_{j}\right), \quad j=1,2,3
$$

and

$$
\theta_{k} \sim \operatorname{Beta}\left(c_{k}, d_{k}\right), \quad k=1,2
$$

where $a_{1}>0, a_{2}>0, a_{3}>0, b_{1}>0, b_{2}>0, b_{3}>0, c_{1}>0, c_{2}>0, d_{1}>0$ and $d_{2}>0$ are known hyperparameters. In addition, considering that $0 \leq \omega \leq \min (p 1, p 2)-p 1 p 2$,
we can assume a generalized beta $(G B)$ prior distribution for the covariance parameter $\omega$. The $G B$ distribution is a continuous probability distribution ranged in an interval not necessary equals to $[0,1]$. The joint posterior density function for $p_{1}, p_{2}, p_{3}, \theta_{1}, \theta_{2}$ and $\omega$ is written as

$$
f\left(\mathbf{p}, \theta_{1}, \theta_{2}, \omega \mid \mathbf{w}\right) \propto L\left(\mathbf{p}, \theta_{1}, \theta_{2}, \omega\right) \times f\left(\mathbf{p}, \theta_{1}, \theta_{2}, \omega\right),
$$

where the likelihood function $L\left(\mathbf{p}, \theta_{1}, \theta_{2}, \omega\right)$ is given by $(7), f\left(\mathbf{p}, \theta_{1}, \theta_{2}, \omega\right)$ is given by the product of the prior probability functions and $\mathbf{w}=\left(t_{1}, d_{1}, t_{2}, d_{2}\right)^{\prime}$ is the vector of observed variables. Expressions for the full conditional posterior distributions are obtained by deriving the posterior distribution of each parameter given the data and all other parameters included in the model. In this article, we use Markov Chain Monte Carlo (MCMC) algorithms to get the posterior summaries of interest. In this way, we generated 510,000 Gibbs samples for each parameter, where the first 10,000 simulated samples were discarded as a burn-in period, which is used to minimize the effect of the initial values. The Bayesian estimates for the parameters of interest are obtained using the means of the respective posterior distributions. In addition, the $95 \%$ credible interval for a given parameter is estimated from the $2.5 t h$ and $97.5 t h$ centiles of its posterior distribution.

The deviance information criterion $(D I C)$ is a generalization of the $A I C$ for Bayesian analysis, easily obtained from the samples generated by MCMC simulation (Spiegelhalter et al., 2014). The $D I C$ value is computed as $D I C=D(\widehat{\beta})+2 n_{p}=2 \bar{D}-D(\widehat{\beta})$, where $D(\widehat{\beta})$ is the deviance evaluated using the mean of the parameters obtained from the MCMC samples, $\bar{D}$ is the posterior mean of the deviance and $n_{p}=\bar{D}-D(\widehat{\beta})$ is a measure of model complexity given by the effective number of parameters of the model. The model with the lowest values of $D I C$ provides the best fit to data. Alternatively, comparison between different models can be also assessed using the log pseudo marginal likelihood ( $L P M L$ ) measure, derived from the conditional predictive ordinate ( $C P O$ ) statistics. The larger is the value of $L P M L$, the better is the fit of the model (Geisser and Eddy, 1979).

All Bayesian parameter estimates and their respective $95 \%$ credible intervals ( $95 \% \mathrm{CrI}$ ) were obtained using the OpenBUGS software version 3.2.2. Convergence of the simulated samples was verified by traceplots. Details of our OpenBUGS program code are provided in an Appendix at the end of the paper.

## 3. Results

In this section, we present a numerical illustration of the proposed model to real medical data from two previously published studies.

### 3.1. The cervical carcinoma study

Let us consider the data from a study that included a total of 148 women diagnosed and treated for invasive cervical carcinoma between 1992 and 2002 (Brenna et al., 2004). This dataset was also used by Martinez and Achcar (2014) to illustrate the performance of a bivariate model based on the generalized Lindley distribution and copula functions. For the purposes of the present study, it was considered a subsample of 118 women who received the standard treatment recommended by the International Federation of Gynecology and Obstetrics (FIGO). Let us define the disease-free survival (DFS) as the time from the date of surgery to the first event of disease recurrence and the overall survival (OS) as the time from the date of surgery to the death. Thus, $T_{1}$ and $T_{2}$ are random variables denoting the DFS and the OS times, respectively. Note that, in this example, it is not possible the case in which $T_{1}>T_{2}$, given that $T_{2}$ is the time to death. However, there are six observations in which $T_{1}=T_{2}$. Both lifetimes are expressed in complete months.

In Table 1, we have the Bayesian (posterior summaries) and maximum likelihood estimates of the parameters for the model based on the BDBG distribution in the presence of censored data and a cure fraction. Note that the Bayesian and maximum likelihood estimates are very similar. Attempting to consider non-informative prior distributions for the parameters, in the Bayesian analysis we assumed uniform $U(0,1)$ prior distribution for the parameters $p_{1}, p_{2}, p_{3}, \theta_{1}$ and $\theta_{2}$ (remember that the uniform $U(0,1)$ distribution is an especial case of the beta distribution with both hyperparameters set to $1)$. In addition, we also assume a generalized beta prior distribution for $\omega$, given by $\operatorname{Beta}(1,1) \times \min (p 1, p 2)-p 1 p 2$. In a brief sensitivity analysis, we also assumed beta prior distributions with both hyperparameters set to the value 0.5 for the parameters, as a special case, but the results did not change substantially. In the frequentist case, standard errors are given Table 1 for the parameters $\phi_{00}, \phi_{01}, \phi_{10}$ and $\phi_{11}$, and also for the quantities $E\left(T_{1}\right)$ and $E\left(T_{2}\right)$, which were obtained using the "delta method". We can note that the Wald method produced unrealistic confidence intervals $(C I)$ for $p_{3}, \phi_{01}$ and $\phi_{10}$, given that the upper limits can be higher than 1 and the lower limits can be lower than 0 .

We also fitted alternative models assuming independence between the probabilities $V_{1}$ and $V_{2}$, which leads to $\omega=0$. In this case, the Bayesian model generated a $D I C$ value equals to 1189.0 and a $L P M L$ value equals to -595.41 , suggesting that the model that includes the term $\omega$ best fits the data, as indicated by the lowest $D I C$ value and highest $L P M L$ value (Table 1). In addition, the log-likelihood value under the frequentist model that considers $\omega=0$ is -592.11 and the respective $A I C$ value is 1194.21 , which reinforces this conclusion.

Figure 1 shows plots of the survival function considering the DFS (panel A) and the OS times (panel B). This figure compares the survival functions obtained by the Kaplan-Meier (KM) estimator and the Bayesian parametric model based on the BDBG distribution in the presence of censored data and a cure fraction. The grey region in the


Figure 1: Plots of the survival functions estimated by the Kaplan-Meier method and assuming the Bayesian bivariate model based on the BDBG distribution. Censoring points are marked by vertical lines on the Kaplan-Meier survival curves. The grey region in the plots describes $95 \%$ credible regions for the parametric marginal survival functions. Data from the cervical carcinoma study (Brenna et al., 2004)

Table 1: Bayesian and maximum likelihood estimates. Data from the cervical carcinoma study (Brenna et al., 2004).

| Parameter | Bayesian estimates |  |  | Maximum likelihood estimates |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | mean | standard deviation | 95\%CrI | estimate | standard error | Wald-type $95 \%$ CI |
| $p_{1}$ | 0.9395 | 0.0078 | (0.9232, 0.9539) | 0.9399 | 0.0077 | (0.9249, 0.9551) |
| $p_{2}$ | 0.9838 | 0.0097 | (0.9652, 0.9992) | 0.9735 | 0.0043 | (0.9651, 0.9819) |
| $p_{3}$ | 0.9836 | 0.0098 | (0.9652, 0.9991) | 0.9979 | 0.0033 | (0.9914, 1.0043) |
| $\phi_{00}$ | 0.5659 | 0.0509 | (0.4662, 0.6650) | 0.5652 | $0.0724^{(a)}$ | (0.4232, 0.7071) |
| $\phi_{01}$ | 0.0273 | 0.0205 | $(0.0012,0.0778)$ | 0.0281 | $0.0753^{(a)}$ | $(-0.1196,0.1758)$ |
| $\phi_{10}$ | 0.0112 | 0.0113 | (0.0002, 0.0420) | 0.0128 | $0.0698{ }^{(a)}$ | (-0.1240, 0.1495) |
| $\phi_{11}$ | 0.3957 | 0.0490 | $(0.3004,0.4925)$ | 0.3940 | $0.0899{ }^{(a)}$ | (0.2176, 0.5703) |
| $\omega$ | 0.2214 | 0.0137 | (0.1899, 0.2431) | 0.2223 | 0.0497 | (0.1249, 0.3197) |
| $\theta_{1}$ | 0.4069 | 0.0491 | $(0.3107,0.5031)$ | 0.4067 | 0.0698 | (0.2698, 0.5435$)$ |
| $\theta_{2}$ | 0.4230 | 0.0511 | $(0.3249,0.5231)$ | 0.4221 | 0.0929 | (0.2398, 0.6043$)$ |
| $E\left(T_{1}\right)$ | 13.49 | 2.204 | (10.05, 18.47) | 16.13 | $1.686^{(a)}$ | (12.82, 19.43) |
| $E\left(T_{2}\right)$ | 31.42 | 4.712 | $(23.44,41.84)$ | 35.05 | $4.208^{(a)}$ | (26.80, 43.29) |
| LPML : -549.54, DIC : 1099.0 |  |  |  | Log-likelihood : -547.90, AIC: 1107.807 |  |  |

${ }^{(a)}$ Standard errors obtained using the $\backslash$ delta method".
Note: $95 \% C r I, 95 \%$ credible interval; $95 \% C I, 95 \%$ confidence interval.
plots describes $95 \%$ credible regions for the marginal survival functions, obtained from the 2.5 th and $97.5 t h$ centiles of the posterior distribution for $S_{C}(t)$ (see equation (5)) at a lifetime $t=t^{*}$, where $t^{*} \geq 1$ is an integer value. The plots in Figure 1 suggest a reasonable approximation between the KM estimates and the values predicted by the parametric model.

### 3.2. The diabetic retinopathy study

In this subsection we consider the model based on the BDBG distribution in the presence of censoring and a cure fraction for the data from the Diabetic Retinopathy Study (Huster et al., 1989), where the objective was to assess the efficacy of photocoagulation treatment for proliferativeretinopathy. Each patient had one eye randomized to laser treatment and the other eye received no treatment. The main endpoint of this study was the severe visual loss in each eye. Let $T_{1}$ and $T_{2}$ be two random variables denoting the time up to visual loss for the control eye and the time up to visual loss for the treatment eye, respectively. Censoring was caused by death, dropout or end of the study. Table 2 compares the results obtained from the Bayesian analysis and the maximum likelihood estimation. In the Bayesian analysis, the choice of the prior distributions was similar to that of the previous application. As can be seen, the Bayesian and maximum likelihood estimates are very close to each other. We note that the upper limit of the $95 \% C I$ for $p_{3}$ is higher than 1 , and the lower limit of the $95 \% C I$ for $\phi_{01}$ is lower than 0 , reinforcing that

Table 2: Bayesian and maximum likelihood estimates. Data from the diabetic retinopathy study (Huster et al., 1989).

| Parameter | Bayesian estimates |  |  | Maximum likelihood estimates |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | mean | standard deviation | 95\%CrI | estimate | standard error | Wald-type $95 \%$ CI |
| $p_{1}$ | 0.9720 | 0.0083 | $(0.9548,0.9872)$ | 0.9711 | 0.0084 | (0.9546, 0.9875) |
| $p_{2}$ | 0.9713 | 0.0057 | (0.9594, 0.9815) | 0.9703 | 0.0059 | (0.9586, 0.9820) |
| $p_{3}$ | 0.9937 | 0.0029 | (0.9871, 0.9982) | 0.9952 | 0.0026 | (0.9902, 1.0003) |
| $\phi_{00}$ | 0.3119 | 0.0620 | (0.2162, 0.4618) | 0.2981 | $0.0516^{(a)}$ | (0.1968, 0.3992) |
| $\phi_{01}$ | 0.0594 | 0.0319 | (0.0069, 0.1289) | 0.0559 | $0.0360^{(a)}$ | $(-0.0147,0.1265)$ |
| $\phi_{10}$ | 0.3472 | 0.0672 | (0.2070, 0.4755) | 0.3493 | $0.0551{ }^{(a)}$ | (0.2413, 0.4573) |
| $\phi_{11}$ | 0.2815 | 0.0519 | (0.1727, 0.3765) | 0.2967 | $0.0493{ }^{(a)}$ | (0.2001, 0.3933) |
| $\omega$ | 0.0667 | 0.0239 | $(0.0212,0.1156)$ | 0.0689 | 0.0236 | (0.0226, 0.1152) |
| $\theta_{1}$ | 0.6286 | 0.0669 | ( $0.4626,0.7288$ ) | 0.6461 | 0.0540 | (0.5401, 0.7520) |
| $\theta_{2}$ | 0.3409 | 0.0616 | (0.2115, 0.4503) | 0.3529 | 0.0613 | (0.2323, 0.4728) |
| $E\left(T_{1}\right)$ | 31.76 | 10.170 | (19.19, 57.49) | 29.82 | $7.952^{(a)}$ | $(14.23,45.41)$ |
| $E\left(T_{2}\right)$ | 29.68 | 5.488 | $(21.08,42.28)$ | 29.14 | $5.596{ }^{(a)}$ | (18.17, 40.11) |
| LPML : -824.74, DIC : 1649.0 |  |  |  | Log-likelihood : -819.64, AIC: 1651.28 |  |  |

${ }^{(a)}$ Standard errors obtained from the Delta method.
Note: $95 \% C r I, 95 \%$ credible interval; $95 \% C I, 95 \%$ confidence interval.
the Wald-type confidence intervals can produce unrealistic results when the respective parameter is estimated to be close to 0 or 1 .

If we assume independence between the probabilities $V_{1}$ and $V_{2}$, a model fitted using $\omega=0$ has a DIC value of 1655.0 , and a $L P M L$ of -828.14 , as opposed to respective values of 1649.0 and -824.74 from the results in Table 2.

In the plots in Figure 2 we compared the survival functions for the $T_{1}$ and $T_{2}$ lifetimes estimated by the KM method and the marginal survival functions obtained from the Bayesian parametric model based on the BDBG distribution. We can note that the estimated survival functions are very close to each other. As in the previous application example, the grey region in the plots describes $95 \%$ credible regions for the parametric marginal survival functions.

## 4. Discussion and remarks

In this paper, we extend the problem of parameter estimation for the model based on the BDBG distribution in presence of censoring, as discussed by Achcar et al. (2016), to the case where a cure fraction is present. We showed that the frequentist and Bayesian approaches can be used for the purpose of estimating the parameters of the model, and


Figure 2: Plots of the survival functions estimated by the Kaplan-Meier method and assuming the Bayesian bivariate model based on the BDBG distribution. Censoring points are marked by vertical lines on the Kaplan-Meier survival curves. The grey region in the plots describes $95 \%$ credible regions for the parametric marginal survival functions. Data from the diabetic retinopathy study (Huster et al., 1989).
the use of free available software like the popular R and OpenBUGS software provide a great facility for this task.

For the Bayesian analysis of bivariate models with cure fractions, a number of authors assume a Dirichlet prior for the parameters $\phi_{00}, \phi_{11}, \phi_{10}$ and $\phi_{01}$, since $\phi_{00}+\phi_{11}+$ $\phi_{10}+\phi_{01}=1$ (for examples, see Achcar et al. (2013) or Davarzani et al. (2015)). In the present article, we alternatively assumed prior beta distributions for the parameters $\theta_{1}$ and $\theta_{2}$, such that $\theta_{1}=\phi_{00}+\phi_{01}$ and $\theta_{2}=\phi_{00}+\phi_{10}$ are the cure fractions related to the lifetimes $T_{1}$ and $T_{2}$, respectively. As an advantage of this choice, we observed that assuming dependence between the random variables $V_{1}$ and $V_{2}$ by the introduction of the parameter $\omega$ denoting the covariance between these indicator variables resulted in much better fit of the proposed model for the numerical examples.

Achcar et al. (2016) state that models based on bivariate discrete distributions could be good alternatives to the analysis of bivariate real data in presence of censoring, since we usually find computational difficulties to get inferences for the parameters of interest using standard continuous lifetime distributions as the popular Block and Basu or the Marshall and Olkin bivariate exponential distributions. In this way, the parametric models based on the BDBG distribution are a good alternative to analyse bivariate discrete lifetime data, considering the ease of implementation using computational software as R or OpenBUGS. However, an important limitation of the BDBG distribution is that their marginal hazard functions are constant, and this can be unrealistic in many applications. Thus, future studies will be required to extend the BDBG distribution to provide a model with a more flexible hazard function while maintaining the ease of computational implementation.

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## Appendix

## A. OpenBUGS

The OpenBUGS code used for estimating the parameters of the BDBG distribution with presence of censoring and a cure fraction is given below.

```
model {
for (i in 1:N) {
    difT[i] <- t1[i] - t2[i]
    k1[i] <- 1 - step(difT[i])
    k3[i] <- equals(t1[i],t2[i])
    k2[i] <- (1-k1[i])*(1-k3[i])
    PT1[i] <- (1-p[1]*p[3])*pow(p[1]*p[3],t1[i]-1)
    PT2[i] <- (1-p[2]*p[3])*pow(p[2]*p[3],t2[i]-1)
    P1A[i] <- phi[1]*pow(p[1],t1[i]-1)*(1-p[1])
                            *pow(p[2]*p[3],t2[i]-1)*(1-p[2]*p[3])
    P1B[i] <- phi[1]*pow(p[2],t2[i]-1)*(1-p[2])
                            *pow(p[1]*p[3],t1[i]-1)*(1-p[1]*p[3])
    P1C[i] <- phi[1]*pow(p[1]*p[2]*p[3],t1[i]-1)
    * (1-p [1] *p [3]-p [2] *p [3] +p [1]*p [2]*p [3])
    P2A[i] <- phi[2]*PT1[i]+phi[1]*pow(p[1],t1[i]-1)
                            *(1-p[1])*pow(p[2]*p[3],t2[i])
    P2B[i] <- phi[2]*PT1[i]+phi[1]*pow(p[2],t2[i])
        *pow(p[1]*p[3],t1[i]-1)*(1-p[1]*p[3])
    P2C[i] <- P2A[i]
    P3A[i] <- phi[3]*PT2[i]+phi[1]*pow(p[1],t1[i])
        *pow(p[2]*p[3],t2[i]-1)*(1-p[2]*p[3])
    P3B[i] <- phi[3]*PT2[i]+phi[1]*pow(p[2],t2[i]-1)
        *(1-p[2])*pow(p[1]*p[3],t1[i])
    P3C[i] <- P3B[i]
    P4[i] <- phi[4]+phi[1]*pow(p[1],t1[i])*pow(p[2],t2[i])
                    *pow(p[3],max(t1[i],t2[i]))
                            +phi[2]*pow(p[1]*p[3],t1[i]-1)
                            +phi[3]*pow(p[2]*p[3],t2[i]-1)
P1[i] <- pow(P1A[i],k1[i])*pow(P1B[i],k2[i])*pow(P1C[i],k3[i])
P2[i] <- pow(P2A[i],k1[i])*pow(P2B[i],k2[i])*pow(P2C[i],k3[i])
P3[i] <- pow(P3A[i],k1[i])*pow(P3B[i],k2[i])*pow(P3C[i],k3[i])
    L[i] <- pow(P1[i],d1[i]*d2[i])*pow(P2[i],d1[i]*(1-d2[i]))
        *pow(P3[i],(1-d1[i])*d2[i])*pow(P4[i],(1-d1[i])*(1-d2[i]))
    logL[i] <- log(L[i])
    zeros[i] <- 0
```

```
    zeros[i] ~ dloglik(logL[i])
}
    phi[1] <- (1-theta[1])*(1-theta[2]) + w
    phi[2] <- (1-theta[1])*theta[2] - w
    phi[3] <- theta[1]*(1-theta[2]) - w
    phi[4] <- theta[1]*theta[2] + w
# Prior distributions
    theta[1] ~ dbeta(1,1)
    theta[2] ~ dbeta(1,1)
    p[1] ~ dbeta(1,1)
    p[2] ~ dbeta(1,1)
    p[3] ~ dbeta(1,1)
    w <- g*(min(theta[1],theta[2]) - theta[1]*theta[2])
    g ~ dunif (0,1)
# Means of the lifetimes
m[1] <- 1/(1-p[1]*p[3])
m[2] <- 1/(1-p[2]*p[3])
# Marginal survival functions
for (t in 1:120) {
S1[t] <- theta[1]+(1-theta[1])*pow(p[1]*p[3],t-1)
S2[t] <- theta[2]+(1-theta[2])*pow(p[2]*p[3],t-1) }
}
```

The data from the cervical carcinoma study in OpenBUGS format are shown below. This dataset can be freely used by students and researchers on their own works, but the article from (Brenna et al., 2004) should be cited as its source.

```
list(N=118, t1=c(28, 8, 116, 2, 1, 112, 7, 17, 32, 1, 19, 5, 29,
    42, 91, 8, 91, 85, 2, 1, 89, 3, 1, 5, 1, 84, 1, 112, 99, 1, 6,
    2, 62, 6, 103, 24, 1, 4, 19, 24, 26, 1, 8, 2, 2, 1, 77, 27, 65,
    2, 64, 8, 16, 91, 54, 90, 60, 8, 1, 1, 93, 3, 101, 10, 5, 12, 1,
    85, 37, 5, 89, 2, 91, 88, 44, 19, 1, 15, 69, 88, 25, 36, 86, 45,
    7, 22, 90, 2, 49, 9, 8, 66, 6, 15, 11, 1, 46, 23, 5, 28, 4, 4,
    15, 13, 1, 1, 6, 32, 49, 23, 2, 39, 19, 37, 55, 43, 1, 1),
t2=c(30, 14, 120, 18, 8, 115, 16, 20, 40, 7, 29, 13, 94, 46, 99,
    13, 92, 94, 10, 6, 90, 17, 6, 18, 4, 86, 10, 113, 100, 10, 14, 13,
    69, 13, 108, 52, 7, 5, 23, 52, 33, 4, 103, 17, 6, 6, 80, 31, 68,
    102, 64, 19, 25, 96, 56, 95, 65, 55, 6, 18, 94, 9, 102, 13, 31,
    18, 11, 90, 45, 14, 90, 16, 91, 92, 48, 25, 2, 27, 69, 89, 56,
```

```
43, 88, 45, 13, 26, 93, 8, 92, 14, 12, 71, 9, 24, 15, 8, 49, 29,
9, 32, 9, 7, 20, 19, 5, 5, 12, 38, 53, 29, 6, 44, 22, 42, 55, 43,
5, 5),
d}1=c(0,1,0,1,0,0,1,1,1,0,1,1, 1, 1, 1, 1, 1, 0, 1, 1, 0
    1, 1, 1, 0, 0, 1, 0, 0, 1, 1, 1, 1, 1, 0, 1, 1, 0, 0, 1, 1, 0, 1,
    1, 1, 1, 0, 0, 0, 1, 0, 1, 1, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 1, 1,
    1, 1, 0, 1, 1, 0, 1, 0, 0, 1, 1, 0, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0,
    1, 1, 1, 1, 0, 1, 1, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0,
    0, 0, 0, 0, 0, 0, 0, 0, 1),
d2=c}(0,1,0,1,0,0,1,1,1,0,1,1,0,1, 1, 1, 1, 0, 1, 1, 0
    1, 1, 1, 0, 0, 1, 0, 0, 1, 1, 1, 1, 1, 0, 1, 1, 0, 0, 1, 1, 0, 0,
    1, 1, 1, 0, 0, 0, 0, 0, 1, 1, 0, 0, 0, 1, 1, 1, 1, 0, 0, 0, 1, 1,
    1, 1, 0, 1, 1, 0, 1, 0, 0, 1, 1, 0, 1, 0, 0, 1, 1, 0, 0, 1, 1, 0,
    1, 1, 1, 1, 0, 1, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
    0, 0, 0, 0, 0, 0, 0, 0, 0))
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